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AL-TR-1992-0059

## AD-A255 769



### AIR FORCE PROCEDURE FOR PREDICTING NOISE AROUND AIRBASES: NOISE EXPOSURE MODEL (NOISEMAP) TECHNICAL REPORT



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**MAY 1992** 

FINAL REPORT FOR THE PERIOD JANUARY 1989 TO MARCH 1992

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AL-TR-1992-0059

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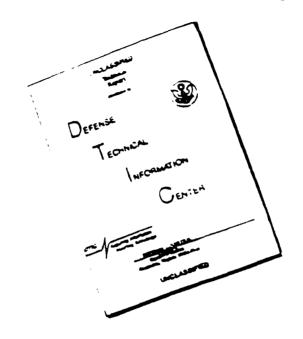
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#### REPORT DOCUMENTATION PAGE

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Public reporting burden for this collection of information is estimated to average 1 nour per response, including the time for reviewing instructions, searching existing data sources, gathering and maintaining the data needed, and completing and reviewing the collection of information. Send comments regarding this burden estimate or any other aspect of this collection of information, including suggestions for reducing this burden, to Washington Headquarters Services, Directorate for Information Operations and Reports, 1215 Jefferson Davis Highway, Suite 1204, Arlington, VA. 22202-4302, and to the Office of Management and Budget. Paperwork Reduction Project (0704-0188), Washington, DC 20503.

1. AGENCY USE ONLY (Leave blank)	2. REPORT DATE	3. REPURT TYPE AN	
	MAY 1992	JAN 89 - MAR	
4. TITLE AND SUBTITLE AIR FORCE PROCEDURE FOR NOISE EXPOSURE MODEL (NO			FUNDING NUMBERS PE: 62202F PR: 7231 TA: 34
6. AUTHOR(S)		_	WU: 11
CAREY L. MOULTON			
7. PERFORMING ORGANIZATION NAME	(S) AND ADDRESS(ES)		8. PERFORMING ORGANIZATION
WYLE LABORATORIES			REPORT NUMBER
128 Maryland El Segundo CA 90245-4115			WR 91-12
9. SPONSORING/MONITORING AGENCY Biodynamic Environment B Biodynamics and Bioengin Armstrong Laboratory Human Systems Division	ranch	S(ES)	10. SPONSORING / MONITORING AGENCY REPORT NUMBER
Wright-Patterson AFB OH	45433-6573		AL-TR-1992-0059
11. SUPPLEMENTARY NOTES			
12a. DISTRIBUTION / AVAILABILITY STA	TEMENT		12b. DISTRIBUTION CODE
Approved for public rele	ase; distributio	n is unlimited.	A
13. ABSTRACT (Maximum 200 words)			
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14. SUBJECT TERMS		<del></del>	15. NUMBER OF PAGES
Acoustics	Engine Noise	Noise Modeling	159
Sound	Community Noise Expo	sure	16. PRICE CODE
Aircraft Noise	Environmental Impact		
17. SECURITY CLASSIFICATION OF REPORT	18. SECURITY CLASSIFICATION OF THIS PAGE	19. SECURITY CLASSIFICATION OF ABSTRACT	20. LIMITATION OF ABSTRACT
UNCLASSIFIED	UNCLASSIFIED	UNCLASSIFIED	UNLIMITED

these algorithms were originally outlined by Dr William Galloway in the report "Community Noise Exposure Resulting from Aircraft Operations: Technical Review" published in November 1974. This report covers all the current algorithms used in NMAP 6.1 and includes an example computation for a

single aircraft takeoff and ground runup operation.

#### **ACKNOWLEDGEMENTS**

The author wishes to thank all of those people who have helped bring this document to fruition. I am especially indebted to Mr. Jerry Speakman and Mr. Robert Lee of the Bio-Medical branch of the Armstrong Medical Research Labs at Wright-Patterson Air Force Base for their guidance and excellent technical advice.

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#### 1.0 INTRODUCTION

This report is intended as a technical overview of the algorithms used in NMAP 6.1 to calculate noise exposure. Most of these algorithms were developed during the inception of the NOISEMAP program which was conceptually outlined by Dr. William Galloway in 1974. Some of the algorithms, such as the new NMAP 6.1 lateral attenuation model and the SAE lateral attenuation models, are recent additions to NOISEMAP.

NOISEMAP was the name given to the FORTRAN program, developed for the Air Force in the mid 1970's, to calculate aircraft noise exposure. This FORTRAN program is now called NMAP 6.1 (the 6.1 being the current version number), and the term NOISEMAP now refers to a suite of programs that includes several supplemental programs such as OMEGA 10.7 and OMEGA 11.3, and "new" programs (circa 1989) such as BASEOPS, MCM, and NMPLOT. The OMEGA 10.7 and 11.3 programs<sup>2</sup> perform the propagation extrapolations on the reference aircraft noise spectra in the NOISEFILE 6.2 database and provide as output the single event noise descriptors that NMAP 6.1 requires for its calculations. The BASEOPS program<sup>3</sup> allows interactive entry of the airbase operations and airfield data for NMAP 6.1 noise contour calculations. The airbase operations data from BASEOPS are then filtered by the Master Control Module (MCM) program<sup>4</sup> which creates the NMAP 6.1 input file (NMI). The NMI file is a processing template which is a combination of processing instructions and reference data that drives the NMAP 6.1 contour calculations. After the contour calculations are complete the NMPLOT program<sup>5</sup> is used to plot the resulting contours along with user selectable airbase information that are entered into BASEOPS.

The NMAP 6.1 program is an effective method of determining noise exposure due to aircraft operations, and includes both military and civilian aircraft in its aircraft reference noise database. This report provides detailed information on the crucial and core algorithms relating to noise exposure calculations so that current users can have a better technical understanding of NMAP 6.1, and that future developers of NOISEMAP will have an adequate foundation for extending the program.

Section 2.0 of this report provides the details on all of the noise exposure calculations in the NMAP 6.1 program. These noise exposure calculations are the end product of a series of operations that include flight segmentation, determining when and where specific noise modules apply (e.g., takeoff roll model, altitude thrust correction, airspeed correction and user-entered sound level adjustments), grid searching, and finally the the noise exposure calculations themselves. The bulk of NMAP's time is spent processing flyover operations because of the complexity of the

geometry involved and the complexity of the merged flight segments. Runup operations on the other hand, are much simpler in companson because of their simpler geometry and the fact that they are single power setting operations. Included at the end of many sub-sections in Section 2.0 are the results of a sample case which are intended to show how each algorithm has been implemented in MNAP 6.1. Section 3 covers some of the unique features of NMAP 6.1. Included in this section is the complete sample calculation with all the supporting data, and a sample contour plot. Also included in Section 3 are tables of all of the aircraft that have reference noise data in the NOISEFILE 6.2 database. This database currently holds 304 aircraft flyover, 398 aircraft runup, and 220 civil aircraft noise spectra. Appendix A contains a program flowchart of NMAP 6.1, and Appendix B contains a summary of all of the subroutines and common blocks in the NMAP 6.1 program.

#### 2.0 NOISEMAP NOISE CALCULATIONS

#### 2.1 Noise Descriptors

The noise descriptors used for noise exposure calculations are the following:

DNL - Day-Night Average Sound Level,

CNEL - Community Noise Equivalent Level,

NEF - Noise Exposure Forecast,

WECPNL - Weighted Equivalent Continuous Perceived Noise Level.

These descriptors cover a broad range of analysis requirements for land use planning in the United States, Canada and Europe,<sup>6</sup> with NEF being used in Canada and the WECPNL metric being predominantly if not exclusively used in Europe.

The DNL metric is the default metric used by the MCM program when compiling the input file for the NMAP 6.1. However, any of the other metrics can be chosen by making a selection in the MCM's RUN-Run options menu.

#### 2.1.1 <u>Day-Night Average Sound Level (DNL)</u>

The DNL descriptor is based on the energy averaged A-weighted sound level integrated over a 24 hour period, with a penalty applied to night-time operations between 2200 hrs and 0700 hrs local time. NMAP 6.1 uses the following relationships to determine DNL exposure:

#### FLYOVER:

$$L_{dn} = L_E + 10 \cdot \log_{10}(N_{day} + 10 \cdot N_{night}) - 49.4$$

#### RUNUP:

$$L_{dn} = L_A + 10 \cdot \log_{10}(N_{day} \cdot t + 10 \cdot N_{night} \cdot t) - 49.4$$

where  $L_{dn}$  = Day-Night Average Sound Level (DNL)

L<sub>E</sub> = Sound Exposure Level (SEL) in dB,

L<sub>A</sub> = A-weighted sound level in dB,

N<sub>day</sub> = number of operations (takeoff or landing) between 0700 hrs and 2200

hrs local time,

 $N_{night}$  = number of operations (takeoff or landing) between 2200 hrs and 0700

hrs local time,

and t = the runup duration in seconds.

The SEL values are interpolated from tables of SEL values versus distance generated by the OMEGA 10.7 program. The OMEGA 10.7 program uses 22 distances starting at 200 ft and ending at 25,000 ft in increments based on one-third octave ratios, i.e., 200 ft, 250 ft, 315 ft, 400 ft, etc. The SEL values are generated for air-to-ground and ground-to-ground sound propagation conditions at each of the one-third octave distance increments. The OMEGA 10.7 program also corrects the reference noise spectra which are expressed in terms of the standard day conditions, for local temperature and humidity (see Section 2.7.1).

The SEL values that are calculated by OMEGA 10.7 are extrapolated from the Air Force's reference noise data file, NOISEFILE 6.2, which contains one-third octave band spectra of aircraft noise normalized to a 1000 ft distance at standard day temperature and humidity, and sea level altitude. The reference database noise spectra cover a wide range of military and civilian aircraft at selected engine power settings and flight conditions. These are processed by OMEGA 10.7 to provide the SEL values at the required set of distances, airbase meteorological conditions and aircraft flight conditions (engine power settings and airspeed) for the two propagation conditions (air-to-ground and ground-to-ground) as mentioned before. This procedure is described in more detail in Reference 2. The OMEGA 10.7 tabulations of SEL values are subsequently included as part of the NMAP 6.1 input file compiled by the MCM program.

The values of A-weighted Sound Level, AL, which are used to estimate noise exposures from aircraft or engine ground runup tests, are similarly calculated at a set of one-third octave distances from 200 ft to 25,000 ft by means of an OMEGA 11.3 program. The OMEGA 11.3 program accesses ground runup reference noise spectra in NOISEFILE 6.2 for specific aircraft or engine test facility operating at selected engine power settings. OMEGA 11.3 then generates a table of AL values for the required set of ground-to-ground propagation distances and azimuth angles relative to the aircraft or test facility's forward axis. This process is also descr. bed in detail in Reference 2.

For both the flyover and runup events, the number of operations and runup duration are entered into the BASEOPS program and are carried through the MCM into the NMAP input file.

#### 2.1.2 Community Noise Equivalent Level (CNEL)

The CNEL descriptor is similar to DNL except that there is an additional penalty for operations occurring between the evening hours of 1900 and 2200 hrs. This breaks the number of noise exposure periods in 24 hours into three time periods, i.e., 0700-1900, 1900-2200, and 2200-0700 hrs. The CNEL was initially developed by the State of California as the standard to be

used for noise planning and analysis around airports, but is also used for environmental analysis of other sources of noise. NMAP 6.1 uses the following relationships to determine CNEL exposure:

FLYOVER:

 $L_{CNE} = L_E + 10 \cdot \log_{10}(N_{day} + 3 \cdot N_{eve} + 10 \cdot N_{night}) - 49.4$ 

**RUNUP**:

 $L_{CNE} = L_A + 10 \cdot \log_{10}(N_{day} \cdot t + 3 \cdot N_{eve} \cdot t + 10 \cdot N_{night} \cdot t) - 49.4$ 

where L<sub>CNE</sub> = Community Noise Equivalent Level

 $N_{cve}$  = number of operations between 1900 hrs and 2200 hrs.

All the other parameters are as listed for DNL.

#### 2.1.3 Noise Exposure Forecast (NEF)

The NEF descriptor is based on the Effective Perceived Noise Level (abbreviated EPNL, with the letter symbol L<sub>EPN</sub>, as a time-integrated single event descriptor) and the non-time integrated, tone-corrected Perceived Noise Level (abbreviated PNLT, with a letter symbol L<sub>PNT</sub>, as the descriptor for instantaneous noise levels). NMAP 6.1 uses the following relationships to determine NEF exposure:

FLYOVER:

 $NEF = L_{EPN} + 10 \cdot log_{10}(N_{day} + 16.67 \cdot N_{night}) - 88.0$ 

**RUNUP:** 

NEF =  $L_{PNT} + 10 \cdot log_{10}(N_{day} \cdot t + 16.67 \cdot N_{night} \cdot t) - 98.0$ 

where LEPN = Effective Perceived Noise Level,

L<sub>PNT</sub> = Perceived Noise Level, Tone-Corrected

and the other parameters are as listed as for DNL.

The EPNL value is obtained from tables of EPNL flyover noise versus one-third octave distances, corrected for temperature and humidity. These tables are generated by the OMEGA 10.7 program in a similar manner as described for the DNL calculations. The PNLT values are obtained from PNLT versus one-third octave distances generated by the OMEGA 11.3 program, also as described for the DNL calculations.

#### 2.1.4 Weighted Equivalent Continuous Perceived Noise Level (WECPNL)

The WECPNL descriptor<sup>7</sup> is based on PNLT and is used frequently in Europe. In the NMAP 6.1 program WECPNL is implemented as a three period day. NMAP 6.1 uses the following relationships to determine WECPNL exposure:

FLYOVER:

WECPNL =  $L_{EPN} + 10 \cdot log_{10}(N_{day} + 3 \cdot N_{cvc} + 10 \cdot N_{night}) - 39.4$ 

**RUNUP:** 

WECPNL =  $L_{PNT} + 10 \cdot log_{10}(N_{day} \cdot t + 3 \cdot N_{cve} \cdot t + 10 \cdot N_{night} \cdot t) - 49.4$ 

where LEPN and LPNT are defined as for NEF above, and N<sub>day</sub>, N<sub>cvc</sub> and N<sub>night</sub> are day, evening and night operations respectively.

The LEPN and LPNT values are obtained as described for the NEF descriptor.

#### 2.2 Flight Segment Addition and the Effects on Grid Exposure

#### 2.2.1 The Flight Segmentation Concept

One of the first major operations that NMAP performs, when processing the input file, is to formulate a three-dimensional model of the aircraft flight parameters entered into the NMAP input file (NMI file). This aircraft flight profile model is constructed from the power, altitude and ground track coordinates which are entered as separate profiles in the NMI file. NMAP 6.1 (and all previous versions of the program) used this segmentation scheme in order to model the geometry of the aircraft operations.

NMAP 6.1 uses these three profiles, as stated before, to build one flight profile based on the three parts. The final aircraft flight profile is based primarily on a power profile with the altitude and ground track profiles being used to further segment the merged flight profile. When the aircraft flight profile has been merged, it will have all the coordinates from the power profile as well as any of the unique coordinates that may exist in the altitude and ground track profiles.

The specifics of the segmentation scheme are as follows:

(1) Elements of the power profile are used as the primary coordinates of the merged flight profile;

- (2) any additional coordinates in the altitude and ground track profile that do not coincide with coordinates at which changes in the power profile are made, are added to the emerging flight profile;
- (3) the emergent flight profile is then an accumulation of all the distinct segments in the altitude, power and ground track profiles.

At this point three terms need to be specifically defined.

- Merged flight profile: A merged flight profile is the resultant combination of all the segments of power, altitude and ground track profiles.
- Flight segment: A flight segment can be considered as the power segment, or that portion of the flight profile that is dominated by a particular power setting.
- Subflight: one or more subflights may occur within a flight segment which are contributions from the altitude and ground track profiles. These subflights may occur wherever there are changes in the altitude and ground tracks, such as altitude changes or turns, that do not coincide with changes in the power profile.

#### 2.2.2 Flight Segment Addition

By segmenting the flight profile the problem now arises of maintaining a continuum where the individual flight segments come together. This problem is handled by the grid searching algorithm (as outlined in section 2.3.2). To synopsize this algorithm, in the context of addition of the segmented flight path, the following points can be made:

- (1) The search for grid points of significant noise exposure are always conducted from the beginning and midpoints of each flight segment.
- (2) The grid point search extends both forwards and backwards from the beginning and midpoints of each segment, and ends when the calculated exposure falls below the exposure cutoff value or the grid boundary is encountered.
- (3) The contributions from each of the segments are cumulatively added to the total grid point exposure, but only if the calculated (new) noise exposure is above the exposure cutoff value.

In this way the exposure contributions from each of the segments are added together to maintain continuity.

#### 2.2.3 Effects on Grid Exposure

The exposure at any grid point is a cumulative sum of all of the contributions of all of the segments in the merged flight path. This can be expressed mathematically for any one grid point as:

Grid Point (x) Exposure = 
$$\sum_{i=1}^{n_{SCg}} E_{SEGi}$$
 (1)

where

 $n_{seg}$  = the number of segments for a given flight,

 $E_{SEGi}$  = the calculated exposure for the ith segment in terms of energy, i.e.,  $10^{(L_{Eseg/10})}$  or  $10^{(L_{EPNseg/10})}$ . Note also that the segment exposure is itself the sum of all the subflight noise exposures within each segment.

#### 2.3 Grid Points - Layout and Spacing

#### 2.3.1 Noise Grid Layout

The grid of noise observer locations that NMAP 6.1 uses to generate noise contours is shown in Figure 1. The grid is 100 by 100 points square and is not resizable nor can it be rotated. The grid spacing is variable, however, thus allowing a coarse or refined contour analysis and to allow coverage over larger land areas. The grid origin (or airfield origin) is also relocatable relative to the airfield runways thus allowing some optimization (or weighting) for areas around the airbase that have a larger volume of operations. The grid is always aligned with a true north orientation.

At the default grid spacing of 1000 feet (304.8 meters) the length of each side of the NMAP grid is 99,000 ft (30,175 meters). This is considered large enough to cover the entire airbase or airport traffic areas for most, if not all, airbases or airports.<sup>8</sup>

Grid point numbering starts from number one at the grid origin and at which point the cumulative grid distance increment is zero. Grid point numbering ends at grid point number 100 at which point the cumulative grid distance increment is 99,000 feet (at the default grid spacing of 1000 feet). Since the grid is square this orientation is consistent in both the x and y directions.

As a convenience to the user, the nominal center of the grid is located at 100,000 ft and 200,000 ft in the x and y directions respectively. This almost always guarantees that the user will be able to define specific points, runup pads and runways in positive x and y coordinates. However, when the program handles these data, it subtracts 50,000 ft and 150,000 ft from the x and y coordinates respectively. This will become apparent in the sample calculation in Section 3.0.

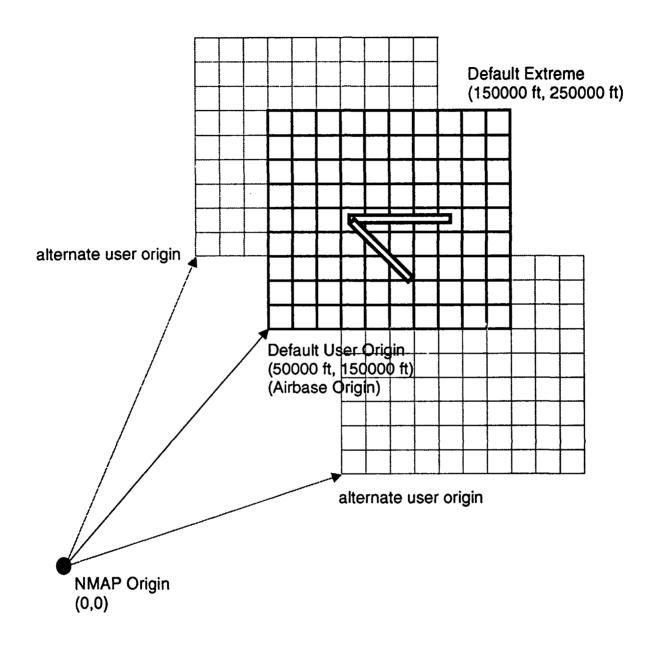


Figure 1. NMAP 6.0 Default Grid Placement as seen by the User. (The figure shows how the grid can be moved relative to the airbase runways in the user coordinate system.)

#### 2.3.2 Finding Grid Points of Significant Exposure

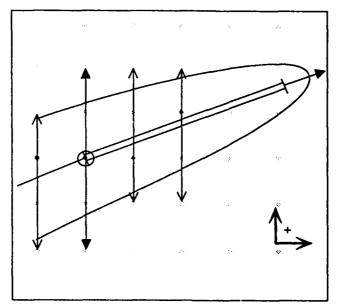
A grid point of significant exposure is one where the calculated noise exposure is at or above a minimum threshold based on the noise descriptor being used. The search for grid points of significant exposure is accomplished by using the aircraft ground track as the centerline of the noise exposure. For each segment in the merged flight track (see section 2.2 for an explanation of segments), the beginning point and the mid-point of the segments, are used as initiation points in the grid search as shown in Figure 2. From each of these initiation points a search is conducted for those grid points that have a calculated exposure value at or above the exposure cutoff limit, or is within the grid array boundary.

The search from an initiation point is conducted along the y-ordinate, above and below that initiation point only. In order to find all the grid points of significant exposure new initiation points must be chosen along the x-ordinate, to the left and right of the current initiation point. These new points are called "reference points". To clarify the terminology, note that an initiation point is in fact a reference point, with the distinction that it coincides with either the beginning or midpoint of a segment.

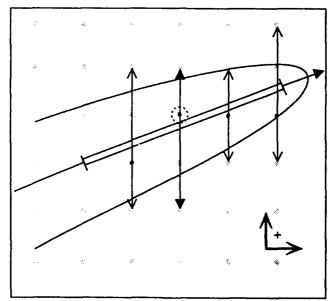
Each new reference point is determined using the following rules:

- (1) The new reference point x-coordinate is located to the left or right of the current reference point, by an amount equal to the grid spacing being used.
- (2) The y-coordinate of the new reference point is located at a grid point closest to the center of the extremes of the ordinate traversal of the last reference point.

From the first initiation point the search proceeds up and down in the y-direction until the grid boundary or exposure cutoff limit is reached, whichever comes first. When a vertical limit has been reached, a new reference point is chosen that is left of the initiation point, and whose ordinate is the midpoint of the ordinate traversal of the last reference point. Traversal of the new reference point proceeds up and down in the y-direction until the exposure cutoff or grid boundary is reached. New reference points are chosen in this direction until exposure cutoff or the grid boundary is reached in the x-direction. At the end of the search to the left of the initiation point a new reference point is then chosen to the right of the initiation point, and the search proceeds as described above, until the exposure cutoff or grid boundary is reached in this x-direction.



Grid Search from the Beginning Initiation Point.



Grid Search from the Mid Point Initiation Point.

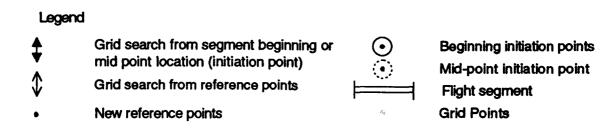


Figure 2. NMAP 6.0 Grid Searching Algorithm Used to Find Grid Points of Significant Exposure

When the exposure cutoff or grid boundary has been reached (both left and right of the first initiation point) then the procedure is repeated for a new initiation point closest to the middle of the current flight segment (see Section 2.9 for the exposure cutoff values).

The algorithm for the grid search as described above results in a dynamic tracking of the noise exposure but runs the risk of sampling the same point more than once, particularly during the grid search from the midpoint of the segment. To avoid the error of over-exposing a particular point, the sign of the noise exposure value is used as a flag. During the grid search the sign of the value of an updated grid point is reversed after a computation has been made. On completion of the grid search the negative exposure values are sought out and their signs restored. Before the grid points are updated they are also checked to see if the value is positive (i.e., > 0.0).

The limits of the grid traversal (i.e., the max x and y and then min x and y distances travelled) are also stored in memory, so that at the end of a flight segment grid search, the bounds of the negative grid points values can be more easily identified and and their values restored.

#### 2.4 Grid Point Noise Exposure Calculations

#### 2.4.1 Flyover Operations

Aircraft noise that is due to flyover operations is covered by two algorithms in the NMAP 6.1 program. One algorithm covers straight flight segments and the other covers curved segments.

Basically, both of these algorithms take the reference noise data and any of the generalized noise corrections at each end of a subflight and extrapolates them to the closest point of approach to the observer location. The generalized noise corrections include the takeoff roll correction,  $\Delta_6$ , altitude thrust adjustment, airspeed, and user input level adjustments called DSEL. These corrections are explained further in Section 2.4.3.

#### 2.4.1.1 Straight Segments

The calculation for the noise exposure due to a straight line segment is determined by the following formulation:

Noise exposure = 
$$E_{rc} \cdot |C_y|$$
. (2)

where  $E_{rc} = 10^{(Lref/10)}$  at the closest point of approach,

L<sub>ref</sub> = the noise exposure value, interpolated or extrapolated to the closest point of approach to the subflight, from the noise exposure tables generated by OMEGA 10.7

Cy = an exposure factor, which is based on the geometry of the aircraft attitude in relation to a direct overflight, and includes generalized corrections factors.

The following equation for  $C_y$  is a numerical formulation that modifies the noise exposure value from an infinite line source to a finite length (see Figure 3):

$$C_y = \left\{I_c \cdot \frac{\left(\sin\left(\text{COA}\right) - \sin\left(\text{COB}\right)\right)}{2}\right\} + \left\{\left[\frac{(F_a - F_b)}{AB} \cdot \text{OC}\right] \cdot \frac{\left(\cos\left(\text{COB}\right) - \cos\left(\text{COA}\right)\right)}{2}\right\} (3)$$

where I<sub>c</sub> = a generalized correction factor that is interpolated to the closest point of approach (see also F<sub>a</sub> and F<sub>b</sub>). This correction factor can include any model that should be applied within a merged flight segment. Current corrections are listed in Section 2.4.3.

COA = the angle subtended by the closest point of approach (CPA) to the beginning of the flight segment,

COB = the angle subtended by the CPA to the end of the flight segment,

F<sub>a</sub> = the value of the generalized correction factor at the beginning of the flight segment,

F<sub>b</sub> = the value of the generalized correction factor at the end of the flight segment,

OC = the slant range distance or the distance between the CPA and the observer location,

AB = the signed length of the segment between points A and B as determined by the difference of AC-BC. This result maintains the sign convention discussed below,

BC, AC = the signed distance between points A and C and points B and C, respectively,

Sign Convention = the angles COA and COB are given the following sign convention.

The angle is positive if the opposite leg of the right triangle formed from the CPA point to the segment point (A or B) is in the same direction as the flight, or negative if opposite. It therefore follows that both COA and COB are positive in figure 3.

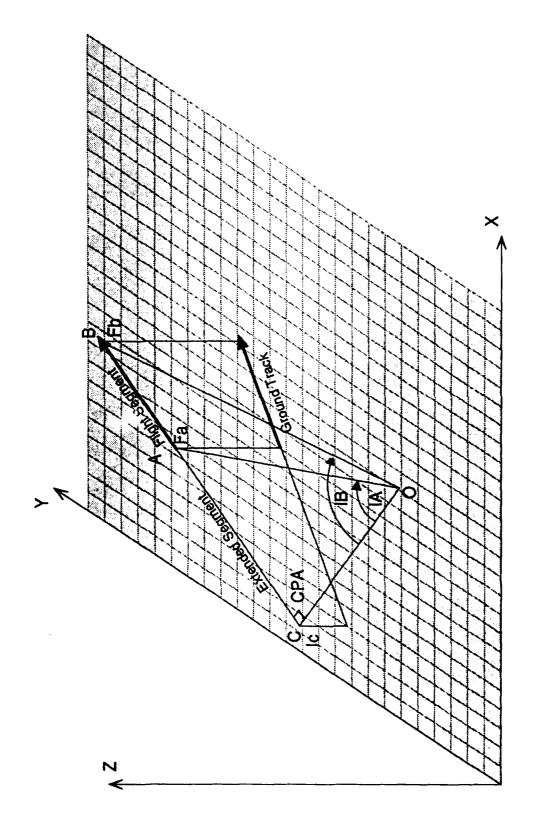


Figure 3. Geometry for the Algorithm Used to Determine Flight Segment Noise Exposure Integral

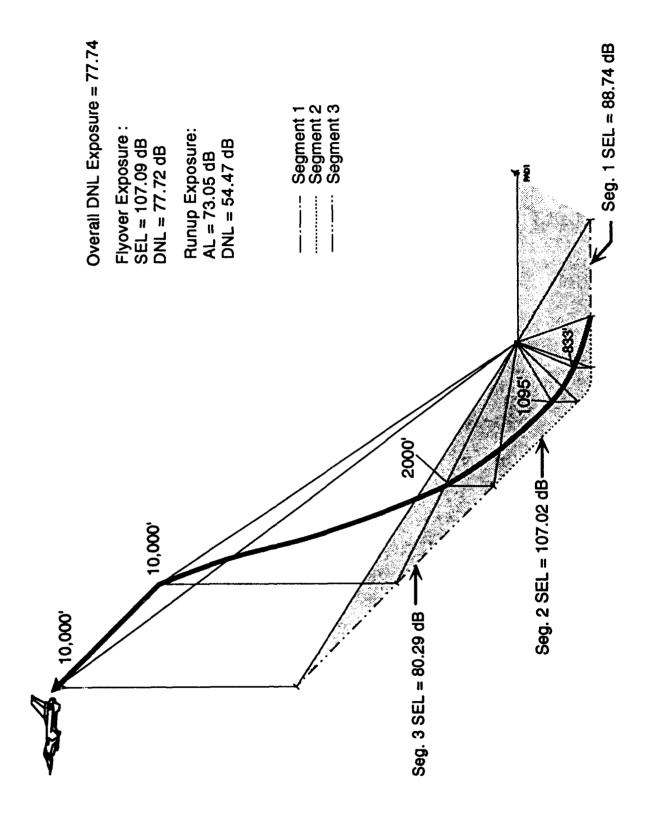


Figure 4. Ground Track Geometry and Resulting Exposures for Sample Case.

Figure 4 shows the ground track geometry and what might be the actual flight track of the sample case after NMAP 6.1 has determined the power and subflight segments. The figure also shows the resulting sound exposures for each segment. The segment sound exposures are used as factors for the reference noise data that are appropriate to the geometry for the particular power segment. The sound exposure for a segment with a single subflight can be calculated straight away from the formulation listed above. The calculations in Section 3.1 for the first segment in the sample case show exactly how that is done.

For segments with multiple subflights a slight deviation is necessary. The basic formulation stays the same except that the relative sound exposure factors are accumulated over the segment using a normalization of the form  $|C_{ysub}|/(SL_{sub})^2$ .

When all of the subflights have been determined then the slant distance associated with the largest exposure factor value in the segment can be found. The slant distance to the associated subflight,  $SL_{dom}$ , is used to determine the reference exposure value,  $L_{ref}$ , as well as to calculate the sum of the exposure factors.

The resulting normalized factor is expanded as follows:

$$\left(\sum_{i=1}^{N_{\text{sub}}} |C_{yi}| / SL_{\text{sub}}^2\right) \cdot SL_{\text{dom}}^2 \tag{4}$$

where  $N_{sub}$  = Number of subflights

SL<sub>sub</sub> = Slant range between the observer and the CPA of the subflight

 $SL_{dom}$  = Slant distance to the subflight with the largest  $C_y$ .

The data in Section 3.1 will show these results in segments 2 and 3 of the sample calculation.

#### 2.4.1.2 Curved Segments

The noise exposure due to an aircraft executing a turn is approached in a similar manner as explained above for straight line segments. The calculated grid point noise exposure is therefore a product of the reference noise level extrapolated to the observer distance and a factor to account for the aircraft attitude. This is expressed, as before, as:

Noise exposure = 
$$E_{rc} \cdot |C_y|$$
 (5)

The value of  $E_{rc}$  is the same as for Eq. 2. The calculation for the value of  $C_y$  is slightly more complicated for curved segments.  $C_y$  is determined from the following formulation based on the geometry shown in Figure 5:

$$C_{y} = R \cdot SL^{2} \left( \frac{\sec \beta}{\det} \right) \left\{ F_{a} \left[ \frac{(2C_{2}\theta + C_{1})}{\det} - \frac{C_{1}}{\sqrt{C_{0}}} \right] + \left[ \frac{(F_{a} - F_{b})}{\theta} \right] \left[ \frac{(C_{1}\theta + 2C_{0})}{\det} - 2\sqrt{C_{0}} \right] \right\}$$
 (6)

where R = the radius of curvature of the aircraft turn,

SL = the slant distance between the middle of the curved segment and the observer,

$$\sec\beta = \sqrt{1 + (\tan\beta)^2},$$

 $\tan \beta = \frac{Z_b \cdot Z_a}{D_b \cdot D_a}$ , where  $Z_a$  and  $Z_b$  are the altitudes at point A and B respectively,  $D_b$  and  $D_a$  are the cumulative distances from the start of roll along the ground track to the points A and B respectively,

$$C_0 = X_0^2 + Y_0^2 + Z_a^2 + R^2 - 2 \cdot R \cdot X_0$$

$$C_1 = -2 \cdot R \cdot Y_0 + 2 \cdot R \cdot \tan\beta \cdot Z_a \cdot \text{symm}$$

$$C_2 = R^2 \cdot \tan \beta^2 + 2 \cdot R (0.47483 \cdot X_0 + \text{symm} \cdot 0.1269 \cdot Y_0)$$

symm = +1 for left, -1 for right turn,

x<sub>0</sub> = the X coordinate of the observer in the coordinate system where the center of curvature of the turn is the origin, and the radial vector to the first point of the segment, in the ground plane, is along the positive x-axis,

 $Y_0$  = the Y coordinate of the observer in the coordinate system outlined above,

$$den = \sqrt{|C_2\theta^2 + C_1\theta + C_0|},$$

 $\det = 4C_0C_2 - C_1^2,$ 

F<sub>a</sub> = the generalized correction factor at point A, at the beginning of the curved segment, as explained in Section 2.4.1.1,

F<sub>b</sub> = the generalized correction factor at point B, at the end of the segment, see Section 2.4.1.1,

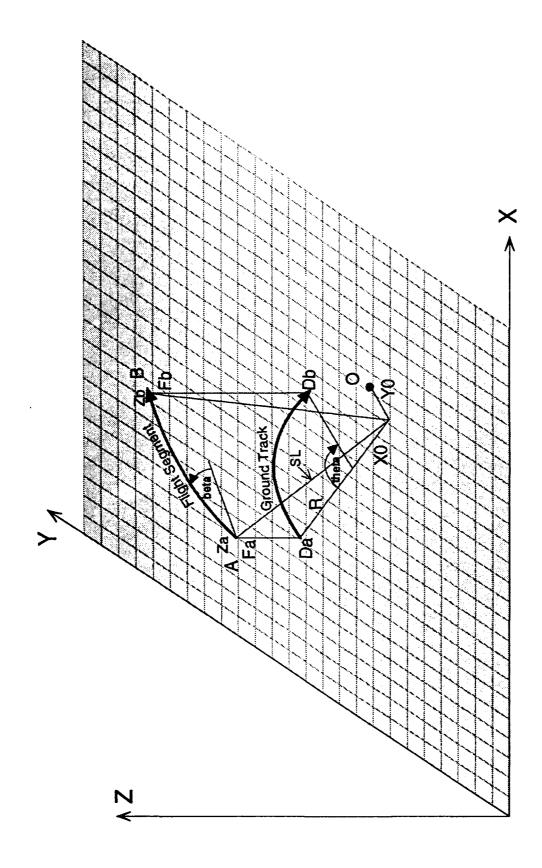


Figure 5. Geometry of the Algorithm Used to Determine Flight Segment Noise Exposure from Curved Flight Path Segments.

the negative value of the arc length of the turn in radians. This value cannot exceed a magnitude of  $\pi/3$  radians (60 degrees) since there is an assumption that the tangent of the angle  $\beta$  can be approximated by the term  $\frac{Z_b - Z_a}{D_b - D_a}$  (see also the description of the variable  $\tan \beta$ ), which is the change in altitude divided by the ground track distance between points A and B.

#### 2.4.2 Runup Operations

The noise calculated for ground runup operations are determined in a similar manner as those for flyover, with the exception that flight segmentation rules and corrections for air-to-ground absorption are not applied.

The OMEGA 11.3 program operates on data in the NOISEFILE 6.2 and produces noise level tables appropriate to the requested noise descriptors corrected for temperature and humidity. The resulting tables are not corrected for altitude but are left in terms of sea-level altitude as is the default for NOISEFILE. The data are organized as basically 10 rows of angles, each row containing data at one-third octave increments, starting at 200 ft and ending at 25,000 ft. NMAP 6.1 interpolates and extrapolates these values to other distances and angles.

The noise exposure is determined by assuming the area of significant exposure will be bounded by the extreme edges of the cardioid shape associated with runup noise directivity patterns. The grid points within this area are searched out, and the noise exposure is calculated. If the calculated noise exposure is above the cut-off value (see Section 2.9 for the exposure cut-off values) for the selected noise descriptor then the grid point is updated by adding the calculated exposure.

The calculated exposure is obtained by determining the following:

- (1) The direction in which the nose of the aircraft is pointing.
- (2) The distance between the grid point (or observer location) and the center of the runup pad.
- (3) The angle between the centerline of the runup pad and the line joining the center of the runup pad to the observer position.
- (4) The appropriate reference noise tables from which the noise exposure will be calculated.

For runup pads, NMAP 6.1 takes item (1) directly from the input file from the AIRFLD keyword<sup>9</sup> and applies the magnetic heading correction before using it as the runup pad heading.

The distance between the center of the pad and the observer position is determined by transforming the NMAP 6.1 grid locations of the observer position, and the center of the runup pad, to a coordinate system with the center of the runup pad as the origin (see Figure 6). This is accomplished with coordinate translation and rotation. The observer angle is measured between the intersection of the heading of the runup pad (to which the aircraft is also aligned) and a line joining the observer position to the center of the runup pad. The length of this line is the distance to the observer.

The proper reference noise values are determined by looking up the reference table for the aircraft in question and, looking up the angle and distance closest to the angle and distance previously found, then interpolating or extrapolating both for angle and distance for the correct exposure value. Section 3.1 shows the development of the runup exposure determined for a sample case.

#### 2.4.3 Noise Corrections

As mentioned earlier, NMAP 6.1 uses noise corrections at the end points of segments and subflights. The purpose of these noise corrections (or generalized correction factors) is to help refine the accuracy of the reference noise data. The current noise corrections are as follows:

- (1) The takeoff roll Δ6 correction scale factor <sup>10</sup>: The takeoff roll model is discussed in detail in Section 2.7. The model is based on a reference directivity noise level adjustment that is applied to the aircraft ground runup reference noise data and scaled by the value of 10<sup>(V/160 kts)</sup> at the start of roll and 1.0 at the point of rotation. V represents the actual takeoff speed and 160 kts is the value defined in Reference 10.
- (2) Airspeed correction: The aircraft reference noise data is generated at discrete airspeeds entered at points of change in the flight profile. Since the reference noise data can be heavily influenced by the aircraft airspeed a correction was added to interpolate the aircraft airspeed to the closest point of approach to the observer, as is done for other noise corrections. This correction has no effect during the ground roll portion of the flight and is therefore has a value of 1.0 at the first two parts in any takeoff. The correction is also 1.0 at the landing point. At all other points the correction is based on  $10^{(V/V_{ref})}$  (where V is the actual aircraft speed and  $V_{ref}$  is the takeoff or landing speed). Touch-and-go's with a

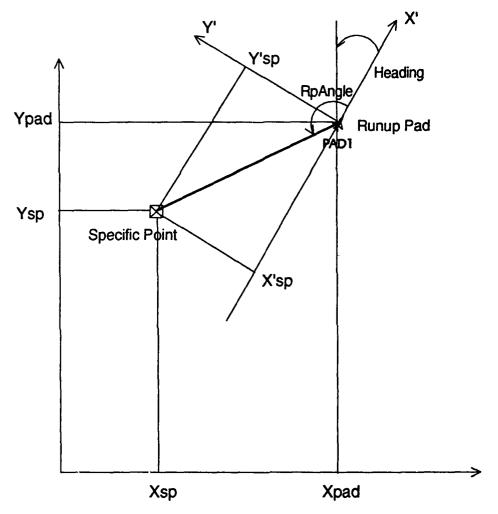


Figure 6. Runup Pad Geometry and Pad Coordinate System. (shaded axis represent the grid coordinate system solid axis represent the pad coordinate system.)

takeoff roll are treated similarly to takeoff, and touch-and-go's with no takeoff roll are treated similarly to landings.

- (3) Altitude thrust adjustment: Above 1,000 ft altitude a correction is applied to correct the reference noise data, which are in terms of sea level conditions for altitude. The correction effectively decreases the reference noise data by 2 dB per 10,000 feet. The correction assumes that noise output is reduced as effective thrust decreases, and effective thrust decreases with altitude (reference 1). This adjustment is calculated as 10[(1000-alt)•2E-5)].
- (4) User-entered noise level adjustments (DSEL): NMAP 6.1 retains a feature that was available in previous versions, which allows users to modify the reference noise data base on information that may not already be contained in NOISEMAP. The complete details on this feature may be found in Reference 8.

#### 2.5 Specific Point Noise Exposure Calculations

Noise exposure calculations that are made at specific points on the ground that are not necessarily aligned with the NMAP grid of observer points, and are completely user-definable are called Specific Point Noise Calculations. The calculations for noise exposure at specific points are done exactly as described for grid point calculations (section 2.4) with the following exceptions:

- (1) No grid searching algorithm is applied for specific points.
- Whereas the grid of observer locations is fixed, specific points are completely user defined and can even be located outside the NMAP grid.
- (3) The maximum number of specific points is 16.
- (4) The specific point calculations are performed independently of the grid point calculations thus allowing these calculations to be made without doing grid point calculations.
- (5) Calculations are not subject to the cut-off values.

The process of calculating the noise exposure at specific points is the following:

- (1) The X,Y coordinates of the specific points are passed to the noise exposure calculation routines instead of grid point coordinates.
- (2) The noise exposure calculations for each of the merged flight segments are performed, as detailed for the grid exposure calculations. The takeoff roll and lateral attenuation models are applied where appropriate.
- (3) The noise exposure at any specific point is the summation of all the contributions from all of the flight segments.

#### 2.6 Takeoff Roll and the Effects of Forward Velocity

A takeoff roll model has been implemented in NMAP to model the sideline noise generated by an aircraft during takeoff roll. The takeoff roll model is based on a study described in detail in reference 10. The results of the study indicate that the change in the noise source emission during the takeoff roll can be approximated by adding a varying correction that is a positive adjustment at the start-of-roll, which reduces to zero at the point of rotation. Using reference 10 terminology, this adjustment is now referred to as  $\Delta_6$ .

The study was based on the noise levels of a Boeing 707-300 with an operating weight of 265,205 lbs, which assures a climb speed of 160 knots based on that aircraft's performance data. Under these reference conditions a runup profile was generated with NOISEMAP 3.2 for the B707-300. The runup noise data were used to simulate an actual aircraft "rollby" using 200 foot grid spacing. The variation in  $\Delta_6$  as a function of sideline distance aircraft weight and accleration was determined from this reference data.

The study also determined a series of adjustments that should be applied to the aircraft reference flyover data in order to model the takeoff directivity pattern. These adjustments are shown in Table 1 and represent the B-707-300 flyover noise levels adjusted to a desired directivity pattern and normalized to the reference ground-to-ground reference noise data. These reference directivity adjustments are added to all aircraft takeoffs as part of the takeoff roll model. The data in this table are 5 dB lower than the data used in Reference 9, since this 5 dB correction is now added by OMEGA 10.7 when it generates the reference noise exposure tables. NMAP 6.1 uses the following model to scale the referenced directivity pattern to the actual aircraft takeoff speed and takeoff roll distance.

Using the reference B707-300 flight parameters listed above, the correction for acceleration tak—the following form:

$$\Delta \operatorname{accl} = -5 \cdot \log_{10} \left[ \left( \frac{V_{\text{rot}}}{V_{\text{ref}}} \right)^2 \cdot \left( \frac{S_{\text{ref}}}{S_{\text{rot}}} \right) \right]$$
 (7)

relative to the acceleration of the reference B707-300. However, the correction relative to a  $V_{rot}$  will require the addition of the difference between the  $V_{ref}$  of 160 kts, leaving the final correction as:

$$\Delta_6 = -5 \cdot \log \left[ \left( \frac{V_{rol}}{V_{ref}} \right)^2 \cdot \left( \frac{S_{ref}}{S_{rol}} \right) \right] + 10 \cdot \log_{10} \left[ \left( \frac{V_{rol}}{V_{ref}} \right) \right]$$
 (8)

This  $\Delta_6$  value is then used to adjust the reference takeoff directivity pattern from the B707-300 to an approximation of the actual aircraft. The study cited did make calculations for two aircraft (a B707-300 with a different takeoff weight and an F-104) with reasonable results. The model was also validated against measured data also with reasonable results.

At the time of the development of the original takeoff roll model,  $V_{rot}$  would almost always differ from the noise data at reference speed  $V_{ref}$ . Currently, the OMEGA 10.7 program generates the noise data set for the input  $V_{rot}$  speed. The  $\Delta_6$  term therefore becomes:

$$\Delta_6 = -5 \cdot \log \left( \frac{S_{\text{ref}}}{S_{\text{rot}}} \right) \tag{9}$$

where  $S_{ref} = 4779$  ft which is the ground roll distance for the referenced B-707 aircraft.

Some of the assumptions of the NMAP 6.1 takeoff roll model, as stated in Reference 10, are as follows:

- (1) The effects of forward velocity on the directivity pattern of the aircraft engine in question will not significantly affect the overall noise levels for the takeoff, and are thus ignored.
- (2) The acceleration of the aircraft is assumed to be constant.
- (3) The directivity pattern of the aircraft at the start-of-roll position (takeoff configuration) is that for a static full-power runup.

To implement this takeoff roll model in NMAP 6.1, the following actions are performed by the program.

- (1) A directivity pattern is constructed based on the reference B707-300 directivity offset shown in Table 1. This is done by adding these offsets to the reference ground-to-ground data for the takeoff power condition of the aircraft in question. In this way a reference noise table is built of level versus angle versus one-third octave distance increment.
- (2) Once the reference directivity pattern has been created, then the noise exposure for takeoff roll is calculated using the same procedures as for the runup exposure calculation.
- (3) The calculated takeoff roll runup exposure is then added to the "flight" exposure, that is, the exposure calculated strictly from the aircraft flyby.

7			8	8		3	3	3	3
12.5	 12.4	12.1	11.8	11.4	10.5	10.1	9.4	8.4	7.2
12.5	 12.4	12.1	11.8	11.4	10.5	10.1	9.4	8.4	7.2
9.7	 9.4	9.1	8.6	8.0	7.0	6.4	6.7	4.7	3.4
8.7	 8.3	7.8	7.1	6.4	5.2	4.3	3.3	1.9	0.2
9.9	 6.3	5.8	5.3	4.7	3.6	2.9	2.0	6.0	-0.5
7.0	 6.8	6.4	5.9	5.4	4.4	3.8	3.0	2.1	6.0
7.1	 7.0	6.8	6.4	6.1	5.3	4.9	4.4	3.7	2.8
9.5	 9.3	9.0	8.5	8.0	7.1	9.9	5.6	5.1	4.0
1.5	 1.3	1.0	0.5	0.0	-0.9	-1.4	-2.1	-2.9	-4.0

Colore Dist. Angle	13500	3150	000	000 9	008 8	0008	10000	12500	16000	20000	25000
0	6.0	4.2	7		•	*	*	٠	*	*	•
20	0.9	4.2	1.1	•	•	•	•		*	*	•
38	2.1	0.2	-2.3	-7.6		•	•	•	*	•	•
22	-1.5	-3.8	-7.2	-24.4	*	٠	٠	*	*	•	•
2	-1.6	-3.0	4.4	-5.3	-7.0	-10.4	•	•	•	•	•
8	- 0.1	-1.2	-2.2	-2.3	-2.6	-3.3	-3.8	-4.5	-5.2	-5.5	-5.6
110	2.1	1.4	0.3	9.0	9.0	0.4	0.3	0.5	0.1	0.3	9.0
130	3.2	2.2	1.4	1.5	1.2	8.0	0.5	0.0	-0.4	-0.5	9.0-
<u>8</u>	4.8	-5.8	9.9-	-6.5	-6.8	-7.2	-7.5	-8.0	-8.4	-8.5	-8.6

to simulate takeoff roll noise levels.

(\* - A value of 1E-35 is used to reduce the influence of the directivity adjustments in these directions.) Table 1. Directivity adjustments that are applied reference runup noise levels

2000	7.2	7.2	3.4	0.2	-0.5	6.0	2.8	4.0	-4.0
1600	8.4	8.4	4.7	1.9	6.0	2.1	3.7	5.1	-2.9
1250	9.4	9.4	6.7	3.3	2.0	3.0	4.4	5.6	-2.1
000 000	10.1	10.1	6.4	4.3	2.9	3.8	6.4	9.9	-1.4
<b>0</b>	10.5	10.5	7.0	5.2	3.6	4.4	5.3	7.1	-0.9
059	11.4	11.4	8.0	6.4	4.7	5.4	6.1	8.0	0.0
200	11.8	11.8	8.6	7.1	5.3	5.9	6.4	8.5	0.5
400	12.1	12.1	9.1	7.8	5.8	6.4	6.8	9.0	1.0
345	12.4	12.4	9.4	8.3	6.3	8.9	7.0	9.3	1.3
250	12.5	12.5	9.7	8.7	9.9	7.0	7.1	9.5	1.5
7.200 A	12.6	12.6	9.6	9.0	6.8	7.2	7.1	9.6	1.6
(J.S. Course Days Angle	0	20	જ	22	2	8	110	130	180

25000	•	•	*	•	•	-5.6	9.0	9.0-	<b>-8</b> .6
20000	*	•	•	٠	٠	-5.5	0.3	-0.5	-8.5
16000	•	•	•	•	*	-5.2	0.1	-0.4	-8.4
12500	•	•	*	*	•	-4.5	0.2	0.0	-8.0
10000	•	*	•	•		-3.8	0.3	0.5	-7.5
0008	•	•	•	•	-10.4	-3.3	0.4	0.8	-7.2
0089	*	*	٠		-7.0	-2.6	9.0	1.2	-6.8
2000	•	*	-7.6	-24.4	-5.3	-2.3	9.0	1.5	-6.5
4000	1.1	1.1	-2.3	-7.2	4.4	-2.2	0.3	1.4	9.9-
.315 <u>0</u>	4.2	4.2	0.5	-3.8	-3.0	-1.2	1.4	2.2	-5.8
.2500	6.0	0.9	2.1	-1.5	-1.6	0	2.1	3.2	4.8
12 Octore Dist. Angle	0	20	38	20	2	8	110	130	180

Table 1. Directivity adjustments that are applied reference runup noise levels to simulate takeoff roll noise levels.
(\* - A value of 1E-35 is used to reduce the influence of the directivity adjustments in these directions.)

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119.4	200 KTS		103.5	79.5	116.4	97.6 70.0
121.4	<b>74</b> ~	×	105.7	83.3	119.1	99.7 75.3
123.3	2	031A1 90.00 % RPM	107.9	86.9	122.2	101.8 80.1
125.3	90 F-1	+	109.9	90.2	125.3	104.0 
127.3	.6 28 Dec	PASS FAN POWER	111.9	93.2	127.3	106.2           
N	OMEGA10	HIGH BYPASS TAKEOFF POW	11 113.8	96.0	H	108.6 90.6
061011	061011WO	COMMENT 061011W0	115.6	98.7	061011	111.2 
SEL	COMMENT 061011W0 OMEGA10.6	COMMENT				

LEGEND

1 Comments Identifying and Describing the Power Conditions 2 AIR-TO-GROUND SEL Values

3 GROUND-TO-GROUND SEL Values

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Figure 7. OMEGA 10.6 Reference Noise Data Set. Generated from the NOISEFILE 6.0 Database.

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	70 PC	G F1	N & 0	76.1	7	ij	ω.	4	ω	4.	α.	7	ω	٦.	ä	9	о	6	د	3	و	4.	ω	о О	ъ.	0	9	ς.	ω	5	급	ω
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Figure 8. OMEGA 11 Reference Noise Data Set. Generated from the NOISEFILE 6.0 Database. (Shaded numbers are angles in degrees measured about the aircraft centerline, 0 being forward of the aircraft. ).

The reference data that are generated by the OMEGA 10.7 and 11.3 programs are then used by NMAP 6.1 to extrapolate to other distances and other angles of propagation relative to the ground plane.

### 2.7.2 Lateral Attenuation and Transition Factor

Lateral attenuation accounts for the effects of ground absorption and aircraft shielding on sound propagation for positions to the side of an aircraft flight track. In NMAP 6.1 this is accomplished by one of two lateral attenuation models. One is applicable to air-to-ground noise level data for civil aircraft<sup>13</sup> and the other is applicable as a transition factor which interpolates between air-to-ground and ground-to-ground noise metric data for military aircraft.<sup>14</sup> Both are shown in Figure 9.

The SAE model is evoked for all civilian aircraft contained in NOISEFILE 6.2. The SAE model has been compared to actual measured civilian and military aircraft noise. The results of these comparisons show that the model predicts lateral attenuation for civilian aircraft with a reasonable level of accuracy but does not perform quite as well for military aircraft, resulting in an over-prediction of the value for the majority of military aircraft. Hence the need for a different lateral attenuation model for military aircraft.

In NMAP 6.1, the military lateral attenuation model is implemented in the form of a transition factor which basically interpolates between the predicted air-to-ground and ground-to-ground propagation data to determine the effects of lateral attenuation on propagation. The models are implemented as follows:

Noise exposure (d, 
$$\beta$$
) |<sub>MIL</sub> = TF • 10(GG(d)/10) + (1-TF) • 10(AG(d)/10) (9)

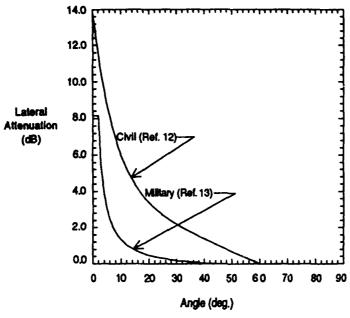
Noise exposure(d, 
$$\beta$$
)  $I_{CIV} = 10^{((AG(d)-A)/10)}$  (10)

where noise exposure  $(d, \beta)$  = the exposure at observer distance d, and elevation angle  $\beta$ ,

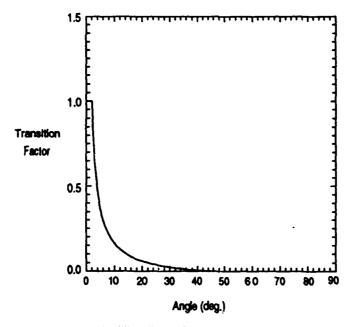
 $\Lambda$  = the SAE lateral attenuation values for civil aircraft, <sup>12</sup>

TF = the transition factor predicted by the NMAP 6.1 lateral attenuation model at angle  $\beta$ ,

- $= 1 \text{ for } 0 \le \beta < 2^{\circ}$
- =  $(2.093/\beta) 0.04651$  for  $2^{\circ} \le \beta < 45^{\circ}$
- $= 0 \text{ for } 45 \le \beta < 90^{\circ}$



a. Lateral Attenuation Models.



b. NMAP 6.0 Transition Factor Model.

Figure 9. SAE and Military Lateral Attenuation Models, and the Transition Factor Model.

GG(d) = the reference OMEGA 10.7 ground-to-ground exposure value at distance d,

AG(d) = the reference OMEGA 10.7 air-to-ground exposure value at distance d.

It can be seen from the military aircraft model that at angles of elevation greater than 45 degrees, the transition factor tends to zero and the noise exposure is predicted solely by the air-to-ground model. Likewise, at low angles of elevation the transition factor term is predicted by 1.0 and the exposure tends to ground-to-ground model.

In the NMAP 6.1 program, the transition factor is returned as a ratio of the ground-to-ground propagation value at  $(d,\beta)$ , and the air-to-ground propagation. Therefore for the first subflight in Section 3.1, the predicted transition factor is 1.0 and the resulting noise exposure is totally controlled by ground-to-ground propagation. The value returned is the ratio of the ground-to-ground reference noise exposure at  $(d,\beta)$  to the air-to-ground noise exposure under the same conditions. When NMAP 6.1 calculates the noise exposure for the segment, the transition factor will be multiplied by the air-to-ground reference noise exposure for that power segment and at the dominant slant distance for the segment. This transition factor ratio (TFR) is calculated as:

TFR = TF • 
$$\left(\frac{10^{\text{GG/10}}}{10^{\text{AG/10}}} - 1\right) + 1$$
 (11)

#### 2.8 Duration

The effect of duration on an aircraft flyby is to increase the noise exposure of the observer over that of some instantaneous level. NMAP 6.1 uses two time integrated metrics that include the effects of duration. These metrics are SEL and EPNL. Reference noise exposure data are determined in terms of these metrics by the OMEGA 10.7 program. OMEGA 10.7 uses the spectral noise data and reference integrated metrics in the NOISEFILE 6.2 noise database, and expands these to other airspeeds and distances to give the required metric. OMEGA 10.7 uses the following equation to adjust for the difference in exposure due to differing propagation distances 15.

Adjustment = 
$$6 \log (D_x/D_{ref})$$
 (12)  
where  $D_x$  = desired distance  
 $D_{ref}$  = reference distance (usually 1000 ft)

OMEGA 10.7 uses the following equation to adjust for differing airspeeds.

Adjustment = 
$$-10 \log (V_x/V_{ref})$$
 (13)  
where  $V_x$  = desired airspeed  
 $V_{ref}$  = reference airspeed

Currently the time-integrated noise levels (SEL or EPNL) are included in the NOISEMAP input file (NMI file) and are the reference noise data that NMAP 6.1 uses in its noise calculations.

# 2.9 Noise Exposure Cut-Off

NMAP 6.1 uses a threshold noise exposure level in order to increase processing efficiency. If the calculated noise exposure level at any grid point is found to be below the threshold level, then the grid search in that direction ends. All the noise exposures up to that point are computed, and all the grid points up to, but not including, the grid point where the exposure fell below the threshold are updated.

The default exposure thresholds are as follows:

DNL	CNEL	NEF	WECPNL
35 dB	35 dB	0 dB	35 dB

#### 2.10 Area Calculations

The calculation of the area bounded by the calculated noise exposure contours is approximated by dividing the grid mesh into four sections of 25 rows of grid points by 100 columns of grid points. The smaller sections are then further subdivided by taking the area bounded by four adjacent grid points and dividing them into five rows by three columns. The smaller 15 point meshes are then used to interpolate grid values to determine a contour edge. The rectangular areas bounded by the interpolated contour edge are then summed, and multiplied by the unit area of the rectangles to determine an approximate contour area.

The NMAP 6.1 area calculations compares reasonably well to calculations based on more accurate vector methods, but tends to have higher values due to the all-or-nothing addition of each subgrid section. An exact calculation of the contour area is made in the NMPLOT program and is displayed in its "show" window.

#### 3.0 NOISEMAP FEATURES AND FLIGHT CHECKS

The following is a summary of the calculations that NMAP 6.1 performs in order to obtain noise exposure contours. These sample calculations concentrate on the development of the noise exposure levels, and do not place a heavy emphasis on such aspects as flight segmentation or any of the other "housekeeping" activities involved in contour development. In fact, the program was allowed to develop all of the support data in these calculations. These data were then taken and formatted in such a way as to illustrate the implementation of the algorithms detailed in Section 2. Figure 10a and b show the NOISEMAP Input (NMI) files that resulted in the specific point summary shown in Figure 11 and the contours shown in Figure 12.

Tables 2, 3 and 4 show the flight segmentation data, the flyover noise exposure summary and the runup noise exposure summary respectively for the specific point. The specific point is specified in the NMI file by the "SPECIF" keyword as detailed in Reference 8. As was said before, the coordinates entered into the NMI file have a positive offset of 50,000 ft in the x-direction and 150,000 ft in the y-direction in order to assure that the user enters coordinates as positive x and y values. It can be seen in Table 2 that the specific point coordinates  $X_{sp}$  and  $Y_{sp}$ , as used by NMAP, have had the offsets removed.

Figure 13 shows the geometry of each of the subflights. Each element of Figure 13 shows the attitudes at each subflight endpoint, the slant distances and other physical data used in the calculations. This figure (along with Figure 4) should be used as a guide to understanding the geometry of the flight activity which produces the calculated noise exposure.

Please note that in many situations during the sample calculation a switch is made from noise levels in decibels to the power equivalent relative power. NMAP does all of its calculation in terms of power and all of its reporting in terms of decibels. It is more convenient and easier to visualize noise levels in decibels and a license is taken in showing some data in decibels and using that same data in calculations as power. To convert between the power P, and the noise level L the following relationships can be used.

To convert relative power to noise level in decibels, use:

$$L = 10 \log_{10}(P)$$

To convert noise level in decibels to relative power, use:

$$P = 10(L/10)$$

```
COMMENT ARCHIVED
COMMENT 0
COMMENT INPUT FILE
COMMENT NMAP1807.BPS
COMMENT CASE NAME
COMMENT F-15 Power runup and flight tests for NOISEMAP report - asp
AIRFLD50000. 150000. 0.
                                        1000.
                                ο. ¯
                                                                           EAST
F-15 Power runup and flight tests for NOISEMAP report - asp
COMMENT This is a test of straight out and straight in operations
COMMENT of the F-15 aircraft for the NOISEMAP 6.0 tech report
COMMENT
COMMENT NOISEMAP input created by MCM v. 1.0 on May 25 1991 at 23:27:04 from: COMMENT F-15 Power runup and flight tests for NOISEMAP report
COMMENT Created by BASEOPS Version 3.01 on 12-28-1990 at 10:25:58
PROCES
DNL
SAELAT
                                                                            ON
SPROCE
SPECIF87999. 202000.
                                                                            TEST
COMMENT *******
COMMENT **
                  FLYOVER
                             DATA
COMMENT *****
                      2 127.3 125.3 123.3
        061011
                                                            119.4
                                                                     117.5F-15
SEL
                                                     121.4
COMMENT 061011W0 OMEGA10.6 28 Dec 90 F-15
                                                          200 KTS
                                                                     59 F
                                                                            70 PCT
COMMENT 061011WO HIGH BYPASS FAN N061031A1
COMMENT 061011W0 TAKEOFF POWER
                                         90.00 % RPM
                          111.9
                                   109.9
                                            107.9
                  113.8
                                                    105.7
                                                             103.5
                                                                      101.2F-15
                                                                                     2
         115.6
          98.7
                                             86.9
                                                              79.5
                                                                       75.4F-15
                   96.0
                            93.2
                                    90.2
                                                     83.3
                                                                                     3
        061011
                                                             116.4
                           127.3
                                   125.3
                                                                      113.8F-15
                      1
                                            122.2
                                                     119.1
                  108.6
                                                              97.6
                                                                       95.5F-15
         111.2
                           106.2
                                   104.0
                                            101.8
                                                     99.7
                                                                                     5
          93.1
                   90.6
                            87.6
                                    84.3
                                             80.1
                                                     75.3
                                                              70.0
                                                                       64.3F-15
SEL
        061021
                           117.1
                                   115.3
                                            113.4
                                                     111.6
                                                             109.7
                                                                      107.9F-15
                                                         250 KTS
COMMENT 061021W0 OMEGA10.6 28 Dec 90 F-15
                                                                     59 F 70 PCT
COMMENT 061021W0 HIGH BYPASS FAN N061031A1 N061051A1 N061031A1
COMMENT 061021W0 TAKEOFF POWER
                                         85.00 % RPM
                          102.4
                                   100.5
                                             98.5
         106.1
                  104.3
                                                              94.2
                                                                       91.9F-15
          89.5
                   86.9
                            84.1
                                    81.1
                                             77.9
                                                      74.5
                                                              70.8
                                                                       66.9F-15
        061021
                           117.1
                                   115.3
                                            112.1
                                                     109.1
                                                             106.4
                                                                      103.8F-15
                                                              88.0
         101.3
                            96.5
                                    94.3
                                                     90.1
                                                                       85.9F-15
                                             92.2
          83.5
                   81.0
                            78.1
                                     74.8
                                             70.6
                                                      65.9
                                                              60.9
                                                                       55.6F-15
RUNWAY100000. 200000. 90000.
                                200000. 0.
COMMENT test departure with 45 degree turn
FLTTRK13000. 0.
                      2000.
                               45.
                                        290000. 0.
                                                                           TKOF9D1
COMMENT F-15 45 degree turn departure
TOROLL
TODSCR61
                          061001
                                                 061001 061011. 8000.
                                                                            061 DEP *
      061011. 20000.
                       061021. 305570.
                                                                             061 DEP
ALTUDE 061001
                       ٥.
                                ٥.
                                         8000.
                                                          20000. 2000.
                                                                            061 DEP *
      200000. 10000.
                                                                            061 DEP
AIRSPD 061001
                                         8000.
                                                 200.
                                                          20000. 250.
                                                                            061 DEP
      200000. 250.
                                                                            061 DEP
PLIGHT061.
               001.
                       50.
                                         5.
                                                                            061 DEP
CLEAR
                                                                           ALL
```

Figure 10a. Nmap 6.0 Sample Case Input File Part 1. (Header and Flyover Data.)

COMMENT *****		********	•		
COMMENT **	RUNUP DAT	A *	•		
COMMENT *****		********	•		
AL 06101	0 105.	5 103.5	99.1 94.8	91.6 88.7	1
COMMENT 06101W	OMEGA11.2 28	Dec 90 59	F 70 PCT 29.92	2 IN HG 74-004	-010 01
COMMENT 06101W	) F-15A AIR	CRAFT	ENG F100-PW-10	00(1) N061	.06A0
COMMENT 06101W	INTERMED PWR	(MIL)	90.00 % NC	930 C FTIT 785	0 LBS/HR
86.1	83.5 80.	9 78.5	76.1 73.7	71.3 68.8	2
66.1	63.4 60.		52.4 47.3	41.7 35.4	3
06101	20 107.	9 105.8	101.8 98.0	94.9 92.0	4
89.2	86.5 83.	8 81.3	78.8 76.3	73.8 71.3	5
68.6	65.7 62.		54.3 49.0	43.2 36.8	6
06101	40 103.		98.2 95.0	92.0 88.9	7
85.9	82.9 80.	0 77.3	74.6 71.9	69.3 66.6	8
63.7	60.6 57.	2 53.3	48.5 43.2	37.4 31.5	9
06101	80 107.	8 105.6	102.6 99.7	96.7 93.6	10
90.6	87.5 84.	4 81.7	78.9 76.1	73.3 70.6	11
67.5	64.3 60.	6 56.4	51.2 45.6	39.7 33.9	12
06101	90 106.	5 104.3	101.2 98.3	95.3 92.2	13
89.0	85.8 82.	6 79.7	76.8 73.9	71.0 68.2	14
65.1	61.9 58.	2 54.1	49.2 44.0	38.7 33.7	15
06101	120 116.	2 114.1	109.2 104.7	101.5 98.4	16
95.6	92.8 90.	1 87.5	85.0 82.5	80.1 77.6	17
75.0	72.3 69.	4 66.1	62.0 57.4	52.4 47.0	18
06101	130 124.	9 122.7	119.0 115.6	112.5 109.4	19
106.2	103.1 99.	9 97.1	94.2 91.4	88.7 86.0	20
83.1	80.0 76.	6 72.8	68.2 63.3	58.2 53.0	21
06101	140 125.	5 123.4	119.5 115.8	112.7 109.6	
106.5	103.5 100.	6 97.9	95.2 92.5	89.9 87.3 60.0 55.0	23
84.4	81.4 78.	1 74.4	70.0 65.1	60.0 55.0	24
06101	150 122.	9 120.8	116.3 112.1	109.0 105.9	25
103.0	100.2 97.	4 94.8	92.2 89.7	109.0 105.9 87.1 84.5 59.9 55.6	26
81.8	78 9 75	9 72 6	68 6 64 3	59.9 55.6	
06101		6 90.5		77.9 74.8	
71.9	69.2 66.	5 63.9	61.4 58.9 38.8 34.9	56.3 53.7	29
50.9	48.2 45.	4 42.3	38.8 34.9	31.1 27.3	
RNPPAD94000.	202000. 30.				PAD1
COMMENT F-15 of	n runup pad 1				
RUDSCR61.	90. 06101			1	RUN1 PAD1
RUNUP 61.	90. 10.	0. 1	60.	1	RUN1 PAD1
CLEAR					
CLEAR				;	ALL
AREA 85.	80. 75.	70.	55.		
END					

Figure 10b. NMAP 6.0 Sample Input File Part 2. (Runup Data.)

```
/* ARCHIVED */
/* INPUT FILE */
NMAP1807.BPS
/* CASE NAME */
P-15 Power runup and flight tests for NOISEMAP report
  12/28/90 ------ NOISEMAP 6.00 ----- PAGE 7
DNL.
                  F-15 Power runup and flight tests for NOISEMAP report
    SUMMARY OF AIRCRAFT FLIGHT OPERATIONS AT SPECIFIC GROUND LOCATION TEST
     X = 87999.0 \text{ FT} \quad Y = 202000.0
        RANK
     AIRCRAFT
     MISSION
   PLIGHT TRK
       POWER 90.00 4 RP
    AIRSPEED 200 KTS
    ALTITUDE
                648 FT
   SLANT DIST
              2105 FT
   ELEV ANGLE 17.95 DEG
               50.000
   EVENTS DAY
       NIGHT
                 5.000
EFCTV SEL 107.09 DB
     DNL 77.72 DB
  CUM DNL
             77.72 DB
                                                PLIGHT DNL
                                                              77.72 DB
                                                TOTAL DNL
                                                             77.74 DB
  12/28/90
             ----- NOISEMAP 6.00 ----- PAGE
DNL
                  F-15 Power runup and flight tests for NOISEMAP report
     SUMMARY OF AIRCRAFT RUNUP OPERATIONS AT SPECIFIC GROUND LOCATION TEST
     X = 87999.0 \text{ FT} \quad Y = 202000.0 \text{ FT}
        RANK
     AIRCRAFT
      THRUST
                    90
    RUNUP PAD PAD1
       POWER 90.00 & NC
   SLANT DIST 6001 PT
       ANGLE 120.0 DEG
   TIME DAY 600.0 SEC
       NIGHT 60.0 SEC
        AL
               73.05 DB
     DNL
              $4.47 DB
  CUM DNL
             54.47 DB
                                                RUNUP DNL
                                                              54.47 DB
                                                              77.74 DB
                                                TOTAL DNL
```

Figure 11. NMAP 6.0 Specific Point Calculation for a Sample Case. (Figure shows the major contributers both flyover and runup operations.)

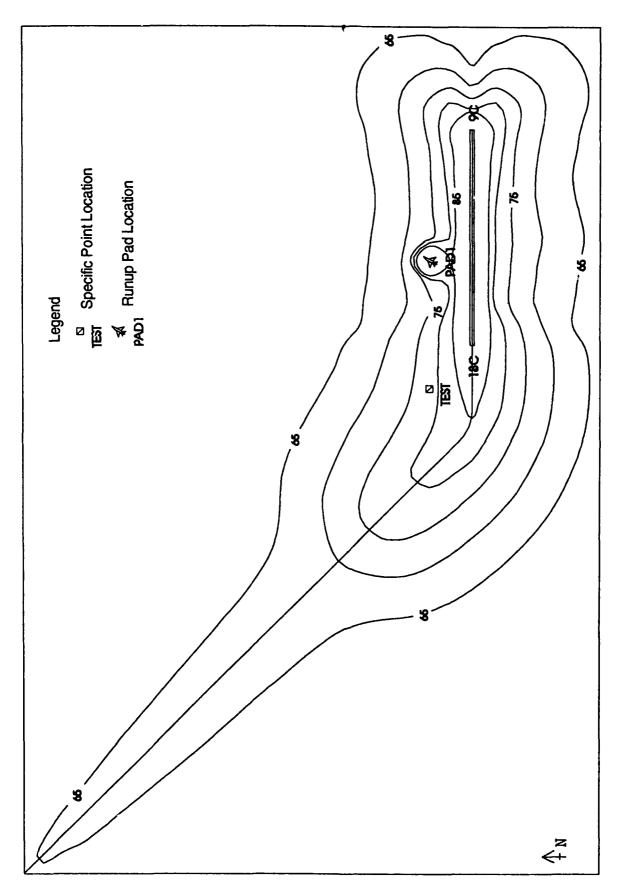


Figure 12. Plot from the NMPLOT 1.1 program of the sample case. (Plot has been modified for this report.)

Volume of ops - Flyover 100
Volume of ops - Runup - 20
Runup time (sec) - 60
Num of power segments - 35
Number of subflights:

(Internal grid coordinates = specified x-50000, specified y-150000) Subflight breakdown:

Flight Segment 1 - takeoff roll, 90% RPM, 200 kts.

bflights: 1 Points: 1:2

Ground coordinates (internal grid)

GTrack Attit

StartY stopY stopY

Heading

0.707107 Heading Altitude **GTrack** Flight Segment 2 - takeoff climb, 90% RPM, 200 kts. Ground coordinates (internal grid) stopX Points: 2:3, 3:4, 4:5 startY startX subflights: 3

Flight Segment 3 - continued climb, 85% RPM, 250 kts.

0.707107

subflights: 2 Points: 5:6, 6:7

Ground coordinates (internal grid)
GTrack Altitude
oflight# startX startY stopX stopY

A

Ver \*\*\* 31776.8 \*\*\* 64.424.8 \*\*\* 95.632.6 \*\*\* 181.704.0 \*\*\* straight 2,000.0 \*\*\*

Specific Point Location (internal grid coordinates)
SpX
SpY
37.999.0 52.000.0

-0.707107 0.7071068 -0.707107 0.7071068

Heading

Generalized Correction Factor

TTLIA dB (sum of flyover and runup exposures)

DNL Exposure at Specific Point=

Table 2. Segmentation of the Flight Parameters

Segment	-	8			က	
subflight	1:2	2:3	3:4	4:5	5:6	6:7
subfitLength	8000	5068.969	1570.79633	5504.094	180177.7	104570.8
Slant CPA	2000	2105.386	2385.885	2872.995	3209.727	10359.57
DominantSlantDist.	2000		****	2105.386		3209.727
Attitude	0	648.8109	833.333	1095.133	2000	10000
<b>ExposeIntgalCPA</b>	1.23981E-08	1.44296E-07	3.69319E-08	3.19116E-08	4.07886E-09	2.24289E-12
TransitionFactorR	0.2455066	0.9471701	0.9580592	0.9650072	0.9940802	-
<b>ExposeIntgalSeg</b>	0.0495925			0.944770456		0.04204493
Weighting	0.012175286			0.899164048		0.041796169
RefExpPowAir-Grn	61407140000	55941890000			2560318000	
in dB	107.88	107.48		***********	94.08	
TORollOffset	1.27076E-27					
TORoll Angle (deg)	9.462				0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	111111111111111111111111111111111111111
•						
SegExpPow	747649495.7		1 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	50300936252		107011483.1
SegExpdB	88.74			107.02		80.29
Overall ExpPow Overall ExpdB	51155597231 107.09					
DNL	77.72 dB	77.72 dB (see section 2.1.1 for formula)	.1 for formula)			
Formulas	Weighting = Seg. 1 Seg. 2 & 3	sum(ExposeIntegralCPA*TransitionFactor)*DominantSlantDist^2 (RefExpPow +TORollOffset)* Weighting RefExpPow *Weighting	sum(ExposeIntegralCPA*TransitionFactc (RefExpPow +TORollOffset)* Weighting RefExpPow "Weighting	ionFactor}*Dom feighting	iinantSlantDist^2	

Table 3. Summary of Flyover Exposure Calculations at the Specific Point

SpecificPoint Coordinate Ypad RunupPad Coordinates

Runup Duration

Transform from Grid Coordinate System to Runup Pad

XdSbac

StartDistance and RunupAngle in new reference

PpAngle RpStant RpAngle

D = 10Log(RpSlant) - 22, 1 <= D <= 22 Real and integer Number to Closest Ref. Table Element Number

D1 = Integer(D) + 1

Reference Exposure Power Data

Slant Distance

5000

RefAngle

RefAngle

Interpolating **60** 

Exposure at Specific Point Due to Runup Aircraft

Interpolate between Reference Angle and SlantDistance

Recuing Runup Exposure Ž

((AngLwr Lvl- AngUprLvl)\*(AngLwr-Angle)/(AngUpr-AngLwr) + AngLwrLvl) \* RunupDuration Interpolation Formulas - Distance= RefUpr - (RefLwr - RefUpr)\*(Uprindex - FractIndex)

Table 4. Summary of the Runup Exposure Calculations at the Specific Point

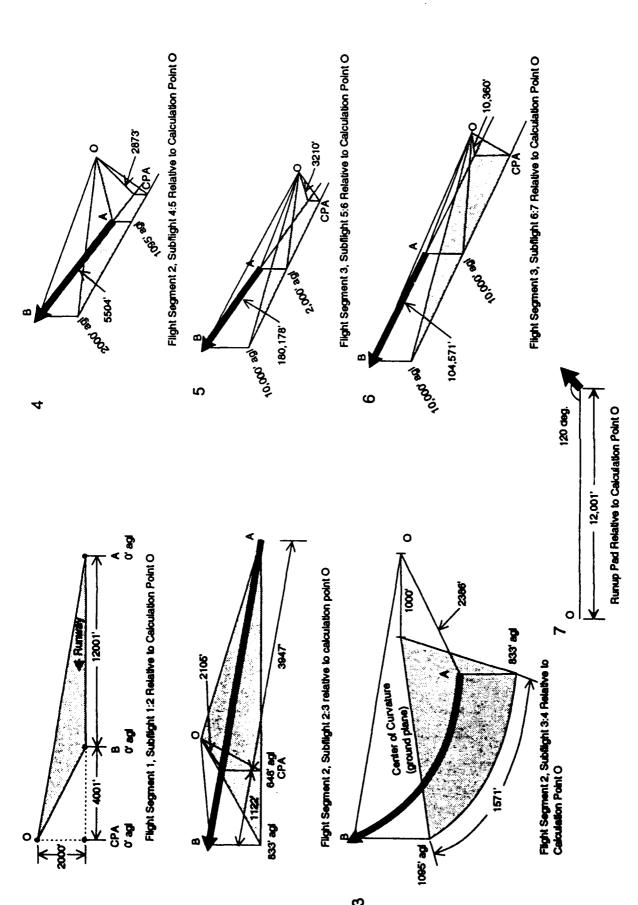


Figure 13. Sample Calculation Subflights 1-6 and Runup Pad.

# 3.1 Example Calculation in Detail

## 3.1.1 Flight Segment 1

 $AC = -12001' \qquad COA = -80.54^{\circ} \\ BC = -4001' \qquad COB = -63.44^{\circ} \\ SL = 4473' \qquad Elevation \ Angle = 0 \\ AB = AC - BC = -8000' \qquad F_a = 1.293828 \\ ALT_{CDa} = 0 \qquad F_b = 1.0$ 

The takeoff roll (TOROLL) calculation is divided into two parts. The first part calculates the noise exposure arising from the flight segment itself, while the second part calculates an offset to account for the ground runup and acceleration effects of takeoff. For the flight segment, NOISEMAP will use the ground-to-ground propagation SEL power values (0° elevation angle), since the altitude at the closest point of approach (CPA) is 0 ft AGL. NOISEMAP obtains a computed reference SEL power value,  $E_{rc}$ , by

$$E_{rc} = 10^{\frac{AiG}{10}} \cdot TFR$$

where TFR is a transition factor ratio and the AtG is the Air-to-Ground propagation value at the slant distance to the CPA. This equation adjusts the reference SEL power value for lateral attenuation by interpolating between the reference Air-to-Ground and Ground-to-Ground propagation SEL power values which are contained in NOISEFILE.

NOISEFILE provides the Air-to-Ground (L<sub>AG</sub>) and Ground-to-Ground (L<sub>GG</sub>) propagation reference values to interpolate to the calculated slant distance in the following manner:

$$L_{AG}$$
 (2000') = 107.9 dB  $L_{AG}$  (2500') = 105.7 dB  $L_{GG}$  (2000') = 101.8 dB  $L_{GG}$  (2500') = 99.7 dB

Using NOISEMAP's algorithm for interpolating the Transition Factor Ratio (TFR) and also noting that the value of the Transition Factor from the NOISEMAP lateral attenuation algorithm is 1.0, then TFR becomes:

TFR = 
$$\frac{L_{GG}(2500') - [L_{GG}(2000') - L_{GG}(2500')] \cdot D'}{L_{AG}(2500') - [L_{AG}(2000') - L_{AG}(2500')] \cdot D'}$$

where D' equals the fractional difference between the index of the upper limit of the interpolation (a number between 1 and 22 representing the one third octane increment) and the fractional index value of the distance being interpolated to. This is determined by:

In power terms the equation becomes:

TFR = 
$$\frac{9.332543E9 - (1.513561E10 - 9.332543E9) \cdot -0.9897}{3.715352E10 - (6.16595E10 - 3.715352E10) \cdot -0.9897}$$

NOISEMAP stores and calculates the noise values using the power value (not in decibels) and only converts to the dB value at the final grid printout. The TFR computed is:

$$TFR = 0.2455066$$

Next, NOISEMAP computes the Exposure Factor, C<sub>y</sub>, for this segment. In this step NOISEMAP also adds any noise level offsets with the following equation in the LINEX subroutine:

$$C_y = \left\{ I_c \cdot \frac{\sin(COA) - \sin(COB)}{2} \right\} + \left\{ \left[ \frac{(F_a - F_b) \cdot OC}{AC - BC} \right] \cdot \frac{\cos(COB) - \cos(COA)}{2} \right\}$$

where

$$I_{c} = \frac{AC \cdot FB - BC \cdot FA}{AC - BC}$$

AC and BC are the distances from the CPA and points A and B, respectively. When computing the sine and cosine functions, the angles COA and COB are defined as positive if the direction from the CPA to the point is the same as the aircraft heading and negative if opposite. F<sub>a</sub> and F<sub>b</sub> are correction factors that are applied at points A and B, respectively. Currently, an altitude correction, the delta six at the start of takeoff roll, airspeed adjustment and DSEL (a user input offset to the SEL) are used by NOISEMAP in the generalized correction factors (see Section 2.4.3). The Altitude correction is computed by the following equation:

Altitude correction = 
$$10[(1000\text{-ALT}) \cdot 10^{-5}]$$

where ALT is in feet.

It is important to note that this correction is set equal to 1.0 for altitudes less than 1000 ft.

Since the takeoff roll algorithm, TOROLL, is invoked, the correction for the start of takeoff roll, ( $\Delta_6$ ), is computed by:

$$\Delta_6 = 5 \log \left( \frac{S_{ref}}{S_{rotate}} \right)$$

where

 $S_{ref} = 4779 \text{ ft (length of the Boeing 707 reference aircraft takeoff roll)}$ 

S<sub>rotate</sub> = 8000 ft (the F-15 input takeoff roll)

$$\Delta_6 = 1.118765 \, dB \rightarrow Power_{\Delta 6} = 10^{10} = 1.293828$$

The takeoff roll correction at the point of rotation is 0, since the omega program computes a Noise Profile data set for the given liftoff speed.

The airspeed correction is based on the rotation speed. However, during takeoff roll, this correction is not applicable. There are now user-entered dB corrections.

C<sub>v</sub> can therefore be calculated as in the following steps:

 $F_a$  (dB) = Altitude correction at pt A + start of TOROLL  $\Delta_6$  + Speed Adjustment at pt A + DSEL at pt A

 $F_a(P) = 1.293828$ 

 $F_b$  (dB) = Altitude correction at pt B + end of TOROLL  $\Delta_6$  + Speed Adjustment at pt B + DSEL at pt B

 $F_b(P) = 1.000000$ 

$$C_{y} = \left\{ \left[ \frac{(-12001 \cdot 1 + 4001 \cdot 1.293828)}{(-12001 + 4001)} \right] \cdot \left[ \frac{(\sin (-80.5^{\circ}) \cdot \sin (-63.4^{\circ}))}{2} \right] \right\} + \left[ \frac{(F_{a} - F_{b}) \cdot 2000}{-8000} \cdot \frac{(\cos (-63.4^{\circ}) \cdot \cos (-80.5^{\circ}))}{2} \right]$$

$$C_v(P) = 0.049592$$

Therefore, the flight part of this segment noise exposure is:

$$E_{rc} \cdot |C_y| = L_{refAG} \cdot TFR \cdot |C_y| = 6.140714E10 \cdot 0.2455066 \cdot 0.049592 = 7.476419E8 (88.74 dB)$$

(Note that the reference air-to-ground power level has been interpolated by NMAP using the methodology shown for the TFR calculation.)

In the second part of the TOROLL calculation, NOISEMAP computes an adjustment to the noise exposure. This adjustment is added to the noise exposure computed above to obtain the total noise exposure for the takeoff roll segment. The Takeoff Roll Ground Runup noise level is

computed by adding the total directivity pattern offset to the ground-to-ground noise level from the start of takeoff roll to the calculation point. For segment 1 the slant distance to start of takeoff roll is 12167 ft and the ground-to-ground noise level from interpolating the NOISEFILE data is 81.04 dB. The angle to the calculation point is  $9.462^{\circ}$  and interpolating in table 1 (page 25) we get  $1 \times 10^{-35}$  for the adjustment. This leaves us with a value of  $1.27076 \times 10^{-27}$  value for the TOROLL adjustment. This essentially adds no correction for the runup portion of the takeoff roll.

The total noise exposure for this segment is essentially equal to the flight segment exposure plus the TOROLL adjustment, that is:

Flight Segment 1 Noise Exposure = 
$$10 \log\{(E_{ref} + E_{TOROLL}) \cdot (TFR \cdot |C_y|)\}$$
  
=  $10 \log\{(6.140714E10 + 1.27076E-27) \cdot 0.012175286\} = 88.74 dB$ 

## 3.1.2 Flight Segment 2

## Subflight 2:3

The second segment is divided further into three subflights. The first subflight 2:3 is the initial liftoff segment. The aircraft starts at 200 kts and 0 ft AGL and climbs to 833 ft AGL at a climb angle of 9.46°. The geometry of this subflight relative to the calculation point is given in Figure 13-2.

The following data are needed for the calculation:

AC = -3947	COA	=	-61.90°
BC = 1122'	COB	=	28.16°
SL = 2105'	Elevation Angle	=	17.93°
The altitude at CPA = 648'	TF	=	0.0702217
The slant distance to CPA $(OC) = 2105$ '	TFR	=	.94717
Flight Segment length (AB) = AC-BC = -5069'	Fa	=	1.0000
	Fb	=	0.9166667
$L_{AG}(2105) = 55,941,890,000 = 107.48 \text{ dB}$	•		
$L_{CC}(2105) = 13.855,120,000 = 101.45 dB$			

The Exposure Factor,  $C_v$ , for the 2:3 subflight is evaluated as before:

$$C_y = -0.6395776$$

From this Cy a normalized value for this subflight is determined by:

$$C_{ycpa} = \frac{|C_y|}{SL^2}$$

$$= \frac{0.639576}{(2105)^2}$$

$$= 1.44341E-7$$

# Subflight 3:4

The second subflight of segment 2 is a climbing turn with a 2000 ft ground plane radius. The aircraft is still climbing at the 9.46° climb angle starting at 833 ft AGL and ending at 1,095 ft AGL after completing the 45° right hand turn. The geometry of subflight 3:4 relative to the calculation point is shown in Figure 13-3.

The following data are needed for this calculation:

Subflight Length	=	1,593 ft
Climb∠	=	9.462°
AtG(2386)	=	69,882,142,782 = 108.4
G(C2386)	=	17,411,793,902 = 102.4
Elevation∠	=	20.43
TF	=	0.055937
TFR	=	0.9580593
Fa	=	0.9166667
Fb	=	0.886594

The Exposure Factor for subflight 3:4 is calculated by the following equation in the TURNEX subroutine:

$$C_y = R \cdot SL^2(\frac{Sec8}{dca}) \{ F_a \{ \frac{2C_20 + C_1}{dcn} - \frac{C_1}{\sqrt{C_0}} \} + [\frac{F_a - F_b}{\theta}] [\frac{C_1\theta + 2C_0}{dcn} - 2\sqrt{C0}] \}$$

where

$$\begin{array}{lll} SL = 2386' & Symm = -1 \\ R = 2000' & dcn = 3004.62885 \\ \theta = -0.785398 & dct = -2.97842E13 \\ X_0 = 0 & Scc \beta = 1.013794 \\ Y_0 = 1000 \\ Z_a = 833.33' & \\ Z_b = 1095' & D_b - D_a = 1570.7963 \end{array}$$

 $tan\beta = 0.166667$ 

$$C_0 = X_0^2 + Y_0^2 + Z_a^2 + R^2 - 2RX_0 = 5,692,440$$

$$C_1 = -2RY_0 + 2R \left[ \frac{Z_b - Z_a}{D_b - D_a} \right] Z_a (Symm) = -4,551,560$$

$$C_2 = R^2 \left( \frac{Z_b - Z_a}{D_b - D_a} \right)^2 + 2R \left( 0.47483 \cdot X_0 + Symm \left( .1269 Y_0 \right) \right) = -395,578$$

Thus, Cy is:

$$C_y = 3.88186E-4 [599.5194 \cdot F_a - 265.3916 (F_a-F_b)]$$
  
= 3.88186E-4 [334.1278 \cdot F\_a + 265.3916 \cdot F\_b]  
= 0.2102330

Normalized exposure factor at CPA for subflight 3:4, Cycpa = 3.69319E-8

# Subflight 4:5

This subflight of the second flight segment is a straight climb that occurs after the 45° right hand turn. The aircraft starts at 1095 ft AGL and reaches 2000 ft AGL. This subflight geometry is shown in Figure 13-4.

The following data are needed for this portion of the calculation:

AC	=	876.8268	COA	=	16.91°
BC	=	6380.921	COB	=	65.76°
			Elevation Angle	=	22.41°
Alt at CPA	=	1095.133	TF	=	0.046886
Slant at CPA	=	2872.995	TFR	=	0.9650072
AB	=	-5504 ft	Fa	=	0.886594
			F <sub>b</sub>	=	0.7639441
L <sub>AG</sub> (2873)	=	104.6 dB			
$L_{GG}(2873)$	=	98.6 dB			

Using the methodology for subflights 1:2 and 2:3, the normalized exposure factor for this subflight is:

$$C_y = -0.263393$$
  
 $C_{ycpa} = 3.191056E-8$ 

NOISEMAP now adds the three subflights together to get the noise exposure value for the second segment by using the following summation:

Noise exposure segment 2 =
$$L_{AGref} \cdot \left(\sum_{i=1}^{n_{subf}} C_{y} \text{kpa}_{i} \cdot \text{TFR}_{i}\right) \cdot (\text{SL}_{DOM})^{2}$$

$$= 55,942,000,000 \cdot (1.44341E-7 \times 0.9471701 + 3.69319E-8 \times 0.9580593 + 3.191056E-8 \times 0.9650072) \cdot (2105.98332)^{2}$$

$$= 50,300,936,352$$

$$= 107.02 \text{ dB}$$

It should be noted that the  $L_{AGref}$  is the reference air-to-ground noise exposure of the dominant subflight. The dominant subflight is determined by the largest  $C_{ycpa}$  term, which in this case occurs at subflight 2:3. The  $L_{AGref}$  is then determined from the slant distance to the CPA of this subflight.

# 3.1.3 Flight Segment 3

This section describes the third flight segment which is the final climb of this flight profile.

## Subflight 5:6

This segment includes a power cutback to 85 percent RPM and a speed increase to 250 kts for the F-15. The geometry of Subflight 5:6 relative to the calculation point is shown in Figure 13-5.

AC = 6218.352	AB =	180,177		
BC = 186396.0	Slant CPA =	3209.727		
$F_a = 0.7639441$	COA =	62.6815°	TF	= 0.0078536
$F_b = 0.5285548$	COB =	88.6840°	TFR	= 0.9940802
	ALT at CPA =	2000'	Elev ∠	$= \sin -1 \left( \frac{ALT_{cp2}}{OA} \right) = 38.5^{\circ}$
	L <sub>AG</sub> (	(3210) = 2.560317E9		
	L <sub>GG</sub> (	(3210) = 6.153103E8		

From previous methods, the noise Exposure Factor for subflight 5:6 is

$$C_y = 0.042032765$$
  
 $C_{ycpa} = 4.07992E-9$ 

## Subflight 6:7

This last subflight of this segment has the aircraft leveling off at 10,000 ft AGL. The geometry in Figure 13-6 relates this subflight track to the calculation point.

The following values are needed in this calculation:

AC = 186135.6	Slant CPA = $10,359.57$	
BC = 290706.4	$COA = 86.814^{\circ}$	TF = 0
$F_a = 0.5285548$	$COB = 87.959^{\circ}$	TFR = 1.0
$F_b = 0.5285348$	ALT at CPA = $10,000$ ft	Elevation $\angle = 74.9^{\circ}$

The noise Exposure Factor for this subflight is:

$$C_y = 0.00024128$$
  
 $C_{ycpa} = 2.24822E-12$ 

NOISEMAP now adds these two subflights together to get the noise exposure value for the third flight segment.

Noise Exposure for Segment 3 = 
$$L_{AGref} \cdot \left( \sum_{i=1}^{n_{subf}} C_{y} kpa_{i} \cdot TFR_{i} \right) \cdot (SL_{DOM})^{2}$$
= 2560318000 \cdot (4.07886E-9 \cdot 0.9940802 + 2.24289E-12 \cdot 1.0) \cdot (3209.727)^{2}
= 107011483
= 80.29 dB

# 3.1.4 Overall Flight Exposure

NOISEMAP computes the total noise exposure from the flight profile by summing the calculated exposure power values of each segment:

The total flyover noise exposure can now be computed by:

Flight Noise Exposure = SEL + 
$$10 \log (N_{day} + 10 N_{night}) - 49.4$$
  
=  $5.115597E10 \cdot 100 / 86,400 = 5.920829E7 = 77.72 dB$ 

#### 3.1.5 Runup Contribution

Figure 13-7 shows the geometry for the runup calculation.

NOISEMAP interpolates from the input runup data set to get the A-weighted sound level at the observer point. At a 120° propagation angle, a runup value can be interpolated from the reference power values in the following manner (see Table 4):

A-Level at 1,000' = 75.0 dB = 31,622,779A-Level at 12,500' = 72.3 dB = 16,982,437A-Level at 12,000' = 73.1 dB = 20,170,528Value = 19,904,649

The runup noise exposure is computed by:

Runup Noise Exposure =  $AL + 10log (Dur_{day} + 10Dur_{night}) - 49.4$ =  $(19,904,649 \cdot (600+10(60))/86,400$ = 276,453in DNL = 54,42 dB

# 3.1.6 Final Specific Point DNL Calculation

The final Noise Exposure for the calculation point is computed by adding the DNL contribution of the flyover and the ground runup operations.

Flyover Noise Exposure = 59,208,290 or DNL = 77.72 dB Runup Noise Exposure = 280146 or DNL = 54.47 dB Total Noise Exposure = 59,414,743 or DNL = 77.74 dB

# 3.2 Flight Checks

The following are a list of flight procedures which NMAP 6.1 checks to insure that the flight conditions are valid. Most of these checks are redundant if the NMI file is created by the MCM.

- (1) Aircraft airborne at end of runway.
- (2) Aircraft is airborne before starting a turn.
- (3) Aircraft not descending below airfield elevation on a touch-and-go.
- (4) Aircraft landing glide slope is  $0.5 < \text{slope} \le 10.0$  degrees.
- (5) Aircraft altitude ascends above 301.0 feet in takeoffs and touch-and-go's.

- (6) The aircraft subflight end distance is greater than the beginning distance (i.e., aircraft not reversing on a subflight segment).
- (7) Aircraft continues to ascend after a touch-and-go and not fall below 301.0 feet altitude within 100 feet from brake release point.

Reference 4 has a complete listing of the error messages from the NMAP 6.1 and MCM programs.

# 3.3 Aircraft Noise Reference Database

The following tables contain the complete list of aircraft in the NOISEFILE 6.2 database. Table 5 shows all of the flyover aircraft reference noise data, Table 6 shows the runup data and Table 7 shows the civilian aircraft data.

Table 5. NOISEFILE 6.2 Flyover Reference Noise Database

PAGE 2	DATE OF OMEGA 6 RUN 27 DEC 79 27 DEC 79 27 DEC 79 27 DEC 79 27 DEC 79	19 DEC 79 19 DEC 79 19 DEC 79	19 DEC 79 19 DEC 79 19 DEC 79	27 DEC 79 27 DEC 79 27 DEC 79 27 DEC 79	30 MAR 88 30 MAR 88 30 MAR 88 30 MAR 88	27 DEC 79 27 DEC 79 27 DEC 79	27 DEC 79 27 DEC 79 27 DEC 79 27 DEC 79	28 FEB 83 28 FEB 83 28 FEB 83 28 FEB 83	24 JUN 87 24 JUN 87 24 JUN 87 24 JUN 87 24 JUN 87 24 JUN 87	18 AUG 88 18 AUG 88 10 FEB 89 18 AUG 88
	DRAG CONFIGURATION NO DRAG NO DRAG FLAPS DN, GEAR UP NO DRAG NO DRAG	FLAPS UP, GEAR DOWN NO DRAG FLAPS 17DEG, GEAR UP	SPEED BRAKE ON NO DRAG NO DRAG	NO DRAG NO DRAG NO DRAG EST. F-101 -3.2DB	SPEED BRAKE OUT SPEED BRAKE OUT FLAPS DOWN, GEAR DOWN TRAFFIC PAITERN	NO DRAG NO DRAG APP. DRAG CONFIGURATION	SPEED BRAKE ON SPEED BRAKE ON NO DRAG FLAPS 60%, GEAR DN	GEAR AND FLAPS DOWN NO DRAG NO DRAG NO DRAG	NO DRAG NO DRAG GEAR AND FLAPS DOWN NO DRAG NO DRAG MIL	GEAR AND FLAPS UP GEAR AND FLAPS UP APPROACH GEAR AND FLAPS UP
07 MAY 91	SLANT AIR RANGE SPEED 1000 FT 250 KTS 1000 FT 140 KTS 1000 FT 140 KTS 1000 FT 150 KTS	1000 FT 140 KTS 1000 FT 180 KTS 1000 FT 120 KTS	1000 FT 200 KTS 1000 FT 300 KTS 1000 FT 125 KTS	1000 FT 300 KTS 1000 FT 299 KTS 1000 FT 370 KTS 1000 FT 200 KTS	1000 FT 300 KTS 1000 FT 299 KTS 1000 FT 190 KTS 1000 FT 200 KTS	1000 FT 180 KTS 1000 FT 250 KTS 1000 FT 115 KTS	1000 FT 300 KTS 1000 FT 299 KTS 1000 FT 301 KTS 1000 FT 170 KTS	1000 FT 150 KTS 1000 FT 350 KTS 1000 FT 300 KTS 1000 FT 160 KTS	1000 FT 350 KTS 1000 FT 350 KTS 1000 FT 130 KTS 1000 FT 200 KTS 1000 FT 200 KTS	1000 FT 275 KTS 1000 FT 360 KTS 1000 FT 165 KTS 1000 FT 270 KTS
	AIRCRAFT NAME C-141A C-141A C-141A C-141A	C-131B C-131B C-131B	T-33A T-33A T-33A	F-100D F-100D F-100D F-100D	F-4C F-4C F-4C	T-39A T-39A T-39A	T-38A T-38A T-38A T-38A	A-10A A-10A A-10A A-10A	7 7 7 7 7 7 7 7 7 7 7 7 7 7 7 7 7 7 7	8-1 8-1 1-1
	_ 6								•	•
	OPERATION POWER DESCRIPTION TAKEOFF POWER CRUISE POWER APPROACH POWER INTERMEDIATE POWER	TAKEOFF POWER CRUISE POWER APPROACH POWER	TAKEOFF POWER CRUISE POWER APPROACH POWER	AFTERBURNER POWER TAKEOFF POWER CRUISE POWER APPROACH POWER	AFTERBURNER POWER TAKEOFF POWER APPROACH POWER TRAFFIC PATTERN	TAKEOFF POWER CRUISE POWER APPROACH POWER	AFTERBURNER POWER TAKEOFF POWER CRUISE POWER APPROACH POWER	APPROACH POWER MAX RATED THRUST NORMAL RATED THRUST TRAFFIC PATTERN	AFTERBURNER POWER TAKEOFF POWER APPROACH POWER INTERMEDIATE POWER TRAFFIC PATTERN INTERMED POWER INTERMED	AFTERBURNER POWER CRUISE POWER APPROACH POWER INTERMED POWER (MIL)
EFILE 6.1	VALUELUNITS OPERATION POW SECOND DESCRIPTION 1.90 EPR TAKEOFF POWER 1.52 EPR CRUISE POWER 1.20 EPR APPROACH POWE 1.20 EPR INTERMEDIATE 1.72 EPR NORMAL RATED	2800 RPM TAKEOFF POWER 2000 RPM CRUISE POWER 2400 RPM APPROACH POWER	TAKEOFF POWER CRUISE POWER APPROACH POWER	2.05 EPR AFTERBURNER POWER 2.0 EPR TAKEOFF POWER 1.75 EPR CRUISE POWER 1.38 EPR APPROACH POWER	AFTERBURNER POWER TAKEOFF POWER APPROACH POWER TRAFFIC PATTERN	1.94 EPR TAKEOFF POWER 1.66 EPR CRUISE POWER 1.37 EPR APPROACH POWER	AFTERBURNER POWER TAKEOFF POWER CRUISE POWER APPROACH POWER	638 C TIT APPROACH POWER 826 C TIT MAX RATED THRUST 756 C TIT NORMAL RATED THRUST 646 C TIT TRAFFIC PATTERN	900 C TIT AFTERBURNER POWER 900 C TIT TAKEOFF POWER 650 C TIT APPROACH POWER 750 C TIT INTERMEDIATE POWER 530 C TIT TRAFFIC PATTERN 960 C TIT INTERMED POWER	3
DATA IN NOISEFILE 6.	SETTING VALUE&UNITS OPERATION POM RST SECOND DESCRIPTION # RPM 1.90 EPR TAKEOFF POWER # RPM 1.52 EPR CRUISE POWER # RPM 1.20 EPR APPROACH POWE # RPM 1.20 EPR INTERMEDIATE # RPM 1.72 EPR NORMAL RATED	800 RPM 000 RPM 400 RPM	100 % RPM TAKEOFF POWER 90 % RPM CRUISE POWER 80 % RPM APPROACH POWER	.05 EPR 2.0 EPR .75 EPR .38 EPR	100 % RPM AFTERBURNER POWER 100 % RPM TAKEOFF POWER 87 % RPM APPROACH POWER 86.5 % RPM TRAFFIC PATTERN	.94 EPR .66 EPR .37 EPR	100 % RPM AFTERBURNER FOWER 100 % RPM TAKEOFF POWER 90 % RPM CRUISE POWER 91 % RPM APPROACH POWER	8 C TIT 6 C TIT 6 C TIT 6 C TIT	00 C TIT AFTERBURNER POWER 00 C TIT TAKEOFF POWER 50 C TIT APPROACH POWER 50 C TIT INTERMEDIATE PO C TIT TRAFFIC PATTERN 60 C TIT INTERMED POWER	C EGT AFTERBURNER POW C EGT CRUISE POWER C EGT APPROACH POWER C EGT INTERMED POWER
DATA IN NOISEFILE 6.	POWER SETTING VALUE£UNITS         OPERATION POW           OPC         FIRST         SECOND         DESCRIFTION           03         96 % RPM         1.90 EPR         TAKEOFF POWER           04         85 % RPM         1.52 EPR         CRUISE POWER           05         68 % RPM         1.20 EPR         APPROACH POWER           16         68 % RPM         1.20 EPR         INTERMEDIATE           12         91 % RPM         1.72 EPR         NORMAL RATED	0 IN HG 2800 RPM 2 IN HG 2000 RPM 7 IN HG 2400 RPM	00 % RPM 90 % RPM 80 % RPM	01 95 % RPM 2.05 EPR 03 94.5 % RPM 2.0 EPR 04 92.3 % RPM 1.75 EPR 05 89 % RPM 1.38 EPR	01 100 % RPM 03 100 % RPM 05 87 % RPM 13 86.5 % RPM	03 100 % RPM 1.94 EPR 04 89 % RPM 1.66 EPR 05 79.5 % RPM 1.37 EPR	00 % RPM 00 % RPM 90 % RPM 91 % RPM	05 5225 NF 638 C TIT 11 6700 NF 826 C TIT 12 6200 NF 756 C TIT 13 5325 NF 646 C TIT	90 % RPM 900 C TIT AFTERBURNER POWER 82 % RPM 650 C TIT APPROACH POWER 85 % RPM 750 C TIT INTERMEDIATE PO 75 % RPM 530 C TIT TRAFFIC PATTERN 2.0 % RPM 960 C TIT INTERMED POWER	7.5 % RPW 874 C EGT AFTERBURNER POW 9.9 % RPW 611 C EGT CRUISE POWER 90 % RPW 600 C EGT APPROACH POWER 8.5 % RPW 877 C EGT INTERMED POWER
IN NOISEFILE 6.	POWER SETTING VALUE&UNITS OPERATION POWERS SECOND DESCRIPTION 1.90 EPR TAKEOFF POWER 1.52 EPR CRUISE POWER 1.20 EPR APPROACH POWER 1.20 EPR INTERMEDIATE 2 91 % RPM 1.72 EPR NORMAL RATED	3 60 IN HG 2800 RPM 4 32 IN HG 2000 RPM 5 27 IN HG 2400 RPM	3 100 % RPM 4 90 % RPM 5 80 % RPM	1 95 % RPM 2.05 EPR 3 94.5 % RPM 2.0 EPR 4 92.3 % RPM 1.75 EPR 5 89 % RPM 1.38 EPR	1 100 % RPM 3 100 % RPM 5 87 % RPM 3 86.5 % RPM	3 100 % RPM 1.94 EPR 4 89 % RPM 1.66 EPR 5 79.5 % RPM 1.37 EPR	1 100 % RPM 3 100 % RPM 4 90 % RPM 5 91 % RPM	5 5225 NF 638 C TIT 1 6700 NF 826 C TIT 2 6200 NF 756 C TIT 3 5325 NF 646 C TIT	90 % RPM 900 C TIT AFTERBURNER POWER 82 % RPM 650 C TIT APPROACH POWER 85 % RPM 750 C TIT APPROACH POWER 75 % RPM 530 C TIT TRAFFIC PATTERN 92.0 % RPM 960 C TIT INTERMED POWER	1 97.5 % RPM 874 C EGT AFTERBURNER POW 4 89.9 % RPM 611 C EGT CRUISE POWER 5 90 % RPM 600 C EGT APPROACH POWER 4 98.5 % RPM 877 C EGT INTERNED POWER

Table 5. NOISEFILE 6.2 Flyover Reference Noise Database Cont'd

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	DRAG CONFIGURATION 10% FLAPS, GEAR DOWN 40% FLAPS, GEAR DOWN NO DRAG	NO DRAG NO DRAG APP. DRAG CONFIGURATION NO DRAG	SPEED BRAKE ON GEAR DOWN GEAR DOWN NO DRAG	GEAR AND FLAPS DOWN GEAR AND FLAPS DOWN GEAR AND FLAPS DOWN NO DRAG	GEAR AND FLAPS DOWN GEAR AND FLAPS DOWN APPROACH	FLAPS 55, GEAR UP FLAPS 33, GEAR DOWN FLAPS 55, GEAR UP FLAPS 33, GEAR DOWN	GEAR DOWN FLAPS 20, GEAR DOWN NO DRAG	GEAR AND FLAPS DOWN GEAR AND FLAPS DOWN NO DRAG	TAKEOFF CRUISE APPROACH(NO INLET SUPPRS)	TAKEOFF POWER APPROACH INTERMEDIATE FLT IDLE-250 KNOTS	APPROACH INTERMEDIATE MAX THRUST TRAFFIC PATTERN
	AIR SPEED 70 KTS 00 KTS 80 KTS	KTS KTS KTS KTS	KTS KTS KTS KTS	KTS KTS KTS	KTS KTS KTS	KTS KTS KTS	KTS KTS KTS	KTS KTS KTS	KTS KTS KTS	KTS KTS KTS	KTS KTS KTS KTS
	SP 170 100 180	350 300 210 290	350 350 300	350 300 150 350	250 240 160	190 125 230 130	150	200 140 250	300 250 140	300 140 225 250	150 240 300 225
Y 91	SLANT RANGE 1000 FT 1000 FT	1111	1111	0000 FFFF	000 FFF	000 FT 000 FT 000 FT	555 FFF	555	600 FFF	0000	1111
07 MAY	1001 10001	1000 1000 1000 1000	1000 1000 1000	1000 1000 1000	1000 1000 1000	1000 1000 1000	1000 1000 1000	1000 1000 1000	1000 1000 1000	1000 1000 1000 1000	1000 1000 1000 1000
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	OPERATION POWER DESCRIPTION TAKEOFF POWER APPROACH POWER INTERMEDIATE POWER	AFTERBURNER POWER TAKEOFF POWER APPROACH POWER INTERMEDIATE POWER	AFTERBURNER POWER TAKEOFF POWER APPROACH POWER INTERMEDIATE POWER	AFTERBURNER POWER TAKEOFF POWER APPROACH POWER INTERMEDIATE POWER	AFTERBURNER POWER TAKEOFF POWER APPROACH POWER	TAKEOFF POWER APPROACH POWER TAKEOFF WITH JETS APPROACH WITH JETS	TAKEOFF POWER APPROACH POWER INTERMEDIATE POWER	TAKEOFF POWER APPROACH POWER INTERMEDIATE POWER	TAKEOFF POWER CRUISE POWER APPROACH POWER	TAKEOFF POWER APPROACH POWER INTERMEDIATE POWER FLT IDLE-250 KNOTS	APPROACH POWER INTERMEDIATE POWER MAX RATED THRUST TRAFFIC PATTERN
	OPERATION POWER DESCRIPTION TAKEOFF POWER APPROACH POWER INTERMEDIATE POWER	WER OWER	AFTERBURNER POWER TAKEOFF POWER APPROACH POWER INTERMEDIATE POWER	æ		TAKEOFF POWER APPROACH POWER TAKEOFF WITH JETS APPROACH WITH JETS	R POWER	OWER	TAKEOFF POWER CRUISE POWER APPROACH POWER	TAKEOFF POWFR APPROACH POWER INTERMEDIATE POWER FLT IDLE-250 KNOTS	APPROACH FOWER INTERMEDIATE POWER MAX RATED THRUST TRAFFIC PAITERN
២ 6.1	OPERATION POWER DESCRIPTION TAKEOFF POWER APPROACH POWER INTERMEDIATE POWER	WER OWER	5 EPR AFTERBURNER POWER 3 EPR TAKEOFF POWER 7 EPR APPROACH POWER 4 EPR INTERMEDIATE POWER	æ		RPM TAKEOFF POWER RPM APPROACH POWER RPM TAKEOFF WITH JETS RPM APPROACH WITH JETS	R POWER	OWER	7 % RPM TAKEOFF POWER 0 % RPM CRUISE POWER 3 % RPM APPROACH POWER	7 C EGT TAKEOFF POWER 7 C EGT APPROACH POWER 9 C EGT INTERMEDIATE POWER 6 C EGT FLT IDLE-250 KNOTS	C EGT APPROACH POWER C EGT INTERMEDIATE POWER C EGT MAX RATED THRUST C EGT TRAFFIC PATTERN
TLE 6	ALUE&UNITS OPERATION POWER SECOND DESCRIPTION TAKEOFF POWER APPROACH POWER INTERNEDIATE POWER	WER OWER	EPR AFTERBURNER POWER EPR TAKEOFF POWER EPR APPROACH POWER EPR INTERMEDIATE POWER	æ		TAKEOFF POWER APPROACH POWER TAKEOFF WITH JETS APPROACH WITH JETS	R POWER	OWER	4 RPM TAKEOFF POWER 4 RPM CRUISE POWER 4 RPM APPROACH POWER	C EGT TAKEOFF POWTR C EGT APPROACH POWER C EGT INTERMEDIATE POWER C EGT FLT IDLE-250 KNOTS	EGT APPROACH POWER EGT INTERMEDIATE POWER EGT MAX RATED THRUST EGT TRAFFIC PATTERN
TLE 6	ALUE&UNITS OPERATION POWER SECOND DESCRIPTION TAKEOFF POWER APPROACH POWER INTERNEDIATE POWER	AFTERBURNER POWER TAKEOFF POWER APPROACH POWER INTERMEDIATE POWER	2.45 EPR AFTERBURNER POWER 2.3 EPR TAKEOFF POWER 1.7 EPR APPROACH POWER 1.4 EPR INTERMEDIATE POWER	AFTERBURNER POWER TAKEOFF POWER APPROACH POWER INTERMEDIATE POWER	AFTERBURNER POWER TAKEOFF POWER APPROACH POWER	HG 2700 RPM TAKEOFF POWER HG 2350 RPM APPROACH POWER HG 2700 RPM TAKEOFF WITH JETS HG 2350 RPM APPROACH WITH JETS	TAKEOFF POWER APPROACH POWER INTERMEDIATE POWER	TAKEOFF POWER APPROACH POWER INTERMEDIATE POWER	107.7 % RPM TAKEOFF POWER 75.0 % RPM CRUISE POWER 82.3 % RPM APPROACH POWER	817 C EGT TAREOFF POWER 617 C EGT APPROACH POWER 679 C EGT INTERMEDIATE POWER 546 C EGT FLT IDLE-250 KNOTS	C EGT APPROACH POWER C EGT INTERMEDIATE POWER C EGT MAX RATED THRUST C EGT TRAFFIC PATTERN
TLE 6	ALUE&UNITS OPERATION POWER SECOND DESCRIPTION TAKEOFF POWER APPROACH POWER INTERNEDIATE POWER	% RPMAFTERBURNER POWER% RPMTAKEOFF POWER% RPMAPPROACH POWER% RPMINTERMEDIATE POWER	9 RPM 2.45 EPR AFTERBURNER POWER 9 RPM 2.3 EPR TAKEOFF POWER 8 RPM 1.7 EPR APPROACH POWER 9 RPM 1.4 EPR INTERMEDIATE POWER	% RPMAFTERBURNER POWER% RPMTAKEOFF POWER% RPMAPPROACH POWER% RPMINTERMEDIATE POWER	9 RPM AFTERBURNER POWER 9 RPM TAKEOFF POWER 9 RPM APPROACH POWER	9 IN HG 2700 RPM TAKEOFF POWER 5 IN HG 2350 RPM APPROACH POWER 9 IN HG 2700 RPM TAKEOFF WITH JETS 5 IN HG 2350 RPM APPROACH WITH JETS	\$ RPM TAKEOFF POWER \$ RPM APPROACH POWER \$ RPM INTERMEDIATE POWER	7 EPR TAKEOFF POWER 6 EPR APPROACH POWER 1 EPR INTERMEDIATE POWER	4 EPR 107.7 & RPM TAKEOFF POWER 2 EPR 75.0 & RPM CRUISE POWER 6 EPR 82.3 & RPM APPROACH POWER	0 % RPM 817 C EGT TAKEOFF POWER 4 % RPM 617 C EGT APPROACH POWER 0 % RPM 679 C EGT INTERMEDIATE POWER 0 % RPM 546 C EGT FLT IDLE-250 KNOTS	5 % N1 567 C EGT APPROACH POWER 3 % N1 670 C EGT INTERMEDIATE POWER 6 % N1 767 C EGT MAX RATED THRUST 5 % N1 580 C EGT TRAFFIC PATTERN
DATA IN NOISEFILE 6	OPERATION POWER DESCRIPTION TAKEOFF POWER APPROACH POWER INTERMEDIATE POWER	RPM AFTERBURNER POWER RPM TAKEOFF POWER RPM APPROACH POWER RPM INTERMEDIATE POWER	RPM 2.45 EPR AFTERBURNER POWER RPM 2.3 EPR TAKEOFF POWER RPM 1.7 EPR APPROACH POWER RPM 1.4 EPR INTERMEDIATE POWER	RPM AFTERBURNER POWER RPM TAKEOFF POWER RPM APPROACH POWER RPM INTERMEDIATE POWER	RPM AFTERBURNER POWER RPM TAKEOFF POWER RPM APPROACH POWER	IN HG 2700 RPM TAKEOFF POWER IN HG 2350 RPM APPROACH POWER IN HG 2700 RPM TAKEOFF WITH JETS IN HG 2350 RPM APPROACH WITH JETS	RPM TAKEOFF POWER RPM APPROACH POWER RPM INTERMEDIATE POWER	EPR TAKEOFF POWER APPROACH POWER EPR INTERMEDIATE POWER	EPR 107.7 % RPM TAKEOFF POWER EPR 75.0 % RPM CRUISE POWER EPR 82.3 % RPM APPROACH POWER	<pre>% RPM 817 C EGT TAKEOFF POWFR % RPM 617 C EGT APPROACH POWER % RPM 679 C EGT INTERMEDIATE POWER % RPM 546 C EGT FLT IDLE-250 KNOTS</pre>	<ul> <li>4 N1</li> <li>567 C EGT</li> <li>A PPROACH POWER</li> <li>8 N1</li> <li>670 C EGT</li> <li>INTERMEDIATE POWER</li> <li>8 N1</li> <li>767 C EGT</li> <li>MAX RATED THRUST</li> <li>8 N1</li> <li>580 C EGT</li> <li>TRAFFIC PATTERN</li> </ul>
DATA IN NOISEFILE 6	POWER SETTING VALUE OPERATION POWER OPC FIRST SECOND DESCRIPTION O3 45 IN HG TAKEOFF POWER O5 24 IN HG APPROACH POWER O6 30 IN HG INTERMEDIATE POWER	102 % RPM AFTERBURNER POWER 102 % RPM TAKEOFF POWER 96.5 % RPM APPROACH POWER 93 % RPM INTERMEDIATE POWER	01 108 % RPM 2.45 EPR AFTERBURNER POWER 03 106 % RPM 2.3 EPR TAKEOFF POWER 05 93 % RPM 1.7 EPR APPROACH POWER 06 86.5 % RPM 1.4 EPR INTERMEDIATE POWER	01         97 % RPM         AFTERBURNER POWER           03         97 % RPM         TAKEOFF POWER           05         81 % RPM         APPROACH POWER           06         86 % RPM         INTERNEDIATE POWER	01         100 % RPM         AFTERBURNER POWER           03         100 % RPM         TAKEOFF POWER           05         92 % RPM         APPROACH POWER	03 59 IN HG 2700 RPM TAKEOFF POWER 05 35 IN HG 2350 RPM APPROACH POWER 08 59 IN HG 2700 RPM TAKEOFF WITH JETS 09 35 IN HG 2350 RPM APPROACH WITH JETS	03 100 % RPM TAKEOFF POWER 05 97 % RPM APPROACH POWER 06 97 % RPM INTERMEDIATE POWER	03       1.97       EPR         05       1.46       EPR         06       1.21       EPR         INTERMEDIATE POWER	03 1.84 EPR 107.7 % RPM TAKEOFF POWER 04 1.12 EPR 75.0 % RPM CRUISE POWER 05 1.26 EPR 82.3 % RPM APPROACH POWER	03 96.0 % RPM 817 C EGT TANEOFF POWFR 05 70.4 % RPM 617 C EGT APPROACH POWER 06 80.0 % RPM 679 C EGT INTERMEDIATE POWER 18 60.0 % RPM 546 C EGT FLT IDLE-250 KNOTS	05 66.5 % N1 567 C EGT APPROACH POWER 06 80.3 % N1 670 C EGT INTERMEDIATE POWER 11 89.6 % N1 767 C EGT MAX RATED THRUST 13 70.5 % N1 580 C EGT TRAFFIC PATTERN
TLE 6	POWER SETTING VALUE&UNITS OPERATION POWER PL FIRST SECOND DESCRIPTION 03 45 IN HG TAKEOFF POWER 05 24 IN HG APPROACH POWER 06 30 IN HG INTERMEDIATE POWER	102.5 % RPM AFTERBURNER POWER 102 % RPM TAKEOFF POWER 96.5 % RPM APPROACH POWER 93 % RPM INTERNEDIATE POWER	1 108 % RPM 2.45 EPR AFTERBURNER POWER 3 106 % RPM 2.3 EPR TAKEOFF POWER 5 93 % RPM 1.7 EPR APPROACH POWER 6 86.5 % RPM 1.4 EPR INTERMEDIATE POWER	1 97 % RPM AFTERBURNER POWER 3 97 % RPM TAKEOFF POWER 5 81 % RPM APPROACH POWER 6 86 % RPM INTERMEDIATE POWER	1 100 % RPM AFTERBURNER POWER 3 100 % RPM TAKEOFF POWER 5 92 % RPM APPROACH POWER	5 35 IN HG 2700 RPM TAKEOFF POWER 5 35 IN HG 2350 RPM APPROACH POWER 6 59 IN HG 2700 RPM TAKEOFF WITH JETS 9 35 IN HG 2350 RPM APPROACH WITH JETS	3 100 % RPM TAKEOFF POWER 5 97 % RPM APPROACH POWER 6 97 % RPM INTERMEDIATE POWER	1.97 EPR TAKEOFF POWER 1.46 EPR APPROACH POWER 1.21 EPR INTERMEDIATE POWER	1.84 EPR 107.7 & RPM TAKEOFF POWER 1.12 EPR 75.0 & RPM CRUISE POWER 1.26 EPR 82.3 & RPM APPROACH POWER	3 96.0 % RPM 817 C EGT TAKEOFF POWER 5 70.4 % RPM 617 C EGT APPROACH POWER 6 80.0 % RPM 679 C EGT INTERMEDIATE POWER 8 60.0 % RPM 546 C EGT FLT IDLE-250 KNOTS	5 66.5 % NI 567 C EGT APPROACH POWER 6 80.3 % NI 670 C EGT INTERMEDIATE POWER 1 89.6 % NI 767 C EGT MAX RATED THRUST 3 70.5 % NI 580 C EGT TRAFFIC PATTERN

Table 5. NOISEFILE 6.2 Plyover Reference Noise Database Cont'd

Table 5. NOISEFILE 6.2 Flyover Reference Noise Database Cont'd

Table 5. NOISEFILE 6.2 Flyover Reference Noise Database Cont'd

SUMMARY OF FLY	FLYOVER	DATA IN NOISEFILE	ILE 6.1		J	07 MAY 91		PAGE 7
COMDECK NAME ACC NS23031AI 523 NS23051AI 523 NS23081AP 523 NS23091AP 523	00000 000000	POWER SETTING V. FIRST 2800 RPM 2400 RPM 2800 RPM 2400 RPM	SECOND 60 IN HG 27 IN HG 100 % RPM 91 % RPM	OPERATION POWER DESCRIPTION TAKEOFF APPROACH TAKEOFF WITH JETS APPROACH WITH JETS	AIRCRAFT NAME C-123K C-123K C-123K C-123K	SLANT AIR RANGE SPEED 1000 FT 140 KTS 1000 FT 120 KTS 1000 FT 200 KTS	DRAG CONFIGURATION EST. C-131 +0DB EST. C-131 +0DB EST. C-131 +T-38 EST. C-131 +T-38	DATE OF OMEGA 6 RUN 27 DEC 79 27 DEC 79 27 DEC 79 27 DEC 79
NS27011AN 527 NS27031AI 527 NS27041AP 527 NS27051AI 527	024	94.5 4 RPM 94.5 4 RPM 92.3 4 RPM 89 4 RPM		afterburner Takeoff Crui Se Approach	11 11 11 11 1 1 1 1 1 20 20 20 20	1000 FT 300 KTS 1000 FT 300 KTS 1000 FT 370 KTS 1000 FT 200 KTS	EST. F-100D +0.5DB EST. F-100D +0.5DB EST. F-100D +0.5DB EST. F-100D +0.5DB	27 DEC 79 27 DEC 79 27 DEC 79 27 DEC 79
NS35031AI 535 NS35051AI 535	65	100 % RPM 30 % RPM		TAKEOFF	C-12 C-12	1000 FT 160 KTS 1000 FT 160 KTS	INM73 BEECH KING AIR INM73 BEECH KING AIR	26 NOV 89 26 NOV 89
NS36031AI 536 NS36041AI 536 NS36051AI 536	0.20	30000 LBS 10000 LBS 5000 LBS		TAKEOFF CRUISE APPROACH	C-17 C-17 C-17	1000 FT 160 KTS 1000 FT 160 KTS 1000 FT 160 KTS	ESTIM 757-200 +3 DB ESTIM 757-200 +3 DB ESTIM 757-200 +3 LB	14 FEB 89 14 FEB 89 14 FEB 89
NS40031AI 540 NS40051AI 540	63	15000 LBS 4000 LBS		TAKEOFF	C-137 C-137	1000 FT 160 KTS 1000 FT 160 KTS	INM10 B-707 + 0.00dB INM10 B-707 + 0.00dB	26 NOV 89 26 NOV 89
NS41031AI S41 NS41041AI S41 NS41051AI S41	000	14000 LBS 6000 LBS 3000 LBS		takeoff Cruise Landing	C-20 C-20 C-20	1000 FT 160 KTS 1000 FT 160 KTS 1000 FT 160 KTS	INM37 BAC-111 + 0.00dB INM37 BAC-111 + 0.00dB INM37 BAC-111 + 0.00dB	26 NOV 89 26 NOV 89 26 NOV 89
NS42031AI 542 NS42041AI 542 NS42051AI 542	003	14000 LBS 6000 LBS 3000 LBS		TAKEOFF CRUISE LANDING	C-22 C-22 C-22	1000 FT 160 KTS 1000 FT 160 KTS 1000 FT 160 KTS	INM24 B-727 + 0.00dB INM24 B-727 + 0.00dB INM24 B-727 + 0.00dB	26 NOV 89 26 NOV 89 26 NOV 89
NS47031AI 547 NS47051AI 547	03	100 % RPM 30 % RPM		TAKEOFF LANDING	C-23 C-23	1000 FT 160 KTS 1000 FT 160 KTS	INM73 CESSNA + 0.00dB INM73 CESSNA + 0.00dB	26 NOV 89 26 NOV 89
NS48031AI 548 NS48041AI 548 NS48051AI 548 NS48061AI 548	0000	40000 LBS 16000 LBS 8000 LBS 32000 LBS		TAKEOFF CRUISE LANDING INTERMEDIATE	교 교 교 교 교 교 교 교 교 교 교 교 교	1000 FT 160 KTS 1000 FT 160 KTS 1000 FT 160 KTS 1000 FT 160 KTS	INMO2 B-747 + 0.00dB INMO2 B-747 + 0.00dB INMO2 B-747 + 0.00dB INMO2 B-747 + 0.00dB	26 NOV 89 26 NOV 89 26 NOV 89 26 NOV 89
NS49031AI 549 NS49051AI 549	03	100 & RPM 30 & RPM		TAKEOFF LANDING	T-34 T-34	1000 FT 160 KTS 1000 FT 160 KTS	INM75 SINGLE ENGINE PROPINM75 SINGLE ENGINE PROP	26 NOV 89 26 NOV 89
NSS0031AI SS0 NSS0051AI SS0	03	100 & RPM 30 & RPM		TAKEOFF	T-41 T-41	1000 FT 160 KTS 1000 FT 160 KTS	INM75 SINGLE ENGINE PROP INM75 SINGLE ENGINE PROP	26 NOV 89 26 NOV 89
N551031AI 551 N551051AI 551	03	100 & RPM 30 & RPM		TAKEOFF	T-42 T-42	1000 FT 160 KTS 1000 FT 160 KTS	INM76 BEECH BARON + 0.0dB INM76 BEECH BARON + 0.0dB	B 26 NOV 89 B 26 NOV 89
N552031AI 552 N552051AI 552	03	100 & RPM 30 & RPM		TAKEOFF	T-44 T-44	1000 FT 160 KTS 1000 FT 160 KTS	INM73 BEECH KING AIR INM73 BEECH KING AIR	26 NOV 89 26 NOV 89
NSS3031AI 553 NSS3041AI 553 NSS3051AI 553 NSS3061AI 553	0000	1550 LBS 600 LBS 300 LBS 1200 LBS		TAKEOFF CRUISE LANDING INTERMEDIATE	T-45 T-45 T-45	1000 FT 160 KTS 1000 FT 160 KTS 1000 FT 160 KTS 1000 FT 160 KTS	INMS7 CESSNA BUS JET+ 0dB INMS7 CESSNA BUS JET+ 0dB INMS7 CESSNA BUS JET+ 0dB INMS7 CESSNA BUS JET+ 0dB	8 26 NOV 89 8 26 NOV 89 8 26 NOV 89 8 26 NOV 89

Table 5. NOISEFILE 6.2 Flyover Reference Noise Database Cont'd

7	RUN 01 023 4	05 01 01	000000	000 4	05 03 04 04	05 04 01 03	05 04 06	01 04 03	00000 034 053
PAGE	TEST 78-008-001 78-008-001 78-008-001 78-008-001	74-004-040 74-004-014 74-004-040	BS-005-001 BS-005-001 BS-005-001 BS-005-001 BS-005-001	74-004-036 74-004-036 74-004-036 74-004-036	AM-007-001 AM-007-001 AM-007-001 AM-007-001 AM-007-001	78-012-001 78-012-001 78-012-001 78-012-001 78-012-001	76-014-001 76-014-001 76-014-001 76-014-001	76-015-001 76-015-001 76-015-001 76-015-001	78-015-001 78-015-001 78-015-001 78-015-001 78-015-001
	DATE OF OMEGA 8 RUN 27 NOV 78 27 NOV 78 27 NOV 78 27 NOV 78	12 FEB 76 18 DEC 75 12 FEB 76	16 MAR 90 16 MAR 90 16 MAP 90 16 MAR 90 16 MAR 90	01 APR 76 01 APR 76 01 APR 76 01 APR 76	26 MAR 91 26 MAR 91 26 MAR 91 26 MAR 91 26 MAR 91	27 NOV 78 27 NOV 78 27 NOV 78 27 NOV 78 27 NOV 78	07 MAR 83 07 MAR 83 07 MAR 83 07 MAR 83	07 MAR 83 07 MAR 83 07 MAR 83 07 MAR 83	15 MAR 90 15 MAR 90 15 MAR 90 15 MAR 90
09 MAY 91	NOISE SOURCE/SUBJECT FIRST LINE E-3A E-3A E-3A	A-378 A-378 A-378	KC-10A KC-10A KC-10A KC-10A KC-10A KC-10A	C-130E C-130E C-130E C-130E	F-18 F-18 F-19 F-19	F-102A F-102A F-102A F-102A F-102A	YC-14 YC-14 YC-14 YC-14	YC-15 YC-15 YC-15 YC-15	C-5A C-5A C-5A C-5A C-5A
	OPERATION POWER DESCRIPTION IDLE 85 % RPM ENG RUNUP 70 % RPM ENG RUNUP TAKEOFF PWR	M ENG RUNUP	r PWR 1 ENG RUNUP 1 ENG RUNUP PWR 1 ENG RUNUP	RUNUP DLE FF PWR	A/B M ENG RUNUP A/B	A/B ENG RUNUP ENG RUNUP	I ENG RUNUP PWR	3701	ENG RUNUP ENG RUNUP
	OPERATION P DESCRIPTION IDLE 85 % RPM EN 70 % RPM EN	MIL PWR IDLE 85 % RPM	MAX CONT IDLE 95 % RPM 70 % RPM TAKEOFF I	POWER RUI LOW IDLE IDLE TAKEOFF	MAX PWR J MIL PWR IDLE 85 % RPM MIN PWR J	MAX PWR MIL PWR IDLE 85 % RPM 75 % RPM	MIL PWR IDLE 85 & RPM TAKEOFF	IDLE 1.8 EPR REVERSE IDLE 1.95 EPR	HIGH IDLE IDLE 80 % RPM   65 % RPM   MAX PWR
5.2	4D UNITS THIRD 1050 LBS/HR 6750 LBS/HR 4100 LBS/HR		0 0	1400 LBS/HK POWER RU 650 LBS/HR LOW IDLE 780 LBS/HR IDLE 2000 LBS/HR TAKEOFF	PWR PWR PWR	PWR PWR RPR	PWR RPM OFF	1100 LBS/HR IDLE 6400 LBS/HR 1.8 EPR 1350 LBS/HR REVERSE 7	
NOISEFILE 6.	VALUES AND UNITS ECOND THIRD 8 % NF 1050 LBS/HR 5 % NF 6750 LBS/HR 0 % NF 4100 LBS/HR 5 % NF 10000 LBS/HR	250 LBS/HR MIL P 495 LBS/HR IDLE 250 LBS/HR 85 %	LBS/HR MAX C LBS/HR 1DLE LBS/HR 95 % LBS/HR 70 % LBS/HR TAKEO LBS/HR 45 %	775 C TIT 1400 LBS/Hk POWER RU 625 C TIT 650 LBS/HR LOW IDLI 560 C TIT 780 LBS/HR IDLE 970 C TIT 2000 LBS/HR TAKEOFF	LBS/HR MAX PWR LBS/HR MIL PWR LBS/HR IDLE LBS/HR 85 & RP LBS/HR MIN PWR	MAX PWR LBS/HR MIL PWR LBS/HR 1DLE LBS/HR 85 % RPM LBS/HR 75 % RPM	C EGT MIL PWR C EGT IDLE C EGT 85 % RPM C EGT TAKEOFF	LBS/HR LBS/HR LBS/HR LBS/HR	LBS/HR HIGH LBS/HR IDLE LBS/HR 80 4 LBS/HR 65 4 LBS/HR 65 4
RUNUP DATA IN NOISEFILE 6.	VALUES AND UNITS ECOND THIRD 8 % NF 1050 LBS/HR 5 % NF 6750 LBS/HR 0 % NF 4100 LBS/HR 5 % NF 10000 LBS/HR	74 C EGT 2250 LBS/HR MIL P 55 C EGT 495 LBS/HR IDLE 90 C EGT 1250 LBS/HR 85 %	20 C EGT 17100 LBS/HR MAX C 50 C EGT 1360 LBS/HR 95 % 30 C EGT 13000 LBS/HR 95 % 30 C EGT 5700 LBS/HR 70 % 08 C EGT 20000 LBS/HR TAKEO 45 C EGT 2800 LBS/HR 45 %	5 C TIT 1400 LBS/Hk POWER RU 5 C TIT 650 LBS/HR LOW IDLL 0 C TIT 780 LBS/HR IDLE 0 C TIT 2000 LBS/HR TAKEOFF	07 C EGT 7367 LBS/HR MAX PWR 15 C EGT 7260 LBS/HR MIL PWR 49 C EGT 624 LBS/HR 1DLE 55 C EGT 3807 LBS/HR 85 % RP 13 C EGT 7279 LBS/HR MIN PWR	.14 EPR 8500 LBS/HR MIL PWR .01 EPR 1100 LBS/HR 1DLE .43 EPR 2000 LBS/HR 75 % RPM .19 EPR 2000 LBS/HR 75 % RPM	99 % NC 770 C EGT MIL PWR 64 % NC 360 C EGT IDLE 93 % NC 635 C EGT 85 % RPM 02 % NC 845 C EGT TAKEOFF	75 EGT 1100 LBS/HR 65 EGT 6400 LBS/HR 00 EGT 1350 LBS/HR 00 EGT 7400 LBS/HR	2 % NF 2300 LBS/HR HIGH 3 % NF 1200 LBS/HR IDLE 9 % NF 8000 LBS/HR 80 % 3 % NF 4600 LBS/HR 65 % 0 % NF 11000 LBS/HR MAX R
RUNUP DATA IN NOISEFILE 6.	POWER SETTING VALUES AND UNITS 1.05 EPR 28 % NF 1050 LBS/HR 1.47 EPR 85 % NF 6750 LBS/HR 1.23 EPR 70 % NF 4100 LBS/HR 1.84 EPR 95 % NF 10000 LBS/HR	00 % RPM 574 C EGT 2250 LBS/HR MIL P 46 % RPM 355 C EGT 495 LBS/HR IDLE 85 % RPM 490 C EGT 1250 LBS/HR 85 %	24 % N1 620 C EGT 17100 LBS/HR MAX C 24 % N1 406 C EGT 1360 LBS/HR 1DLE 95 % N1 750 C EGT 13000 LBS/HR 95 % 70 % N1 530 C EGT 5700 LBS/HR 70 % 11 % N1 908 C EGT 20000 LBS/HR 7AKEO 45 % N1 445 C EGT 2800 LBS/HR 45 %	9600 IN-LBS 775 C TIT 1400 LBS/Hk POWER RU 800 IN-LBS 625 C TIT 650 LBS/HR LOW IDLI 1400 IN-LBS 560 C TIT 780 LBS/HR IDLE 6800 IN-LBS 970 C TIT 2000 LBS/HR TAKEOFF	5.1 % NC 807 C EGT 7367 LBS/HR MAX PWR 63 % NC 815 C EGT 7260 LBS/HR MIL PWR 63 % NC 449 C EGT 624 LBS/HR 1DLE 85 % NC 655 C EGT 3807 LBS/HR 85 % RP 95 % NC 813 C EGT 7279 LBS/HR MIN PWR	% NC       2.14 EPR       8500 LBS/HR       MAX PWR         % NC       2.13 EPR       8500 LBS/HR       MIL PWR         % NC       1.01 EPR       1100 LBS/HR       1DLE         % NC       1.43 EPR       3500 LBS/HR       85 % RPM         % NC       1.19 EPR       2000 LBS/HR       75 % RPM	% NF         99 % NC         770 C EGT         MIL PWR           % NF         64 % NC         360 C EGT         IDLE           % NF         93 % NC         635 C EGT         85 % RPM           % NF         102 % NC         845 C EGT         TAKEOFF	.04         EPR         375         EGT         1100         LBS/HR           1.8         EPR         465         EGT         6400         LBS/HR           .08         EPR         400         EGT         1350         LBS/HR           .95         EPR         500         EGT         7400         LBS/HR	1.6 EPR     42 % NF     2300 LBS/HR     HIGH       .18 EPR     23 % NF     1200 LBS/HR     IDLE       3.5 EPR     79 % NF     6000 LBS/HR     80 %       2.5 EPR     63 % NF     4600 LBS/HR     65 %       4.4 EPR     90 % NF     11000 LBS/HR     MAX
DATA IN NOISEFILE 6.	PC FIRST SECTING VALUES AND UNITS 13 1.05 EPR 28 % NF 1050 LBS/HR 18 1.47 EPR 85 % NF 6750 LBS/HR 21 1.23 EPR 70 % NF 4100 LBS/HR 30 1.84 EPR 95 % NF 10000 LBS/HR	4 100 4 RPM 574 C EGT 2250 LBS/HR MIL P 3 46 4 RPM 355 C EGT 495 LBS/HR IDLE 8 85 4 RPM 490 C EGT 1250 LBS/HR 85 4	5 103 ¢ N1 820 C EGT 17100 LBS/HR MAX C 6 95 ¢ N1 750 C EGT 13000 LBS/HR 1DLE 170 ¢ N1 530 C EGT 5700 LBS/HR 95 ¢ 0 111 ¢ N1 908 C EGT 20000 LBS/HR 70 ¢ 0 111 ¢ N1 445 C EGT 20000 LBS/HR 7AKEO	9 9600 IN-LBS 775 C TIT 1400 LBS/Hk POWER RU 1 800 IN-LBS 625 C TIT 650 LBS/HR LOW IDLI 3 1400 IN-LBS 560 C TIT 780 LBS/HR IDLE 0 16800 IN-LBS 970 C TIT 2000 LBS/HR TAKEOFF	3 95.1 % NC 807 C EGT 7367 LBS/HR MAX PWR 3 63 % NC 449 C EGT 7260 LBS/HR MIL PWR 8 85 % NC 655 C EGT 3807 LBS/HR 85 % RP 2 95 % NC 813 C EGT 7279 LBS/HR MIN PWR	4 96 % NC 2.14 EPR 8500 LBS/HR MIL PWR 3 57 % NC 1.01 EPR 1100 LBS/HR 1DLE 8 85 % NC 1.43 EPR 3500 LBS/HR 85 % RPM 0 75 % NC 1.19 EPR 2000 LBS/HR 75 % RPM	4 100 % NF 99 % NC 770 C EGT MIL PWR 3 22 % NF 64 % NC 360 C EGT IDLE 8 85 % NF 93 % NC 635 C EGT 85 % RPM 0 111 % NF 102 % NC 845 C EGT TAKEOFF	3 1.04 EPR 375 EGT 1100 LBS/HR 3 1.8 EPR 465 EGT 6400 LBS/HR 4 1.08 EPR 400 EGT 1350 LBS/HR 6 1.95 EPR 500 EGT 7400 LBS/HR	2     1.6 EPR     42 % NF     2300 LBS/HR     HIGH       3     1.18 EPR     23 % NF     1200 LBS/HR     IDLE       9     3.5 EPR     79 % NF     6000 LBS/HR     80 %       2     2.5 EPR     63 % NF     4600 LBS/HR     65 %       1     4.4 EPR     90 % NF     11000 LBS/HR     MAX

Table 6. NOISEFILE 6.2 Runup Reference Noise Database Cont'd.

Table 6. NOISEFILE 6.2 Runup Reference Noise Database Cont'd.

Table 6. NOISEFILE 6.2 Runup Reference Noise Database Cont'd.

78-013-001 78-013-001 78-013-001 78-013-001 78-013-001

202220 20222

F-105D F-105D F-105D F-105D

RUNUP RUNUP

NC RPM

MAX PWR MIL PWR IDLE 90 % NC 80 % RPM

LBS/HR LBS/HR LBS/HR LBS/HR

11000 1700 5550 2800

2.41 2.41 1.17 1.68 1.30

22222

102 102 69 80

03 04 11 11 11 12

077 077 077 077

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Table 6. NOISEFILE 6.2 Runup Reference Noise Database Cont'd.

Table 6. NOISEFILE 6.2 Runup Reference Noise Database Cont'd.

Table 6. NOISEFILE 6.2 Runup Reference Noise Database Cont'd.

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80	RUN 03 1 02	1 02	003	1 02 1 01 1 03	1 01 1 02 1 03	031	1 03 1 02 1 01	003	034	030	03
PAGE	EST 17-001 17-001 17-001	18-001 18-001 18-001	33-001 33-001 33-001 33-001	4 - 00 4 - 00 4 - 00 - 00	26-001 26-001 26-001	7-730-001 7-730-001 7-730-001 7-730-001	31-00 31-00 31-00	33-001 33-001 33-001 33-001	38-001 38-001 38-001 38-001	77-746-001 77-746-001 77-746-001	761-001 761-001 761-001
	TES' BF-717 BF-717 BF-717	BF-71( BF-71( BF-71)	77-83 77-83 77-83 77-83	78-83 78-83 78-83 78-83	77-726	7-17 7-17 7-17	7-77 7-77 7-77	77-73 77-73 77-73 77-73	79-7 79-7 79-7	7-77 7-77 7-77	7-77 7-77 7-77
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	OPERATION POWER DESCRIPTION MAX PWR A/B MIL PWR 90 % RPM ENG RU	MAX PWR / MIL PWR 85 % RPM	MIL PWR IDLE 85 % RPM 70 % RPM	MIL PWR POWER RUNUP IDLE 85 % RPM EN	80 % RPM MAX PWR MAX PWR W	MAX PWR / MIL PWR IDLE 70 % RPM	MAX PWR A MIL PWR 85 % RPM	PWR PWR SR RI	WAR WAR RPy	MAX PWR A MIL PWR 80 % RPM	مين من من موس
		AX P	IL F DLE 5 %	_	80 g MAX MAX	ער נו	MAX F MIL F FF 85 %	FF MAX PWR FF MIL PWR FF POWER RI FF IDLE	MAX PWR MIL PWR IDLE 80 & RPM	FF MAX FFF MIL F	FF MAX PFF MIL PFF 80 %
		Δ. D	114 (c) and and	C EGT C EGT C EGT	EPR 80 & EPR MAX EPR MAX	ער נו	MAX F MIL F PPH FF 85 %	PSI FF MAX PWR PSI FF MIL PWR PSI FF POWER R PSI FF IDLE	FTIT MAX PWR FTIT MIL PWR FTIT IDLE	PPH FF MAX P PPH FF MIL P 80 %	PPH FF MAX P PPH FF MIL P PPH FF 80 %
5.2	D UNITS THIRD	Δ. D	114 (c) and and	572 C EGT 416 C EGT 438 C EGT 400 C EGT	80 g MAX MAX	ער נו	MAX F MIL F FF 85 %	FF MAX PWR FF MIL PWR FF POWER RI FF IDLE	920 FTIT MAX PWR 920 FTIT MIL PWR 440 FTIT 1DLE 650 FTIT 80 % RPW	FF MAX FFF MIL F	FF MAX PFF MIL PFF 80 %
9	SS AND UNITSTHIRD	Δ. D	S/HR MIL E S/HR 1DLE S/HR 85 % S/HR 70 %	572 C EGT 416 C EGT 438 C EGT 400 C EGT	S/HR 1.22 EPR 80 % S/HR 2.35 EPR MAX S/HR 2.79 EPR MAX	ער נו	MAX F MIL F 850 PPH FF 85 %	00 PSI FF MAX PWR 00 PSI FF MIL PWR 25 PSI FF POWER RU 00 PSI FF IDLE 90 PSI FF 75 % RPA	920 FTIT MAX PWR 920 FTIT MIL PWR 440 FTIT 1DLE 650 FTIT 80 % RPW	000 PPH FF MAX F 500 PPH FF MIL F 80 %	6900 PPH FF MAX P 7200 PPH FF MIL P 3200 PPH FF 80 %
9	VALUES AND UNITS SCOND THIRD 5 LBS 1 LBS 1 LBS	Δ. D	LBS/HR IDLE LBS/HR 1DLE LBS/HR 85 % LBS/HR 70 %	00 LBS/HR 572 C EGT 00 LBS/HR 416 C EGT 00 LBS/HR 438 C EGT 00 LBS/HR 400 C EGT	0 LBS/HR 1.22 EPR 80 % 0 LBS/HR 2.35 EPR MAX 0 LBS/HR 2.79 EPR MAX	ער נו	60 C EGT MAX F 60 C EGT 2850 PPH FF 85 %	C EGT 2100 PSI FF MAX PWR C EGT 2100 PSI FF MIL PWR C EGT 1425 PSI FF POWER RU C EGT 500 PSI FF IDLE C EGT 790 PSI FF 75 % RPM	LBS/HR 920 FTIT MAX PWR 12BS/HR 920 FTIT MIL PWR LBS/HR 440 FTIT 1DLE LBS/HR 650 FTIT 80 % RPW	C EGT 8000 PPH FF MAX F C EGT 3500 PPH FF MIL F C EGT 800 %	C TIT 36900 PPH FF MAX P C TIT 7200 PPH FF MIL P C TIT 3200 PPH FF 80 %
IN NOISEFILE 6.	ETTING VALUES AND UNITS SECOND THIRD 19825 LBS 13260 LBS 4630 LBS	MAX P MIL P 85 %	8000 LBS/HR 100 LBS/HR 100E 3200 LBS/HR 85 % 1500 LBS/HR 70 %	9000 LBS/HR 572 C EGT 1600 LBS/HR 416 C EGT 1000 LBS/HR 438 C EGT 3700 LBS/HR 400 C EGT	2200 LBS/HR 1.22 EPR 80 8 8550 LBS/HR 2.35 EPR MAX 13000 LBS/HR 2.79 EPR MAX	MAX F MIL F IDLE 70 %	660 C EGT MAX F MIL F 400 C EGT 2850 PPH FF 85 %	635 C EGT 2100 PSI FF MAX PWR 635 C EGT 2100 PSI FF MIL PWR 500 C EGT 1425 PSI FF POWER R 517 C EGT 500 PSI FF 1DLE 405 C EGT 790 PSI FF 75 % RP	920 FTIT MAX PWR 920 FTIT MIL PWR 440 FTIT 1DLE 650 FTIT 80 % RPW	670 C EGT 8000 PPH FF MAX F 670 C EGT 3500 PPH FF MIL F 400 C EGT 80 %	940 C TIT 36900 PPH FF MAX P 940 C TIT 7200 PPH FF MIL P 690 C TIT 3200 PPH FF 80 %
NOISEFILE 6.	ER SETTING VALUES AND UNITSST SECOND THIRD THIRD RPM 19825 LBS RPM 13260 LBS RPM 4630 LBS	RPM MAX P RPM MIL P RPM 85 %	RPM 8000 LBS/HR IO00 LBS/HR IO00 LBS/HR BF # 3200 LBS/HR B5 \$ \$ \$ \$ \$ \$ \$ \$ \$ \$ \$ \$ \$ \$ \$ \$ \$ \$	RPM 9000 LBS/HR 572 C EGT RPM 1600 LBS/HR 416 C EGT RPM 1000 LBS/HR 438 C EGT RPM 3700 LBS/HR 400 C EGT	RPM 2200 LBS/HR 1.22 EPR 80 % RPM 8550 LBS/HR 2.35 EPR MAX RPM 13000 LBS/HR 2.79 EPR MAX	RPM MAX F RPM MIL F RPM IDLE RPM 70 %	RPM 660 C EGT	RPM 635 C EGT 2100 PSI FF MAX PWR RPM 635 C EGT 2100 PSI FF MIL PWR RPM 500 C EGT 1425 PSI FF POWER R SPPM 517 C EGT 500 PSI FF 1DLE RPM 405 C EGT 790 PSI FF 75 % RPM	N2 38000 LBS/HR 920 FTIT MAX PWR N2 8150 LBS/HR 920 FTIT MIL PWR N2 850 LBS/HR 440 FTIT IDLE N2 3600 LBS/HR 650 FTIT 80 % RPW	RPM 670 C EGT 8000 PPH FF MAX F RPM 670 C EGT 3500 PPH FF MIL P RPM 400 C EGT 80 %	RPM 940 C TIT 36900 PPH FF MAX P RPM 940 C TIT 7200 PPH FF MIL P RPM 690 C TIT 3200 PPH FF 80 %
DATA IN NOISEFILE 6.	POWER SETTING VALUES AND UNITS FIRST SECOND THIRD 103 % RPM 19825 LBS 103 % RPM 13260 LBS 90 % RPM 4630 LBS	MAX P MIL P 85 %	8000 LBS/HR 100 LBS/HR 100E 3200 LBS/HR 85 % 1500 LBS/HR 70 %	7.7 % RPM 9000 LBS/HR 572 C EGT 70 % RPM 1600 LBS/HR 416 C EGT 4.4 % RPM 1000 LBS/HR 438 C EGT 5.6 % RPM 3700 LBS/HR 400 C EGT	2200 LBS/HR 1.22 EPR 80 8 8550 LBS/HR 2.35 EPR MAX 13000 LBS/HR 2.79 EPR MAX	MAX F MIL F IDLE 70 %	8.5 % RPM 660 C EGT MAX F 8.5 % RPM 660 C EGT 2850 PPH FF 85 %	100 % RPM 635 C EGT 2100 PSI FF MAX PWR 9.5 % RPM 635 C EGT 2100 PSI FF MIL PWR 94 % RPM 500 C EGT 1425 PSI FF POWER R1 48 % RPM 517 C EGT 790 PSI FF IDLE 75 % RPM 405 C EGT 790 PSI FF 75 % RPM	38000 LBS/HR 920 FTIT MAX PWR 8150 LBS/HR 920 FTIT MIL PWR 850 LBS/HR 440 FTIT 1DLE 3600 LBS/HR 650 FTIT 80 % RPW	670 C EGT 8000 PPH FF MAX F 670 C EGT 3500 PPH FF MIL F 400 C EGT 80 %	940 C TIT 36900 PPH FF MAX P 940 C TIT 7200 PPH FF MIL P 690 C TIT 3200 PPH FF 80 %
RUNUP DATA IN NOISEFILE 6.	PC FIRST SECOND THIRD 103 % RPM 19825 LBS 103 % RPM 13260 LBS 103 % RPM 13260 LBS 17 90 % RPM 4630 LBS	6 % RPM MAX P 6 % RPM MIL P 5 % RPM 85 %	6 % RPM 8000 LBS/HR MIL F 5 % RPM 1000 LBS/HR 100E 5 % RPM 3200 LBS/HR 85 % 0 % RPM 1500 LBS/HR 70 %	70 % RPM 9000 LBS/HR 572 C EGT 70 % RPM 1600 LBS/HR 416 C EGT .4 % RPM 1000 LBS/HR 438 C EGT .6 % RPM 3700 LBS/HR 400 C EGT	0 % RPM 2200 LBS/HR 1.22 EPR 80 % 6 % RPM 8550 LBS/HR 2.35 EPR MAX 6 % RPM 13000 LBS/HR 2.79 EPR MAX	7 % RPM MAX F 7 % RPM MIL F 3 % RPM IDLE 0 % RPM 70 %	.5 % RPM 660 C EGT MAX F .5 % RPM 660 C EGT 2850 PPH FF 85 %	00 % RPM 635 C EGT 2100 PSI FF MAX PWR 54 % RPM 635 C EGT 2100 PSI FF MIL PWR 94 % RPM 500 C EGT 1425 PSI FF POWER R1 8 % RPM 517 C EGT 500 PSI FF 1DLE 75 % RPM 405 C EGT 790 PSI FF 75 % RPM	1 % N2 38000 LBS/HR 920 FTIT MAX PWR 1 % N2 8150 LBS/HR 920 FTIT MIL PWR 5 % N2 850 LBS/HR 440 FTIT 1DLE 0 % N2 3600 LBS/HR 650 FTIT 80 % RPW	01 % RPM 670 C EGT 8000 PPH FF MAX F 01 % RPM 670 C EGT 3500 PPH FF MIL F 80 % RPM 400 C EGT 80 %	\$ RPM 940 C TIT 36900 PPH FF MAX P \$ RPM 940 C TIT 7200 PPH FF MIL P \$ RPM 690 C TIT 3200 PPH FF 80 \$
GROUND RUNUP DATA IN NOISEFILE 6.	ACC OPC FIRST SECOND THIRD 361 03 103 % RPM 19825 LBS 361 04 103 % RPM 13260 LBS 361 17 90 % RPM 4630 LBS	3 96 % RPM MAX P 4 96 % RPM MIL P 8 85 % RPM 85 % 85 %	4 96 % RPM 8000 LBS/HR MIL F 3 55 % RPM 1000 LBS/HR IDLE 8 95 % RPM 3200 LBS/HR 85 % 1 70 % RPM 1500 LBS/HR 70 %	4 97.7 % RPM 9000 LBS/HR 572 C EGT 9 70 % RPM 1600 LBS/HR 416 C EGT 3 54.4 % RPM 1000 LBS/HR 438 C EGT 8 85.6 % RPM 3700 LBS/HR 400 C EGT	9 80 % RPM 2200 LBS/HR 1.22 EPR 80 % 1 96 % RPM 8550 LBS/HR 2.35 EPR MAX 9 96 % RPM 13000 LBS/HR 2.79 EPR MAX	3 97 % RPM MAX F 4 97 % RPM MIL F 3 53 % RPM IDLE 1 70 % RPM 70 %	3 98.5 % RPM 660 C EGT MAX F 4 98.5 % RPM 660 C EGT 2850 PPH FF 85 %	3 100 % RPM 635 C EGT 2100 PSI FF MAX PWR 99.5 % RPM 635 C EGT 2100 PSI FF MIL PWR 9 94 % RPM 500 C EGT 1425 PSI FF POWER RU 3 48 % RPM 517 C EGT 500 PSI FF IDLE 0 75 % RPM 405 C EGT 790 PSI FF 75 % RPM	3 91 % N2 38000 LBS/HR 920 FTIT MAX PWR 4 91 % N2 8150 LBS/HR 920 FTIT MIL PWR 3 65 % N2 850 LBS/HR 440 FTIT IDLE 9 80 % N2 3600 LBS/HR 650 FTIT 80 % RPM	3 101 % RPM 670 C EGT 8000 PPH FF MAX F 4 101 % RPM 670 C EGT 3500 PPH FF MIL F 9 80 % RPM 400 C EGT 80 % 80 %	3 91 % RPM 940 C TIT 36900 PPH FF MAX P 4 91 % RPM 940 C TIT 7200 PPH FF MIL P 9 80 % RPM 690 C TIT 3200 PPH FF 80 %
RUNUP DATA IN NOISEFILE 6.	CC OPC FIRST SECOND THIRD 61 03 103 % RPM 19825 LBS 61 04 103 % RPM 13260 LBS 61 17 90 % RPM 4630 LBS	62 03 96 % RPM MAX P 62 04 96 % RPM MIL P 62 18 85 % RPM 85 % RPM 85 %	63 04 96 % RPM 8000 LBS/HR MIL F 63 13 55 % RPM 1000 LBS/HR 10LE 63 18 85 % RPM 3200 LBS/HR 85 % 63 21 70 % RPM 1500 LBS/HR 70 %	64 04 97.7 % RPM 9000 LBS/HR 572 C EGT 64 09 70 % RPM 1600 LBS/HR 416 C EGT 64 13 54.4 % RPM 1000 LBS/HR 438 C EGT 64 18 85.6 % RPM 3700 LBS/HR 400 C EGT	65 19 80 % RPM 2200 LBS/HR 1.22 EPR 80 % 65 31 96 % RPM 8550 LBS/HR 2.35 EPR MAX 65 49 96 % RPM 13000 LBS/HR 2.79 EPR MAX	66 03 97 % RPM MAX F 66 04 97 % RPM MIL F 66 13 53 % RPM IDLE 66 21 70 % RPM 70 %	67 03 98.5 % RPM 660 C EGT MAX F 67 04 98.5 % RPM 660 C EGT MIL F 67 18 85 % RPM 400 C EGT 2850 PPH FF 85 %	68 03 100 % RPM 635 C EGT 2100 PSI FF MAX PWR 68 04 99.5 % RPM 635 C EGT 2100 PSI FF MIL PWR 68 09 94 % RPM 500 C EGT 1425 PSI FF POWER RI 68 13 48 % RPM 517 C EGT 500 PSI FF IDLE 68 20 75 % RPM 405 C EGT 790 PSI FF 75 % RPM	69 03 91 % N2 38000 LBS/HR 920 FTIT MAX PWR 69 04 91 % N2 8150 LBS/HR 920 FTIT MIL PWR 69 13 65 % N2 850 LBS/HR 440 FTIT 1DLE 69 19 80 % N2 3600 LBS/HR 650 FTIT 80 % RPW	70 03 101 % RPM 670 C EGT 8000 PPH FF MAX F 70 04 101 % RPM 670 C EGT 3500 PPH FF MIL F 70 19 80 % RPM 400 C EGT 800 %	71 03 91 % RPM 940 C TIT 36900 PPH FF MAX P 71 04 91 % RPM 940 C TIT 7200 PPH FF MIL P 71 19 80 % RPM 690 C TIT 3200 PPH FF 80 %

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PAGE	TEST 7-778-001 7-778-001 7-778-001 7-778-001	9-001 9-001 9-001 9-001	1-001	2-001	3-001	1-001 1-001 1-001 1-001	95-001 95-001 95-001	507-001 507-001 507-002 507-001	508-001 508-001 508-001 508-001	09-039 09-039 09-039	-001 -001 -001	-001
ы	TE: 77-77 77-77 77-77	8-77 8-77 6-77 77-8	6-991	.6-992	66-9	90-994 90-994 90-994 90-994	91-999 91-999 91-99	9-9-9	9-19-9	1111	74-5111-74-5111-74-5111-74-5111-74-5111-74-5111-74-5111-74-511-74-5111	76-513 76-513 76-513
	PO 90 90 7 7 7 90 90 90 90 90 90 90 90 90 90 90 90 90	7 90 7 90 7 90 7 90 7 90 7 90 7	78 7	78 7	787	0000	91 6	76 7 76 7 76 7	76 7 76 7 76 7	76 77 76 7 76 7	76 77 76 7 97 7 97 7 97 7 97 97 97 97 97 97 97 9	76 7 76 7 76 7
	AAAAAA ABAAAA	MAR MAR MAR	MAY	MAY	MAY	NOV NOV	FEB FEB	MAY MAY MAY	MAY MAY MAY	APR APR APR	APR APR APR APR	N N N N N N N N N N N N N N N N N N N
	DAT OMEGA 15 K 15 K 15 K 15 K	15 15 15 15	19	19	19	221	20 20 20	21 21 21 21	25 25 25 25	e e e e e e e e e e e e e e e e e e e	<b>~~~~</b>	005
	SOURCE/SUBJECT LINE -17) F-106 SUPP -17) F-106 SUPP -17) F-106 SUPP -17) F-106 SUPP -17) F-106 SUPP	13) F-111A SUPP 13) F-111A SUPP 13) F-111A SUPP 13) F-111A SUPP 13) F-111A SUPP	I) SUPPRESSORS	II) SUPPRESSORS	III) SUPPRESSORS	3333	STAND STAND STAND					
MAY 91	NOISE SOURC FIRST LINE (AF32A-17) (AF32A-17) (AF32A-17) (AF32A-17) (AF32A-17)	(AF32A-13 (AF32A-13 (AF32A-13 (AF32A-13 (AF32A-13	(GRADE	(GRADE	GRADE	ST CELL ST CELL ST CELL		118 118 118	1440 440 640	SAEB SAEB SAEB SAEB	F-111D F-111D F-111D F-111D	ммм
7₩ 60	SESSEE	33333	Ö	9	5	TEST TEST TEST TEST	TEST TEST TEST	2222	7777	(2) (2) (2) (2)		~ ~ ~
	OPERATION POWER DESCRIPTION MAX PWR A/B MIL PWR IDLE 95 % RPM ENG RUNUP 85 % RPM ENG RUNUP	PWR ZONE 5 A/B PWR ZONE 3 A/B PWR RPWR ENG RUNUP	PWR A/B	PWR A/B	PWR A/B	PWR A/B CONT PWR S RPM ENG RUNUP	O LBS THRUST LBS THRUST	ETO CHECK	PWR RPM ENG RUNUP	PWR A/B PWR RPM ENG RUNUP	PWR ZONE 3 A/B PWR RPW ENG RUNUP RPM ENG RUNUP	PWR RPM ENG RUNUP
	OPERUDESCH MAX H MIL I IDLE 95 %	MAX MAX MIC IDLE 75 %	<b>W</b>	<b>WAX</b>	MAX	MAX MAX IDLE 80 %	20000 4000 I IDLE	MAGNETO IDLE TAXI TAKEOFF	MIL I IDLE 85 % 75 %	MAX MIL IDLE 80 8	MAX I MIL I IDLE 85 %	MIL I IDLE 70 %
6.2	AND UNITS THIRD 10500 LBS/HR 1600 LBS/HR 2400 LBS/HR	33800 LBS/HR 20200 LBS/HR 5900 LBS/HR 900 LBS/HR 1500 LBS/HR										
FILE	LUES PR PR PR PR	7117 7117 7117						IN MAP IN MAP IN MAP	EPR EPR EPR			
NOISEFI	ING VALUE SECOND 2.18 EPR 2.18 EPR 1.2 EPR 2.0 EPR 1.85 EPR	1104 C 1094 C 1086 C 558 C 726 C						27.5 I 13 I 24 I 62 I	1.93 1.03 1.46 1.25			
DATA IN	SET	22222	RPM	RPM	RPM	RPM RPM RPM			RPM RPM RPM	RPM RPM RPM	22222 22222	RPM RPM RPM
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GROUND	000 03 13 16 18	01 04 13 20	03	03	03	03 05 13	139	08 113 115 30	04 113 20	03 13 19	00 11 18 10 10	21
or G	ACC 372 372 372 372	373 373 373 373	391	392	393	394	395 395 395	507 507 507 507	508 508 508 508	5009 509	511 511 511 511 511	513 513 513
SUMMARY	COMDECK NAME N37203A0 N37204A0 N37213A0 N37216A0	N37301A0 N37302A0 N37304A0 N37313A0	N39103A0	N39203A0	N39303A0	N39403A0 N39405A0 N39413A0 N39419A0	N39504A0 N39509A0 N39513A0	NS0708A0 NS0713A0 NS0715A0 NS0730A0	NS0804A0 NS0813A0 NS0818A0 NS082CA0	NS0903A0 NS0904A0 NS0913A0 NS0919A0	NS1102A0 NS1104A0 NS1113A0 NS1118A0 NS1118A0	NS1304A0 NS1313A0 NS1321A0

Table 6. NOISEFILE 6.2 Runup Reference Noise Database Cont'd.

10	RUN 02 01 01	000 000 000 000 000	03	0000	03 02 04	03	007	007	03
PAGE 1	ST 6-001 6-001 6-002 6-002	17-001 17-001 17-001 17-001 17-001	8-001 8-001 8-001	519-001 519-001 519-001 519-001	0-001 0-001 0-001 0-001	1-001 1-001 1-001 1-001	7-002 7-002 7-001 7-001	7-001 7-001 7-001	9-001 9-001
a	TEST 76-516-001 76-516-001 76-516-002 76-516-001	76-517-001 76-517-001 76-517-001 76-517-001 76-517-001	76-518-001 76-518-001 76-518-001	76-519-001 76-519-001 76-519-001 76-519-001	76-520-001 76-520-001 76-520-001 76-520-001	76-521-001 76-521-001 76-521-001 76-521-001	77-527-002 77-527-002 77-527-001 77-527-001	AM-007-001 AM-007-001 AM-007-001	76-039-001 76-039-001
	OF RUN 76 76 76	76 76 76 76 76	76	76 76 76	76 76 76	76 76 76 76	77 77 77	911	91
	AAAA AAAA	APR APR APR APR APR	APR APR APR	DEC DEC DEC DEC	DEC DEC DEC	DEC DEC DEC	007 007 007	MAR MAR MAR	MAR
	DAT OMEGA 24 M 25 M 25 M	76 76 76 76 76 76	27 27 27	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	13	1 1 4 4 4 4 4 4 4 4 4 4 4 4 4 4 4 4 4 4	26 26 26 26	26 26 26	26 26
91	SOURCE/SUBJECT LINE			2707 2707 20703 20703	ላሴ D የፋ D የፋ D የፋ D	44.N& P 46.N& P 46.N& P 46.N& P		A SURROGATE A SURROGATE A SURROGATE	SURROGATE SURROGATE
09 MAY 9	NOISE FIRST T-29 T-29 T-29	SR-71 SR-71 SR-71 SR-71 SR-71	U-2 U-2 U-2	B-52B&D&E B-52B&D&E B-52B&D&E B-52B&D&E	C-130A&D C-130A&D C-130A&D C-130A&D	C-130H&N&P C-130H&N&P C-130H&N&P C-130H&N&P	11 11 11 11 11 11 11 11 11 11 11 11 11	F-117A F-117A F-117A	B-2 SI
9	OPERATION POWER DESCRIPTION MAGNETO CHECK IDLE TAXI TAXI	MAX PWR A/B MIL PWR IDLE 50 % RPM ENG RUNUP MIN PWR A/B 30 % RPM ENG RUNUP	MIL PWR IDLE 85 % RPM ENG RUNUP	IDLE 90 % RPM ENG RUNUP 80 % RPM ENG RUNUP MAX PWR	POWER RUNUP LOW IDLE IDLE TAKEOFF PWR	POWER RUNUP LOW IDLE IDLE TAKEOFF PWR	MAX PWR A/B MIL PWR IDLE 70 % RPM ENG RUNUP	MIL PWR IDLE 85 % RPM ENG RUNUP	INTERMED PWR (MIL) IDLE
2	AND UNITSTHIRD			1.05 EPR 2.04 EPR 1.35 EPR 2.45 EPR	1400 LBS/HR 650 LBS/HR 780 LBS/HR 2000 LBS/HR	1400 LBS/HR 650 LBS/HR 780 LBS/HR 2000 LBE/HR		7260 LBS/HR 624 LBS/HR 3807 LBS/HR	
N NOISEFILE 6	SETTING VALUES A SECOND 27.5 IN MAP 13 IN MAP 24 IN MAP 62 IN MAP			300 C EGT 520 C EGT 340 C EGT 580 C EGT	775 C TIT 625 C TIT 560 C TIT 970 C TIT	775 C TIT 625 C TIT 560 C TIT 970 C TIT		815 C EGT 449 C EGT 655 C EGT	1317 C TIT 848 C TIT
GROUND RUNUP DATA IN NOISEFIL	FIRST 2050 RPM 800 RPM 1000 RPM 2800 RPM	80 20 20 20 20 20 20 20 30 30 30 30 30 30 30 30 30 30 30 30 30	100 % RPM 68 % RPM 85 % RPM	61 & RPM 90 & RPM 80 & RPM 94 RPM	9600 IN-LBS 800 IN-LBS 1400 IN-LBS 16800 IN-LBS	9600 IN-LBS 800 IN-LBS 1400 IN-LBS 16800 IN-LBS	100 % RPM 97 % RPM 53 % RPM 70 % RPM	94 % NC 63 % NC 85 % NC	97.2 % RPM 70.5 % RPM
OUND	0PC 08 13 30	00 113 123 134 135 136 137	04 13 18	13 17 19 31	09 111 30	09 111 13	03 13 21	04 113 18	13
)F GR	ACC 516 516 516 516	\$17 \$17 \$17 \$17 \$17	518 518 518	519 519 519 519	\$20 \$20 \$20	521 521 521 521 521	527 527 527 527	567 567 567	568
SUMMARY OF	COMDECK NAME NS1608A0 NS1613A0 NS1615A0 NS1630A0	NS1703A0 NS1704A0 NS1713A0 NS1725A0 NS1742A0	NS1804A0 NS1813A0 NS1818A0	NS1913A0 NS1917A0 NS1919A0 NS193A0	NS2009A0 NS2011A0 NS2013A0 NS2030A0	NS2109A0 NS2111A0 NS2113A0 NS2130A0	NS2703A0 NS2704A0 NS2713A0 NS2721A0	NS6704A0 NS6713A0 NS6718A0	NS6806A0 NS6813A0

END OF DATA FILE. NUMBER OF NORMALIZED DATA DECKS= 398

Table 7. NOISEFILE 6.2 Civil Reference Noise Database

Table 7. NOISEFILE 6.2 Civil Reference Noise Database cont'd

SUMPARI OF	40173	Z,	DATA IN CE	VIL DATABASE 6	7	13	MAY 91			PAGE 3
COMDECK NAME N230031AI N230041AI N230051AI	ACC OF 230 0	PC PC 03 14 605 3	POWER SETTING FIRST 14000 LBS 6000 LBS 3000 LBS	NG VALUELUNITS SECOND	OPERATION POWER DESCRIPTION TAKEOFF CRUISE LANDING	AIRCRAFT NAME B727-2017 B727-2017 B727-2017	SLANT RANGE 1000 FT 1000 FT	AIR SPEED 160 KTS 160 KTS 160 KTS	ENGINE TYPE JTBD(AC-LINED) JTBD(AC-LINED) JTBD(AC-LINED)	DATE OF OMEGA 6 RUN 14 JAN 88 14 JAN 88 14 JAN 88
N231031AI N231051AI	231 0	03 40	0000 LBS		TAKEOFF	A-300 A-300	1000 FT 1000 FT	160 KTS 160 KTS	2-E HIGH TB CF6 2-E HIGH TB CF6	14 JAN 88 14 JAN 88
N232031AI N232051AI	232 0	03 38 05 10	800 . BS		TAKEOFF	B767-CF6 B757-CF6	1000 FT 1000 FT	160 KTS 160 KTS	CF6-80A/JT9D7R4 CF6-80A/JT9D7R4	22 JAN 88 22 JAN 88
N233031AI N233051AI	233 0	03 38 05 10	8000 LBS		TAKEOFF	B767-JT9 B767-JT9	1000 FT 1000 FT	160 KTS 160 KTS	CF6-80A/JT9D7R4 CF6-80A/JT9D7R4	22 JAN 88 22 JAN 88
N234031AI N234051AI	234 0	03 40	0000 LBS		TAKEOFF	A-310 A-310	1000 FT 10( ) FT	160 KTS 160 KTS	2-E HIGH TB CF6 2-E HIGH TB CF6	14 JAN 88 14 JAN 88
N235031AI N235051AI	235 0	03 16 05 4	6000 LBS 4000 LBS		TAKEOFF	B737-300B1 B737-300B1	1000 FT 1000 FT	160 KTS 160 KTS	CFM56 CFM56	14 JAN 88 14 JAN 88
N236031AI N236051AI	236 0 236 0	03 16 05 4	6000 LBS 4000 LBS		TAKEOFF	B737-300B2 B737-300B2	1000 FT 1000 FT	160 KTS 160 KTS	CFM56 CFM56	14 JAN 88 14 JAN 88
N237031AI N237041AI N237051AI	237 0 237 0 237 0	03 14 04 6 05 3	4000 LBS 6000 LBS 3000 LBS		TAKEOFF CRUISE LANDING	BAC-111 BAC-111 BAC-111	1000 FT 1000 FT 1000 FT	160 KTS 160 KTS 160 KTS	JT8D (UNTREATED) JT8D (UNTREATED) JT8D (UNTREATED)	14 JAN 88 14 JAN 88 14 JAN 89
N238041AI N238041AI N238051AI N238061AI N238131AI	238 0 238 0 238 0 238 0 238 1	03 10 04 4 05 2 06 8	00000 LBS 4000 LBS 2000 LBS 80000 LBS 6000 LBS		TAKEOFF CRUISE LANDING INTERMEDIATE TRAFFIC PATTERN	F-28-MK2 F-28-MK2 F-28-MK2 F-28-MK2 F-28-MK2	1000 FT 1000 FT 1000 FT 1000 FT	160 KTS 160 KTS 160 KTS 160 KTS 160 KTS	RB183 MK555-15 RB183 MK555-15 RB183 MK555-15 RB183 MK555-15 RB183 MK555-15	14 JAN 88 14 JAN 88 14 JAN 88 14 JAN 88 14 JAN 88
N230031AI N230051AI N239051AI N239061AI N239131AI	2339 00 00 00 00 00 00 00 00 00 00 00 00 00	03 10 04 4 05 2 06 8	00000 LBS 4000 LBS 2000 LBS 8000 LBS 6000 LBS		TAKEOFF CRUISE LANDING INTERMEDIATE TRAFFIC PATTERN	F-28-MK4 F-28-MK4 F-28-MK4 F-28-MK4	1000 FT 1000 FT 1000 FT 1000 FT	160 KTS 160 KTS 160 KTS 160 KTS 160 KTS	RB183 MK555-15 RB183 MK555-15 RB183 MK555-15 RB183 MK555-15 RB183 MK555-15	14 JAN 88 14 JAN 88 14 JAN 88 14 JAN 88 14 JAN 88
N240031AI N240041AI N240051AI	240 240 240 00 240	03 14 04 6 05 3	000 LBS 000 LBS		TAKEOFF CRUISE LANDING	DC9~30D9 DC9~30D9 DC9-30D9	1000 FT 1000 FT 1000 FT	160 KTS 160 KTS 160 KTS	JT8D (UNTREATED) JT8D (UNTREATED) JT8D (UNTREATED)	14 JAN 88 14 JAN 88 14 JAN 88
N241031AI N241041AI N241051AI	241 241 241 0	03 14 04 6 05 3	4000 LBS 6000 LBS 3000 LBS		TAKEOFF CRUISE LANDING	DC9-1007 DC9-1007 DC9-1007	1000 1000 1000 1000	160 KTS 160 KTS 160 KTS	JT8D (UNTREATED) JT8D (UNTREATED) JT8D (UNTREATED)	14 JAN 88 14 JAN 88 14 JAN 88
N242031AI N242041AI N242051AI	242 0	03 14 04 6 05 3	4000 LBS 6000 LBS 3000 LBS		takeoff Cruise Landing	B737-09 B737-09 B737-09	1000 FT 1000 FT 1000 FT	160 KTS 160 KTS 160 KTS	JT8D (UNTREATED) JT8D (UNTREATED) JT8D (UNTREATED)	14 JAN 88 14 JAN 88 14 JAN 88

4	OF RUN 1 88 1 88	888	888	888	888	& & & & & & & & & & & & & & & & & & &	8 8 8 8 8 8 8 8	88 88 88 88 88	88 88 88	88 88 88 88	8 8 8 8 8 8	88 88 88
PAGE	DATE (OMEGA 6 14 JAN 14 JAN 14 JAN 14 JAN 14 JAN	14 JAN 14 JAN 14 JAN	14 JAN 14 JAN 14 JAN	14 JAN 14 JAN 14 JAN	14 JAN 14 JAN 14 JAN	22 JAN 22 JAN 22 JAN 22 JAN	22 JAN 22 JAN 22 JAN 22 JAN	22 JAN 22 JAN 32 JAN 22 JAN	14 JAN 14 JAN 14 JAN	14 JAN 14 JAN 14 JAN	14 JAN 14 JAN 14 JAN	14 JAN 14 JAN 14 JAN
_	<b>5</b>											
	ENGINE TYPE JTBD(AC-LINED) JTBD(AC-LINED) JTBD(AC-LINED)	JT8D(AC-LINED) JT8D(AC-LINED) JT8D(AC-LINED)	JT8D(AC-LINED) JT8D(AC-LINED) JT8D(AC-LINED)	JT8D(AC-LINED) JT8D(AC-LINED) JT8D(AC-LINED)	JT8D(AC-LINED) JT8D(AC-LINED) JT8D(AC-LINED)	209/217 209/217 209/217 209/217	JT8D-209/217 JT8D-209/217 JT8D-209/217 JT8D-209/217	JT8D-209/217 JT8D-209/217 JT8D-209/217 JT8D-209/217	-535 -535 -535	JET & FAN JET & FAN JET & FAN	F TFE 731 F TFE 731 F TFE 731	CJ610 CJ610 CJ610
	ENGINE JT8D(A JT8D(A	JT8D( JT8D( JT8D(	JT8D( JT8D( JT8D(	JT8D( JT8D( JT8D(	JT8D( JT8D( JT8D(	JT8D-209/21 JT8D-209/21 JT8D-209/21 JT8D-209/21	JT8D- JT8D- JT8D-	JT8D- JT8D- JT8D-	RB211- RB211- RB211-	TURBOJET TURBOJET TURBOJET	2-E TF 2-E TF 2-E TF	2-E TU 2-E TU 2-E TU
	AIR SPEED 160 KTS 160 KTS	160 KTS 160 KTS 160 KTS	160 KTS 160 KTS 160 KTS	160 KTS 160 KTS 160 KTS	160 KTS 160 KTS 160 KTS	160 KTS 160 KTS 160 KTS 160 KTS	160 KTS 160 KTS 160 KTS 160 KTS	160 KTS 160 KTS 160 KTS 160 KTS	160 KTS 160 KTS 160 KTS	160 KTS 160 KTS 160 KTS	160 KTS 160 KTS 160 KTS	160 KTS 160 KTS 160 KTS
MAY 91	SLANT RANGE 1000 FT 1000 FT	1000 FT 1000 FT 1000 FT	1000 FT 1000 FT 1000 FT	1000 FT 1000 FT 1000 FT	1000 FT 1000 FT 1000 FT	1000 FT 1000 FT 1000 FT 1000 FT	1000 FT 1000 FT 1000 FT 1000 FT	1000 FT 1000 FT 1000 FT 1000 FT	1000 FT 1000 FT 1000 FT	1000 FT 1000 FT 1000 FT	1000 FT 1000 FT 1000 FT	1000 FT 1000 FT 1000 FT
13	AIRCRAFT NAME DC9-30QN9 DC9-30QN9 DC9-30QN9	DC9-10QN7 DC9-10QN7 DC9-10QN7	B737-QN9 B737-QN9 B737-QN9	DC9-50D17 DC9-50D17 DC9-50D17	B737-D17 B737-D17 B737-D17	MD-81 MD-81 MD-81 MD-81	MD-82 MD-82 MD-82 MD-82	MD-83 MD-83 MD-83 MD-83	B757-RR B757-RR B757-RR	COMJET COMJET COMJET	LEAR-35 LEAR-35 LEAR-35	LEAR-25 LEAR-25 LEAR-25
	OPERATION POWER DESCRIPTION TAKEOFF CRUISE LANDING	TAKEOFF CRUISE LANDING	TAKEOFF CRUISE LANDING	TAKEOFF CRUISE LANDING	TAKEOFF CRUISE LANDING	TAKEOFF CRUISE LANDING INTERMEDIATE	TAKEOFF CRUISE LANDING INTERMEDIATE	TAKEOFF CRUISE LANDING INTERMEDIATE	TAKEOFF CRUISE LANDING	takeoff Cruise Landing	takeoff Cruise Landing	TAKEOFF CRUISE LANDING
DATABASE 6.2	VALUE&UNITS C SECOND I						6014	FOMA		701	201	201
DATA IN CIVIL	POWER SETTING V FIRST 14000 LBS 6000 LBS 3000 LBS	14000 LBS 6000 LBS 3000 LBS	14000 LBS 6000 LBS 3000 LBS	14000 LBS 6000 LBS 3000 LBS	14000 LBS 6000 LBS 3000 LBS	16000 LBS 8000 LBS 4000 LBS 12000 LBS	16000 LBS 8000 LBS 4000 LBS 12000 LBS	16000 LBS 8000 LBS 4000 LBS 12000 LBS	30000 LBS 10000 LBS 5000 LBS	100 % RPM 60 % RPM 30 % RPM	2650 LBS 1500 LBS 1000 LBS	2600 LBS 1800 LBS 700 LBS
YOVER	070 93 05	03 04 05	003	003	03 04 05	03 05 05 06	0 4 0 0 0 0 0	0000	003	03 04 05	03 04 05	003
SUMMARY OF FLY	COMDECK NAME ACC N243031AI 243 N243041AI 243 N243051AI 243	N244031AI 244 N244041AI 244 N244051AI 244	N245031AI 245 N245041AI 245 N245051AI 245	N246031AI 246 N246041AI 246 N246051AI 246	N247031AI 247 N247041AI 247 N247051AI 247	N248031AI 248 N248041AI 248 N248051AI 248 N248061AI 248	N249031AI 249 N249041AI 249 N249051AI 249 N249061AI 249	N250031AI 250 N250041AI 250 N250051AI 250 N250061AI 250	N251031AI 251 N251041AI 251 N251051AI 251	N253031AI 253 N253041AI 253 N253051AI 253	N254031AI 254 N254041AI 254 N254051AI 254	N255031AI 255 N255041AI 255 N255051AI 255

SUMMARY OF FL	FLYOVER	DATA IN CIVIL DATABASE 6.	2	13 1	MAY 91			PAGE 5
COMDECK NAME ACC N256031A1 256 N256041A1 256 N256051A1 256	0PC 03 04	POWER SETTING VALUE&UNITS FIRST SECOND 3750 LBS 2500 LBS 850 LBS	OPERATION POWER DESCRIPTION TAKEOFF CRUISE	AIRCRAFT NAME SABER-80 SABER-80 SABER-80	SLANT RANGE 1000 FT 1000 FT	AIR SPEED 160 KTS 160 KTS 160 KTS	ENCINE TYPE 2-E TF CF700 2-E TF CF700 2-E TF CF700	DATE OF OMEGA 6 RUN 14 JAN 88 14 JAN 88 14 JAN 88
N257031AI 257 N257041AI 257 N257051AI 257 N257061AI 257	0000	1550 LBS 600 LBS 300 LBS 1200 LBS	TAKEOFF CRUISE LANDING INTERMEDIATE	CESSNA-500 CESSNA-500 CESSNA-500 CESSNA-500	1000 FT 1000 FT 1000 FT	160 KTS 160 KTS 160 KTS 160 KTS	2-E TF JT15D 2-E TF JT15D 2-E TF JT15D 2-E TF JT15D	14 JAN 88 14 JAN 88 14 JAN 88 14 JAN 88
N258031AI 258 N258051AI 258	03	5000 LBS 1900 LBS	TAKEOFF	CL-600	1000 FT 1000 FT	160 KTS 160 KTS	2-E TF ALF502L 2-E TF ALF502L	14 JAN 88 14 JAN 88
N259031AI 259 N259041AI 259 N259051AI 259 N259061AI 259 N259131AI 259	03 08 13	10000 LBS 4000 LBS 2000 LBS 8000 LBS 6000 LBS	TAKEOFF CRUISE LANDING INTERMEDIATE TRAFFIC PATTERN	GULF-GIIB GULF-GIIB GULF-GIIB GULF-GIIB	1000 FT 1000 FT 1000 FT 1000 FT	160 KTS 160 KTS 160 KTS 160 KTS 160 KTS	SPEY MK511 SPEY MK511 SPEY MK511 SPEY MK511 SPEY MK511	14 JAN 88 14 JAN 88 14 JAN 88 14 JAN 88 14 JAN 88
N260031AI 260 N260041AI 260 N260051AI 260	03 05	2100 LBS 1500 LBS 670 LBS	TAKEOFF CRUISE LANDING	MU-3001 MU-3001 MU-3001	1000 FT 1000 FT 1000 FT	160 KTS 160 KTS 160 KTS	2-E TF JT150-5 2-E TF JT15D-5 2-E TF JT15D-5	14 JAN 88 14 JAN 88 14 JAN 88
N261031AI 261 N261041AI 261 N261051AI 261 N261061AI 261 N261061AI 261	03 05 06 13	6000 LBS 3000 LBS 2000 LBS 5000 LBS 4000 LBS	TAKEOFF CRUISE LANDING INTERMEDIATE TRAFFIC PATTERN	CL-601 CL-601 CL-601 CL-601 CL-601	1000 FT 1000 FT 1000 FT 1000 FT	160 KTS 160 KTS 160 KTS 160 KTS 160 KTS	2-E TF CF34 2-E TF CF34 2-E TF CF34 2-E TF CF34 2-E TF CF34	14 JAN 88 14 JAN 88 14 JAN 88 14 JAN 88 14 JAN 88
N262031AI 262 N262041AI 262 N262051AI 262	03 04 05	95.5 % RPM 86.6 % RPM 69.2 % RPM	TAKEOFF CRUISE LANDING	ASTRA-1125 ASTRA-1125 ASTRA-1125	1000 FT 1000 FT 1000 FT	160 KTS 160 KTS 160 KTS	GARRETT TFE 731 GARRETT TFE 731 GARRETT TFE 731	14 JAN 88 14 JAN 88 14 JAN 88
N263031AI 263 N263051AI 263	03 05	100 % RPM 30 % RPM	TAKEOFF	ELECTRA188 ELECTRA188	1000 FT 1000 FT	160 KTS 160 KTS	T56-A-7/501-D13 T56-A-7/501-D13	03 MAR 89 03 MAR 89
N265031AI 265 N265051AI 265	03	10. 3 RPM 28 % RPM	TAKEOFF	DHC-7 DHC-7	1000 FT 1000 FT	160 KTS 160 KTS	4-E TP PT6A-50 4-E TP PT6A-50	14 JAN 88 14 JAN 88
N266031AI 266 N266051AI 266	03	100 \$ RPM 30 \$ RPM	TAKEOFF	CONVAIR580 CONVAIR580	1000 FT 1000 FT	160 KTS 160 KTS	ALLISON 501-D13 ALLISON 501-D13	14 JAN 88 14 JAN 88
N267031AI 267 N267041AI 267 N267051AI 267	03 05	100 & RPM 73 & RPM 32 & RPM	TAKEOFF CRUISE LANDING	BAE-HS-748 BAE-HS-748 BAE-HS-748	1000 FT 1000 FT 1000 FT	160 KTS 160 KTS 160 KTS	RR DART MK532 RR DART MK532 RR DART MK532	14 JAN 88 14 JAN 88 14 JAN 88
N268031AI 268 N268041AI 268 N268051AI 268	03	100 % RPM 65 % RPM 35 % RPM	TAKEOFF CRUISE LANDING	SD3-30 SD3-30 SD3-30	1000 FT 1000 FT 1000 FT	160 KTS 160 KTS 160 KTS	2-E TP PT6A 2-E TP PT6A 2-E TP PT6A	14 JAN 88 14 JAN 88 14 JAN 88

PAGE 6	DATE OF OMEGA 6 RUN 14 JAN 88 14 JAN 88	14 JAN 88 14 JAN 88	14 JAN 88 14 JAN 88	14 JAN 88 14 JAN 88 14 JAN 88	14 JAN 88 14 JAN 88	14 JAN 88 14 JAN 88	14 JAN 88 14 JAN 88	14 JAN 88 14 JAN 88	14 JAN 88 14 JAN 88	03 MAR 89 03 MAR 89	02 OCT 90 02 OCT 90 02 OCT 90 02 OCT 90 02 OCT 90 02 OCT 90	21 DEC 90 21 DEC 90 21 DEC 90 21 DEC 90 21 DEC 90 21 DEC 90
	ENGINE TYPE 2-ENGINE TP 2-ENGINE TP	4-ENGINE PISTON 4-ENGINE PISTON	2-E PIST>12500 2-E PIST>12500	2-E TP GE CT7 2-E TP GE CT7 2-E TP GE CT7	SM 2-ENGINE TP SM 2-ENGINE TP	1-ENG VAR PITCH 1-ENG VAR PITCH	1-E FIXED PITCH	2-E PIST<12500 2-E PIST<12500	1-E 1985 FLEET 1-E 1985 FLEET	T56-A-15 T56-A-15	JT8D-7 EM-BI JT8D-7 EM-BI JT8D-7 EM-BI JT8D-7 EM-BI JT8D-7 EM-BI JT8D-7 EM-BI	JT8D-15 EM-BI JT8D-15 EM-BI JT8D-15 EM-BI JT8D-15 EM-BI JT8D-15 EM-BI
	AIR SPEED 160 KTS 160 KTS	160 KTS 160 KTS	160 KTS 160 KTS	160 KTS 160 KTS 160 KTS	160 KTS 160 KTS	160 KTS 160 KTS	160 KTS 160 KTS	160 KTS 160 KTS	160 KTS 160 KTS	160 KTS 160 KTS	160 KTS 160 KTS 160 KTS 160 KTS 160 KTS	160 KTS 160 KTS 160 KTS 160 KTS 160 KTS 160 KTS
MAY 91	SLANT RANGE 1000 FT 1000 FT	1000 FT 1000 FT	1000 FT 1000 FT	1000 FT 1000 FT 1000 FT	1000 FT 1000 FT	1000 FT 1000 FT	1000 FT 1000 FT	1000 FT 1000 FT	1000 FT 1000 FT	1000 FT 1000 FT	1000 FT 1000 FT 1000 FT 1000 FT 1000 FT	1000 FT 1000 FT 1000 FT 1000 FT 1000 FT
13 1	AIRCRAFT NAME DHC-6A27 DHC-6A27	DC-6R2800 DC-6R2800	DC-3R2800 DC-3R2800	SAAB-340 SAAB-340 SAAB-340	CESSNA441 CESSNA441	GA-1ENG-VP GA-1ENG-VP	GA-1ENG-FP GA-1ENG-FP	B-BARON58P B-BARON58P	COMPOS-1EN COMPOS-1EN	HERCULES HERCULES	B727-EM7 B727-EM7 B727-EM7 B727-EM7 B727-EM7	B727-EMS B727-EMS B727-EMS B727-EMS B727-EMS B727-EMS
	OPERATION POWER DESCRIPTION TAKEOFF LANDING	Takeoff Landing	tak eoff Landing	TAKEOFF CRUISE LANDING	takeoff Landing	tak eoff Landing	takeoff Landing	takeoff Landing	tak eoff Landing	tak eoff Landing	TAKEOFF POWER INTERMED POWER (MIL) INTERMEDIATE POWER TRAFFIC PATTERN CRUISE POWER LANDING	TAKEOFF POWER INTERMED POWER (MIL) INTERMEDIATE POWER TRAFFIC PATTERN CRUISE POWER LANDING
DATABASE 6.2	POWER SETTING VALUE UNITS FIRST SECOND 100 % RPM 30 % RPM											
DATA IN CIVIL DATABASE	R SETTING PEIRST 0 % RPM 0 % RPM	O & RPM O & RPM	O & RPM	00 & RPM 15 & RPM 15 & RPM	00 & RPM 30 % RPM	100 % RPM 30 % RPM	100 % RPM 30 % RPM	100 % RPM 30 % RPM	100 % RPM 30 % RPM	100 & RPM 28 % RPM	14000 LBS 12000 LBS 10000 LBS 7000 LBS 5000 LBS 3000 LBS	14000 LBS 12000 LBS 10000 LBS 7000 LBS 5000 LBS 3000 LBS
ď	POWER F1 100 30	100	10	10	<b>~</b>	•						444
OVER DA	OPC F 03 100 05 30	03 10 05 3	03 10 05 3	03 10 04 E	03 1	000	03	03	03	03	00 10 00 10 10 10 10 10 10 10 10 10 10 1	04040 64040 7444
OF FLYOVER DA			5 1	€ <b>4.</b> 2	. s	<b>е</b> у	e v	276 03 276 05	277 03 277 05			

END OF DATA FILE. NUMBER OF NORMALIZED DATA DECKS= 220

## REFERENCES

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## APPENDIX A

## NMAP 6.0 Flowchart

The following is a program flowchart of NMAP 6.0. Figures 1 through 13-A show the overall structure of the program and the remaining pages show the individual subroutine structures. Subroutines are listed alphabetically.

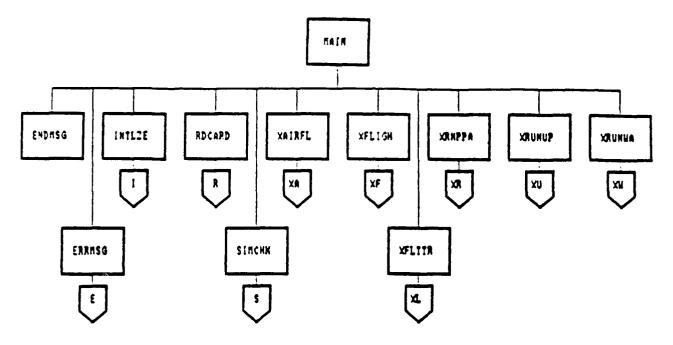


Figure 1. Main Program Procedure Call Reference

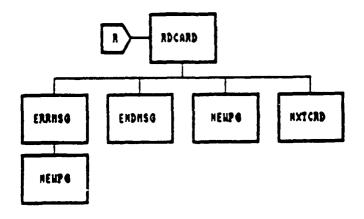


Figure 2. Subroutine RDCARD Procedure Call Reference

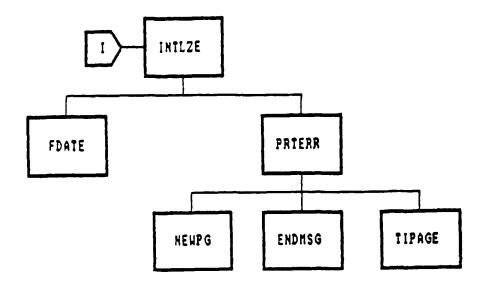


Figure 3. Subroutine INTLZE Procedure Call Reference

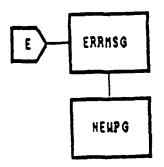


Figure 4. Subroutine ERRMSG Procedure Call Reference

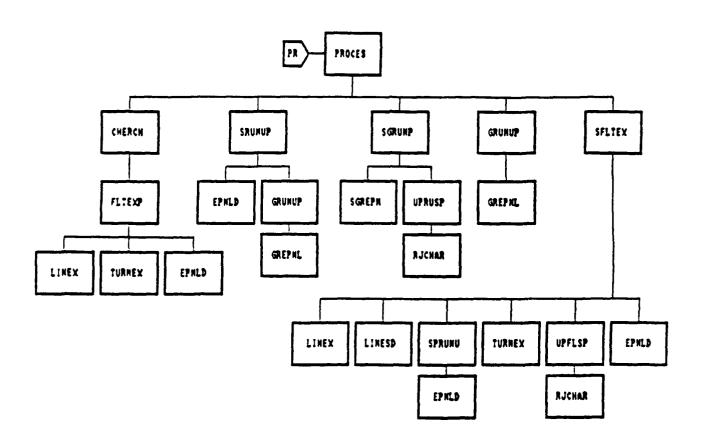


Figure 5. Subroutine PROCES Procedure Call Reference

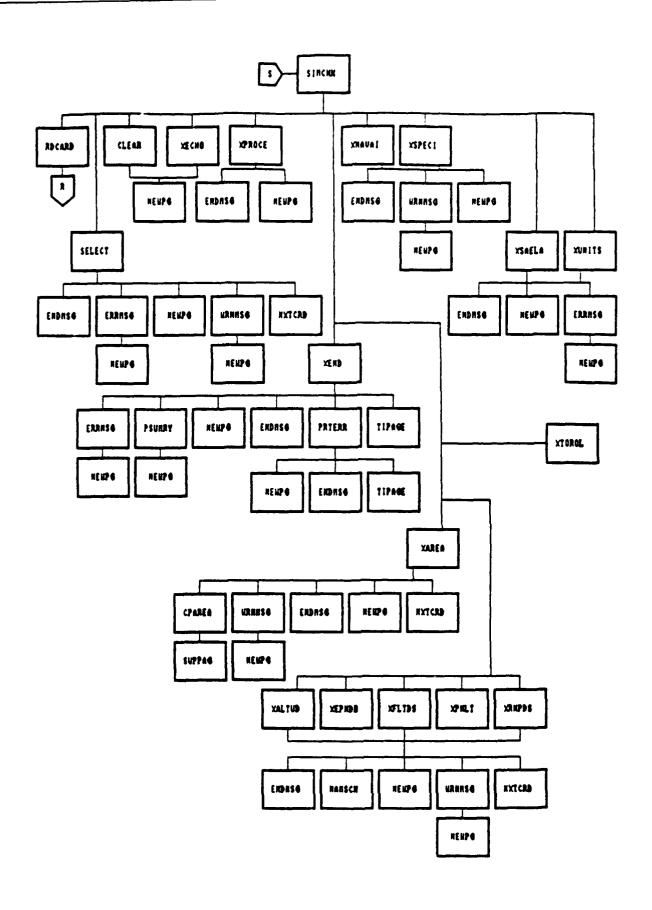


Figure 6. Subroutine SIMCHK Procedure Call Reference

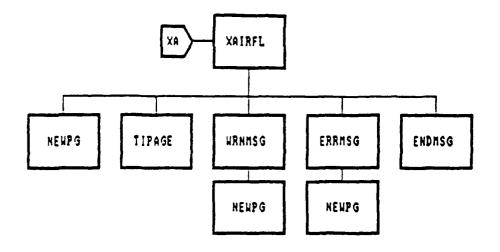


Figure 7. Subroutine XAIRFL Procedure Call Reference

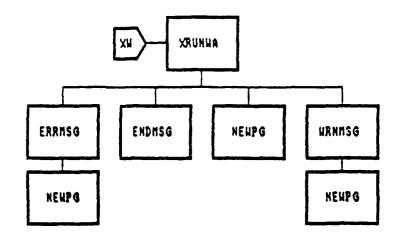


Figure 8. Subroutine XRUNWA Procedure Call Reference

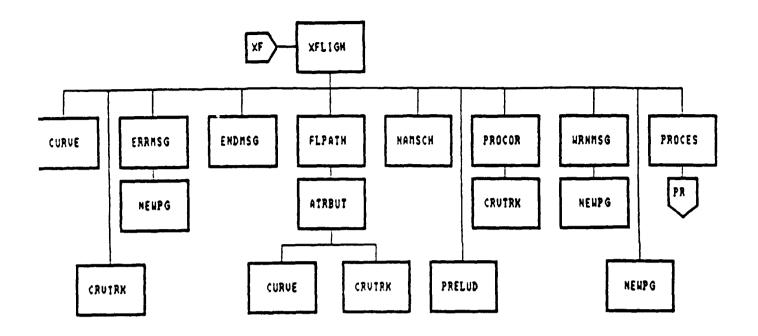


Figure 9. Subroutine XFLIGH Procedure Call Reference

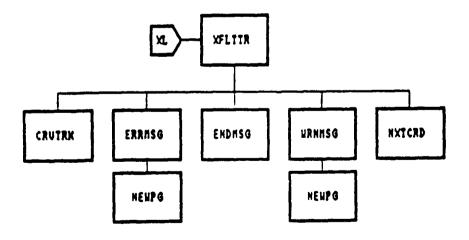


Figure 10. Subroutine XFLTTR Procedure Call Reference

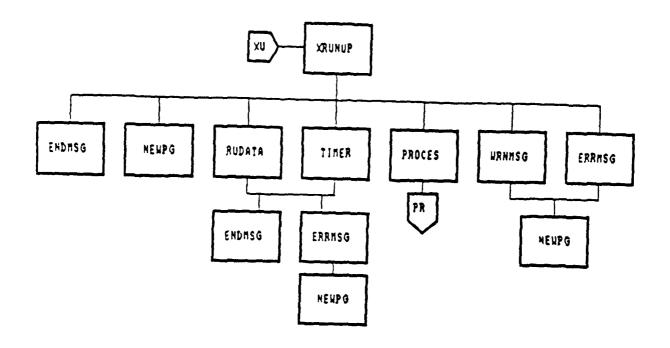


Figure 11. Subroutine XRUNUP Procedure Call Reference

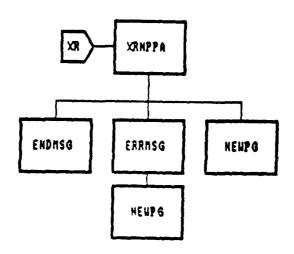


Figure 12. Subroutine XRNPPA Procedure Call Reference

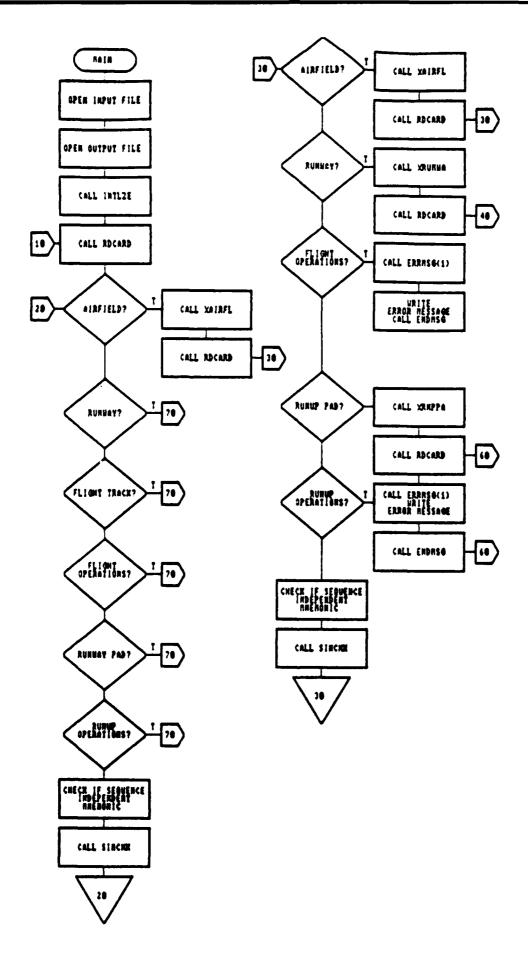


Figure 13. Main Program Flow Diagram

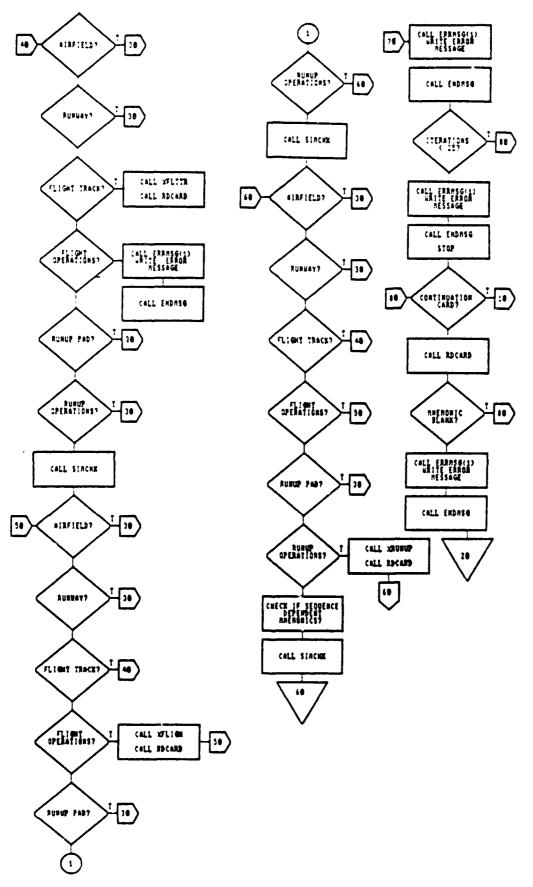


Figure 13-A. Main Program Flow Diagram (Continued)

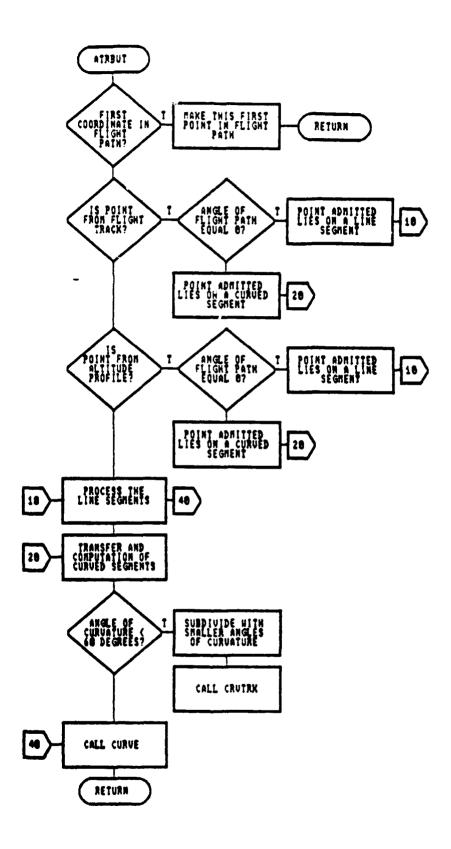


Figure 14. SubProgram ATRBUT Flow Diagram

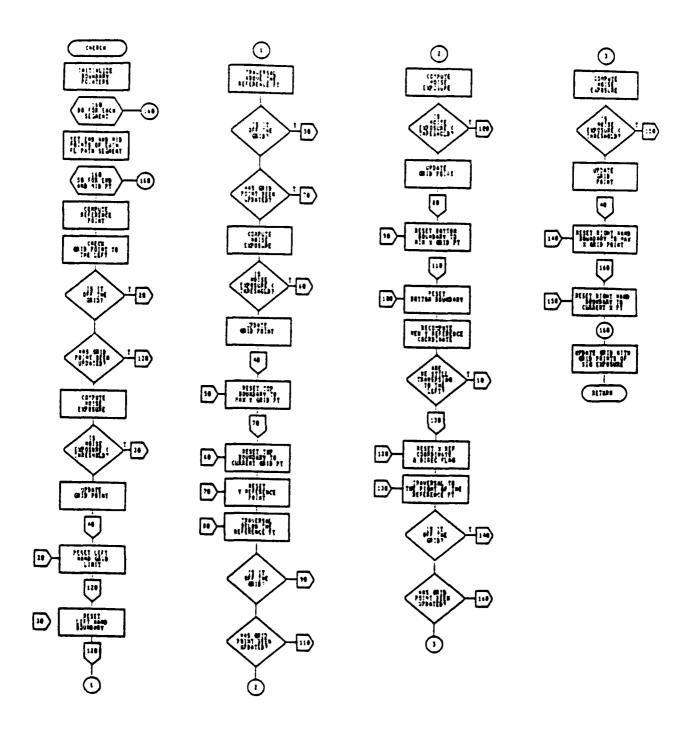


Figure 15. SubProgram CHERCH Flow Diagram

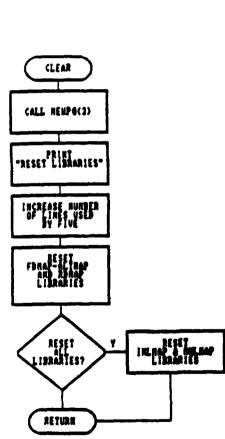


Figure 16. SubProgram CLEAR Flow Diagram

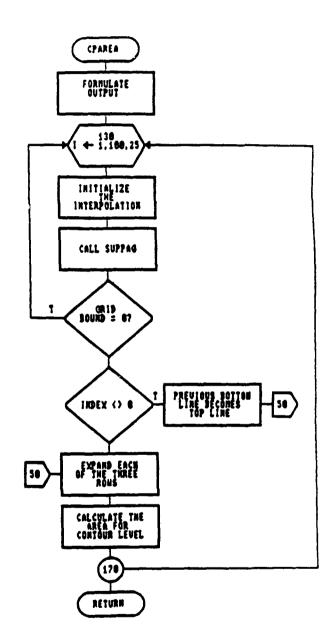


Figure 17. SubProgram CPAREA Flow Diagram

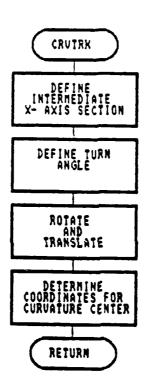


Figure 18. SubProgram CRVTRK Flow Diagram

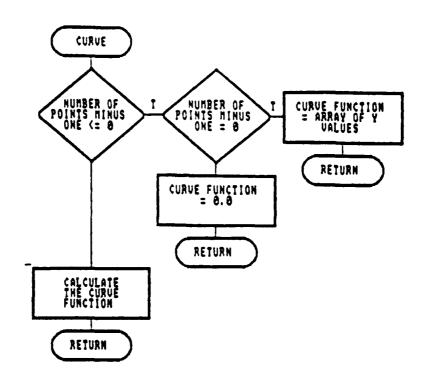


Figure 19. SubProgram CURVE Flow Diagram

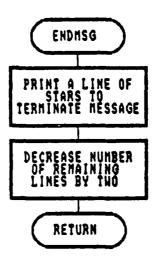


Figure 20. SubProgram ENDMSG Flow Diagram

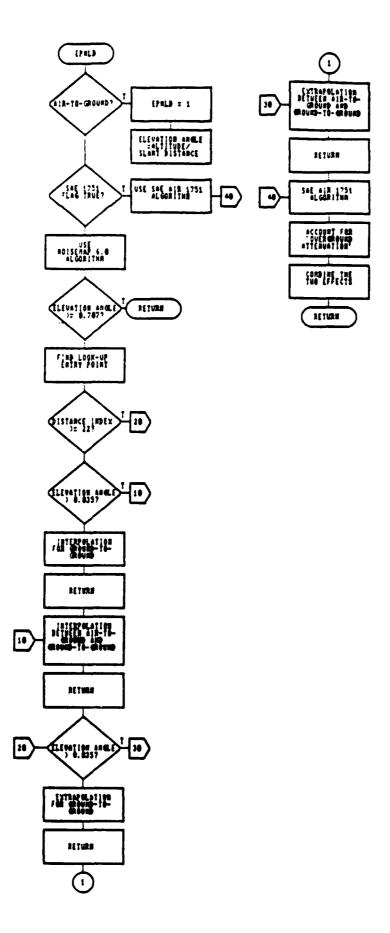


Figure 21. SubProgram EPNLD Flow Diagram

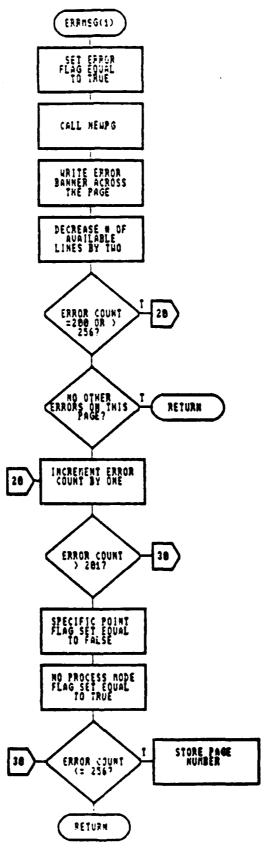


Figure 22. SubProgram ERRMSG Flow Diagram

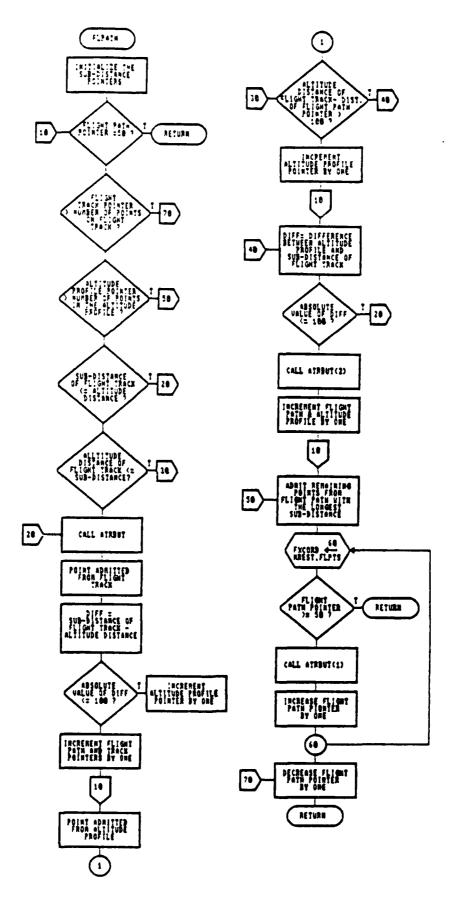


Figure 23. SubProgram FLPATH Flow Diagram

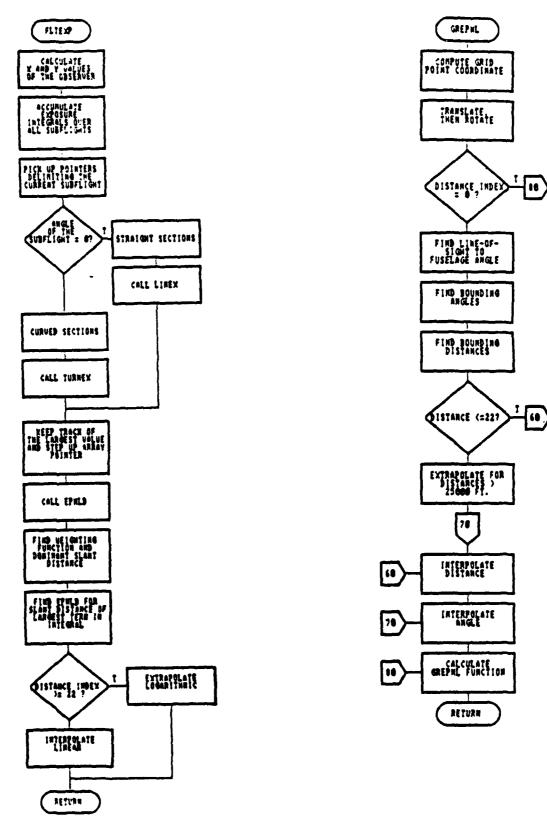


Figure 24. SubProgram FLTEXP Flow Diagram

Figure 25. SubProgram GREPNL Flow Diagram

40)

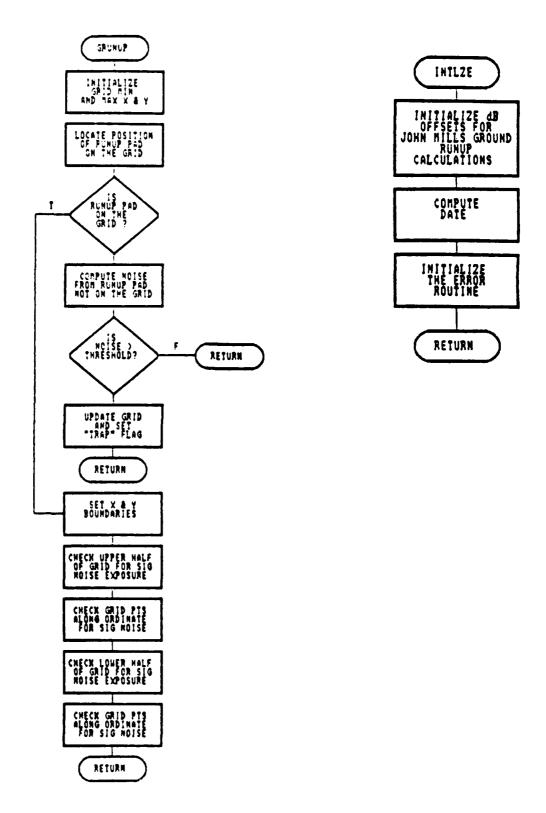


Figure 26. SubProgram GRUNUP Flow Diagram

Figure 27. SubProgram INTLZE Flow Diagram

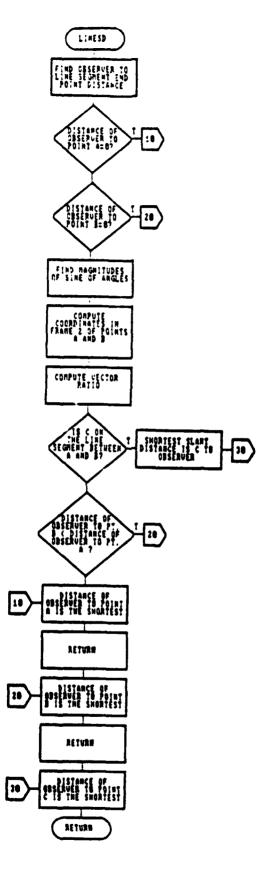


Figure 28. SubProgram LINESD Flow Diagram

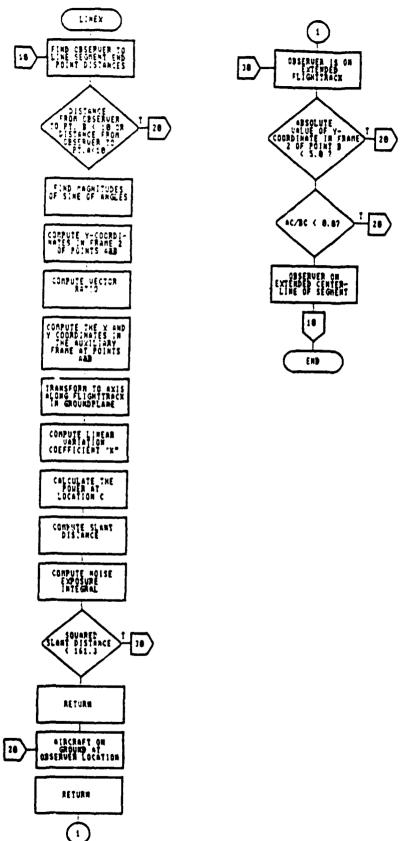


Figure 29. SubProgram LINEX Flow Diagram

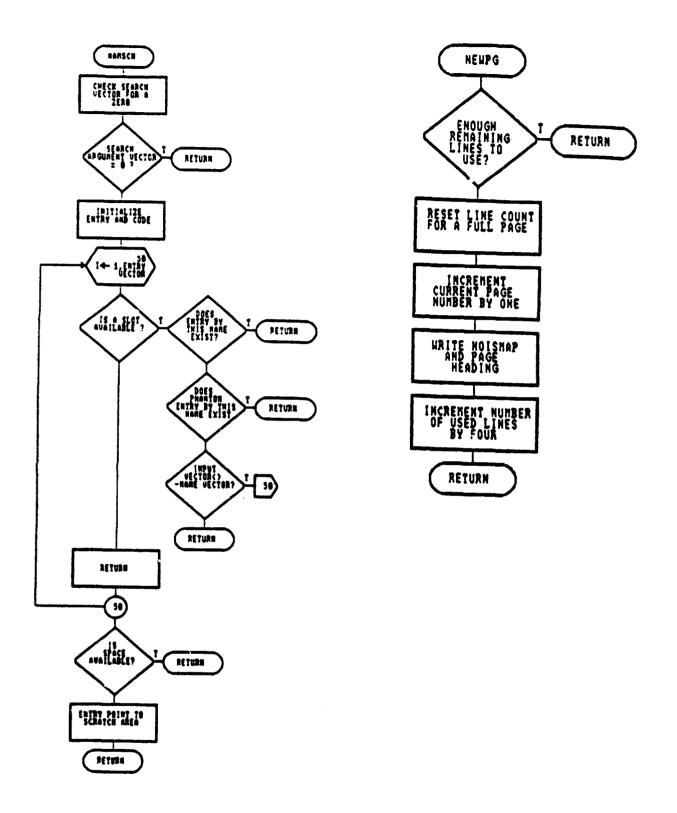
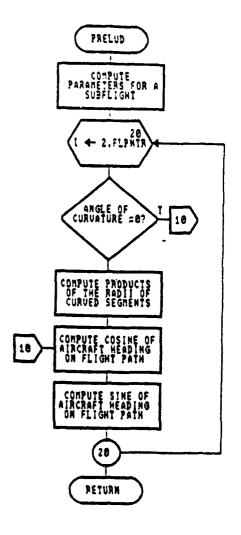


Figure 30. SubProgram NAMSCH Flow Diagram

Figure 31. SubProgram NEWPG Flow Diagram



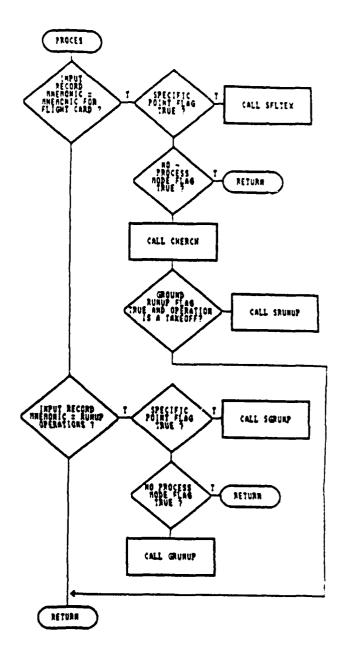


Figure 32. SubProgram PRELUD Flow Diagram

Figure 33. SubProgram PROCES Flow Diagram

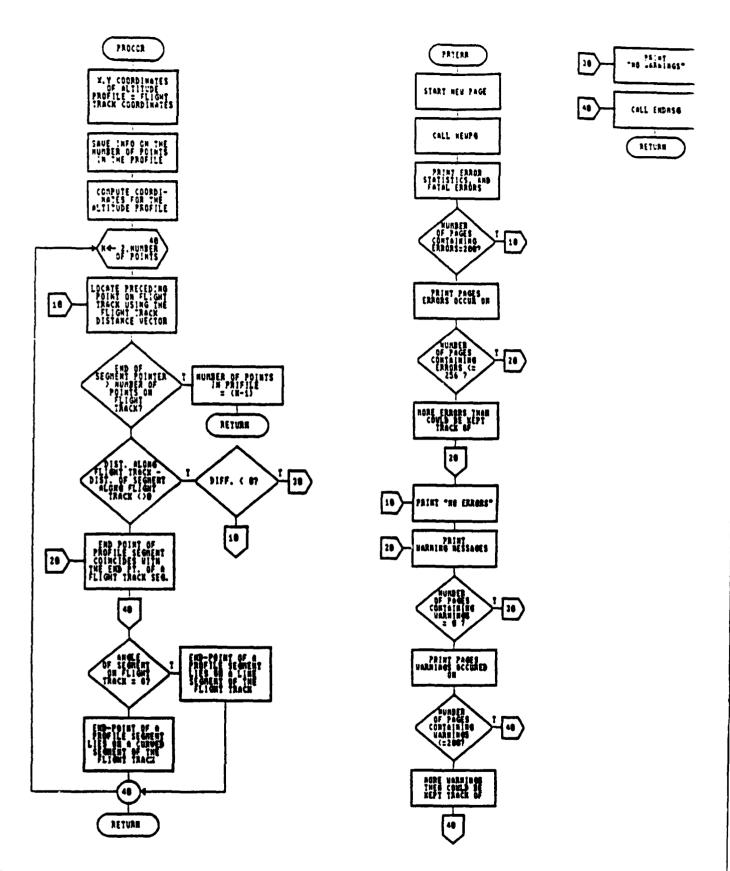


Figure 34. SubProgram PROCOR Flow Diagram

Figure 35. SubProgram PRTERR Flow Diagram

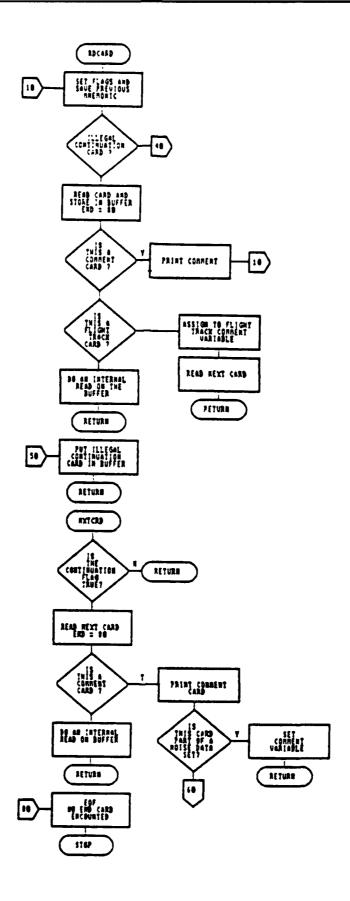


Figure 36. SubProgram RDCARD Flow Diagram

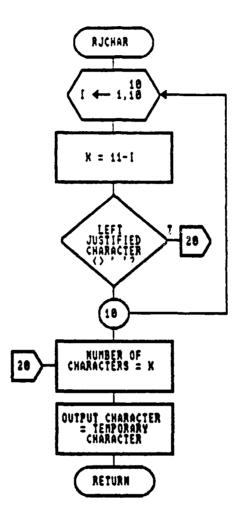


Figure 37. SubProgram RJCHAR Flow Diagram

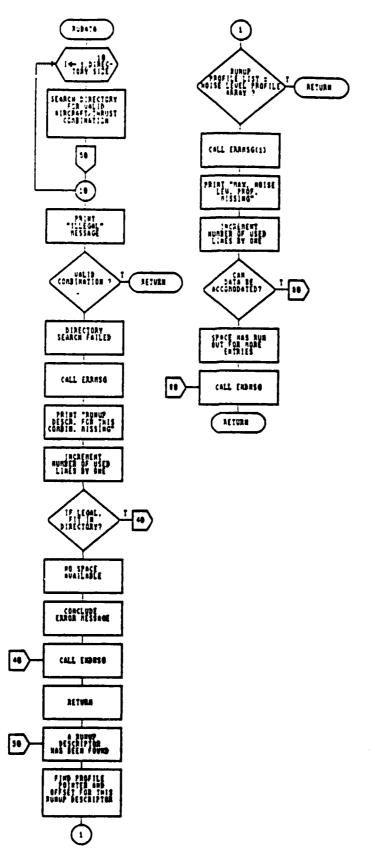


Figure 38. SubProgram RUDATA Flow Diagram

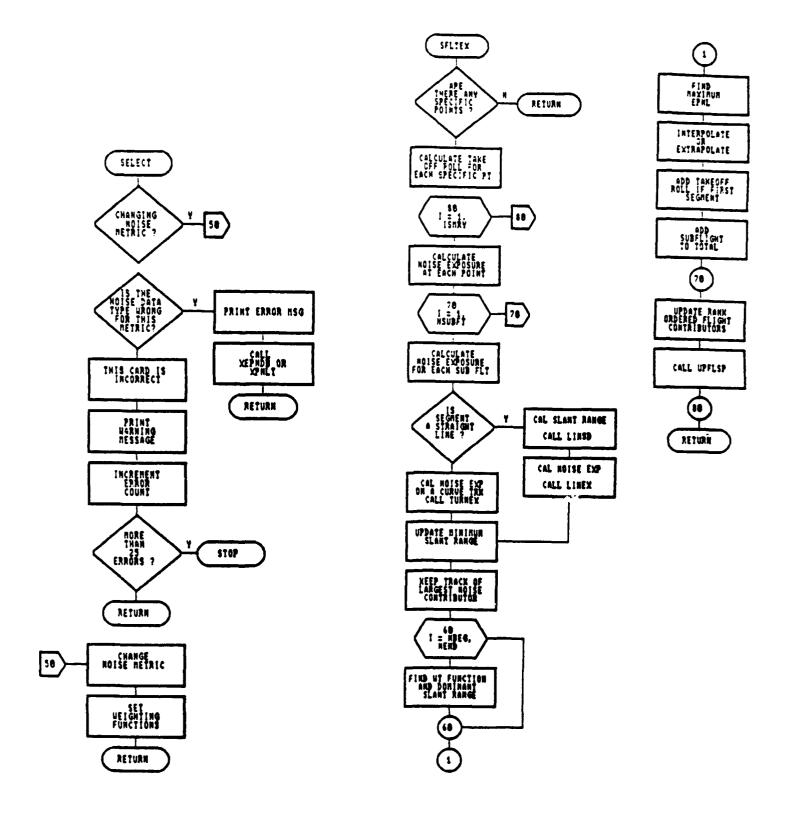


Figure 39. SubProgram SELECT Flow Diagram

Figure 40. SubProgram SFLTEX Flow Diagram

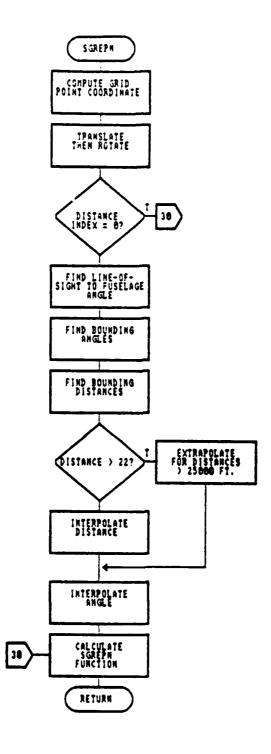


Figure 41. SubProgram SGREPN Flow Diagram

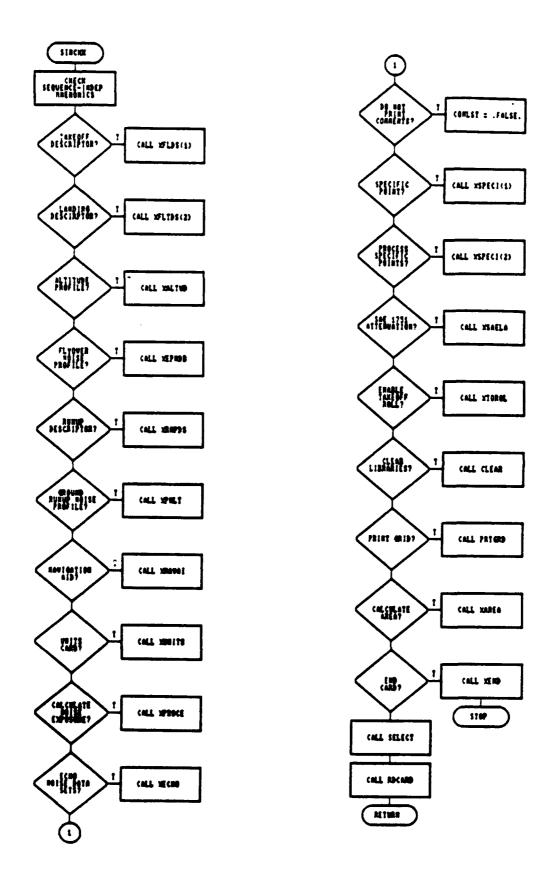
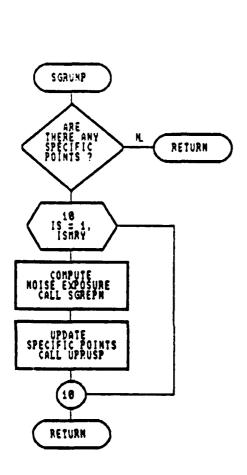


Figure 42. SubProgram SIMCHK Flow Diagram



SPRUNU

I + 1.22

SAE LATERAL T CALL EPNLD

FLAG TRUE?

CALCULATE RUNUP NOISE LEVEL TABLE

CALCULATE RUNUP NOISE LEVEL TABLE

RUNUP NOISE LEVEL TABLE

RUNUP NOISE LEVEL PROFILE ARRAY = 9

RETURN

Figure 43. SubProgram SGRUNP Flow Diagram

Figure 44. SubProgram SPRUNU Flow Diagram

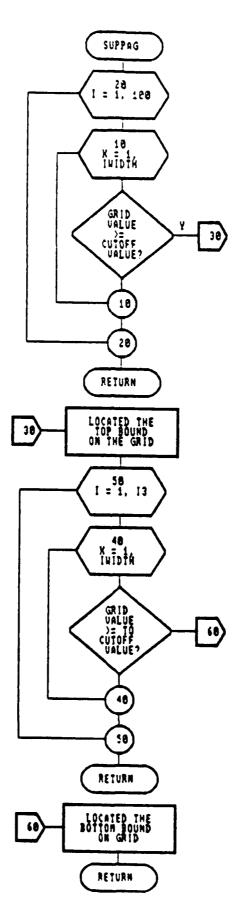


Figure 45. SubProgram SUPPAG Flow Diagram

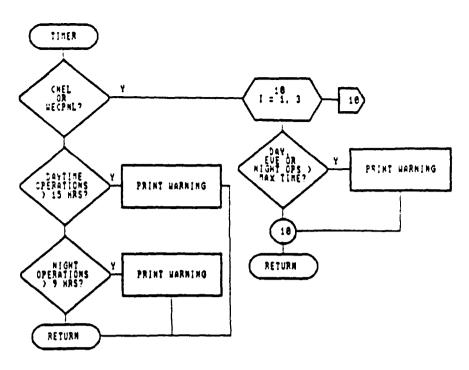


Figure 46. SubProgram TIMER Flow Diagram

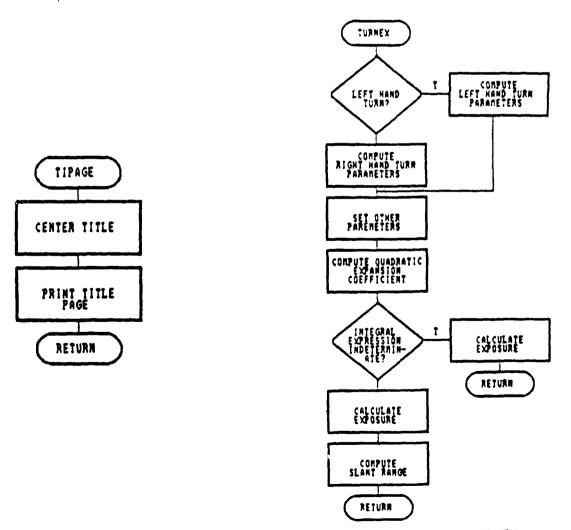


Figure 47. SubProgram TIPAGE Flow Diagram

Figure 48. SubProgram TURNEX Flow Diagram

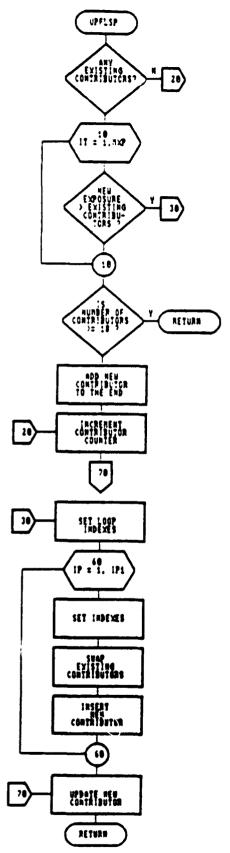


Figure 49. SubProgram UPFLSP Flow Diagram

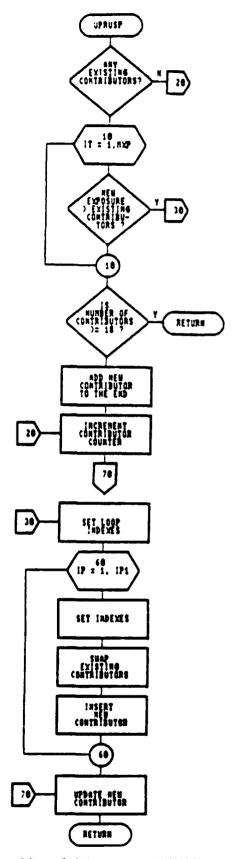


Figure 50. SubProgram UPRUSP Flow Diagram

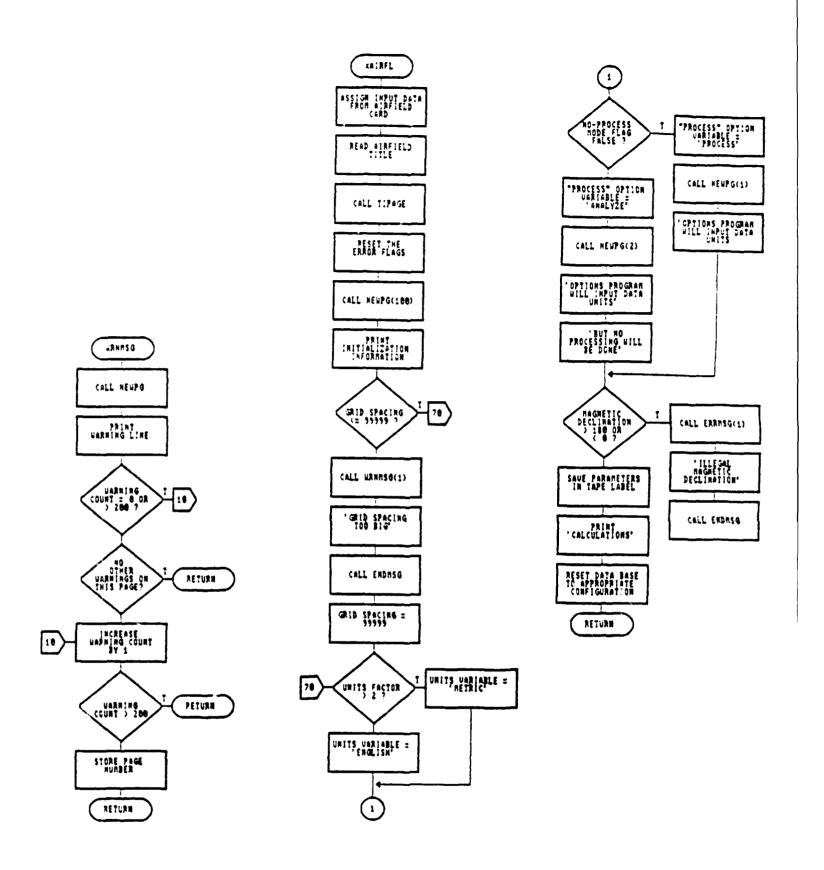


Figure 51. SubProgram WRNMSG Flow Diagram

Figure j2. SubProgram XAIRFL Flow Diagram

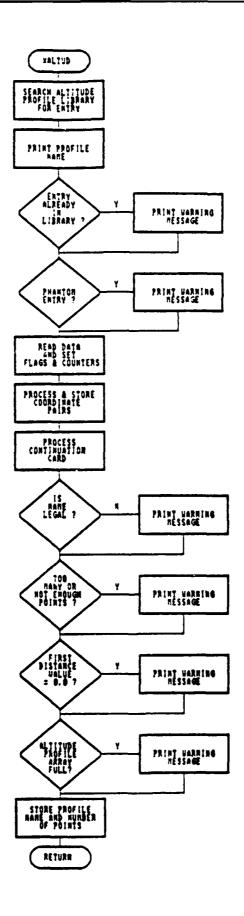


Figure 53. SubProgram XALTUD Flow Diagram

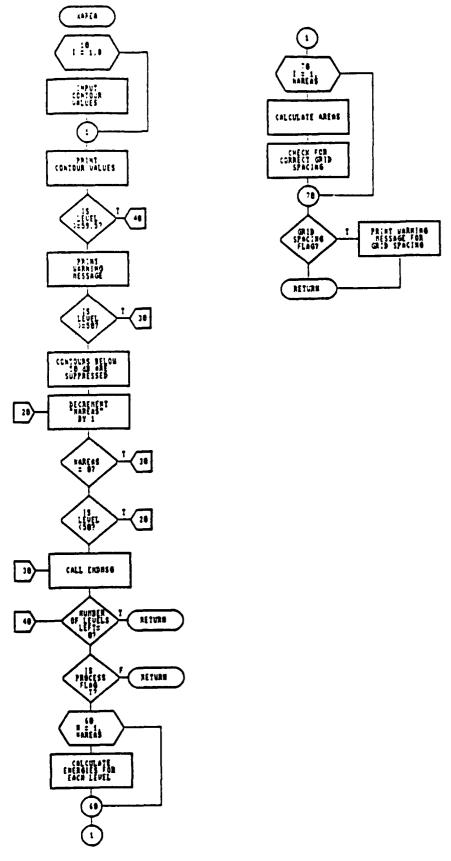
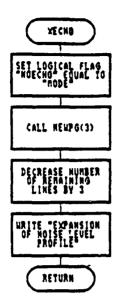


Figure 54. SubProgram XAREA Flow Diagram



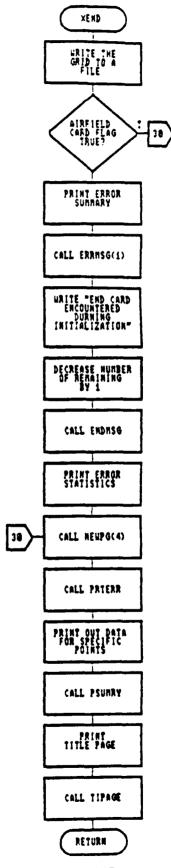


Figure 56. SubProgram XEND Flow Diagram

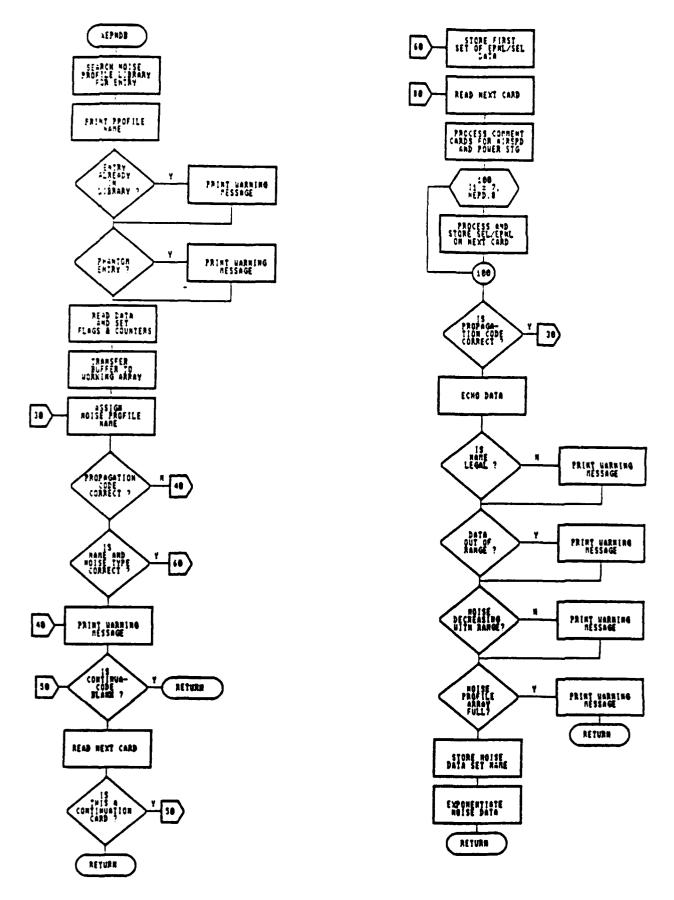


Figure 57. SubProgram XEPNDB Flow Diagram

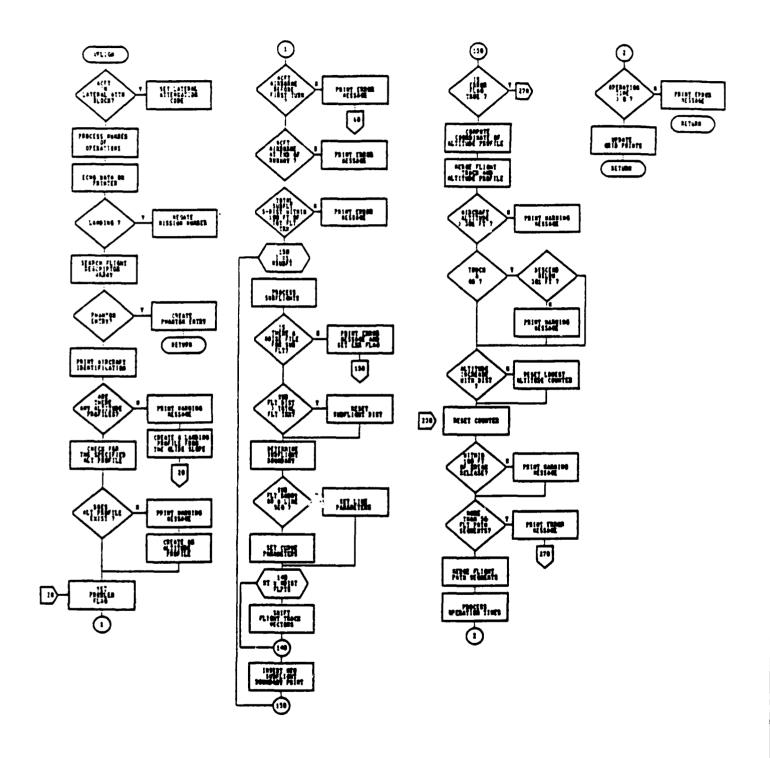


Figure 58. SubProgram XFLIGH Flow Diagram

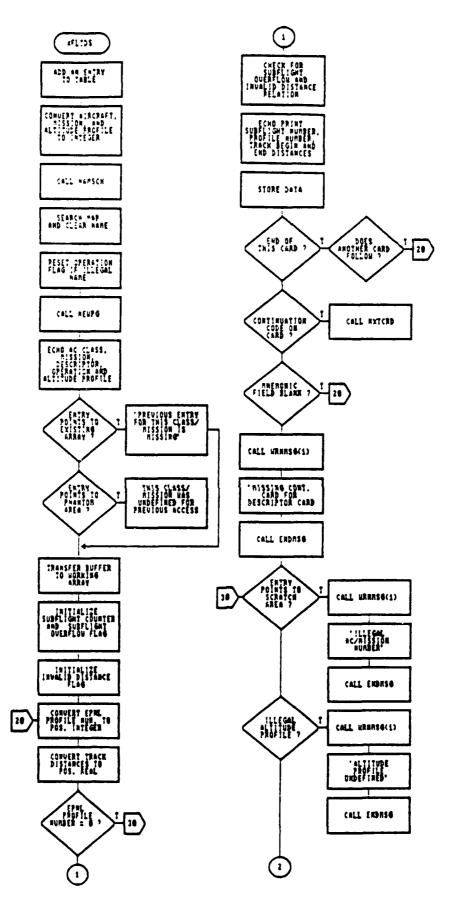


Figure 59. SubProgram XFLTDS Flow Diagram

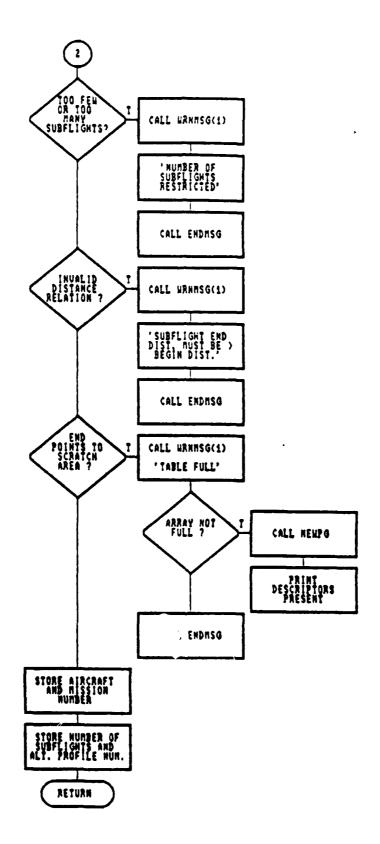


Figure 59-A. SubProgram XFLTDS Flow Diagram (Continued)

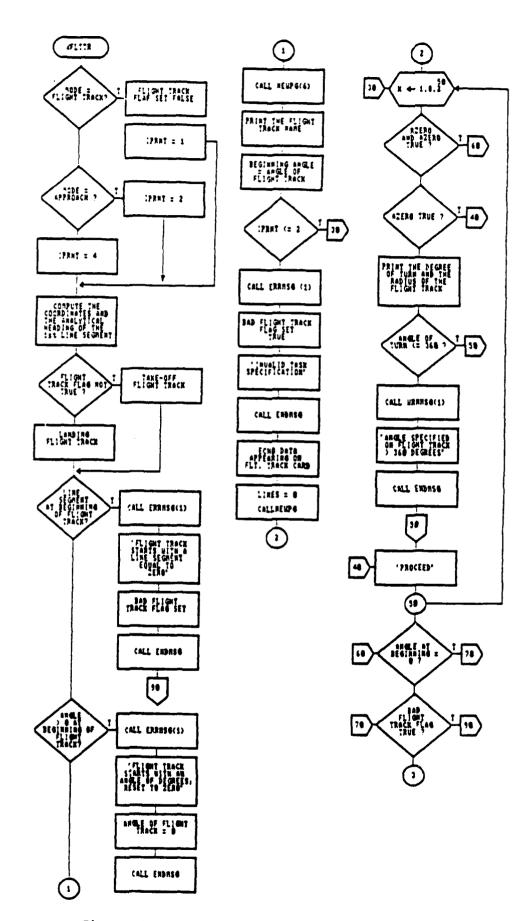


Figure 60. SubProgram XFLTTR Flow Diagram

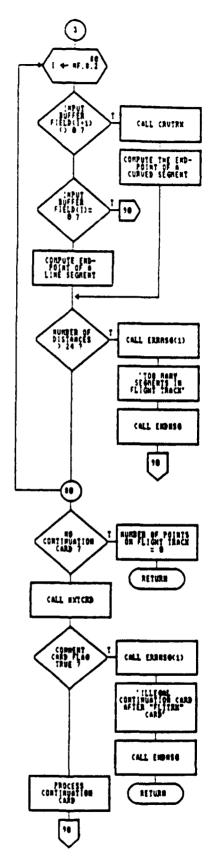


Figure 60-A. SubProgram XFLTTR Flow Diagram

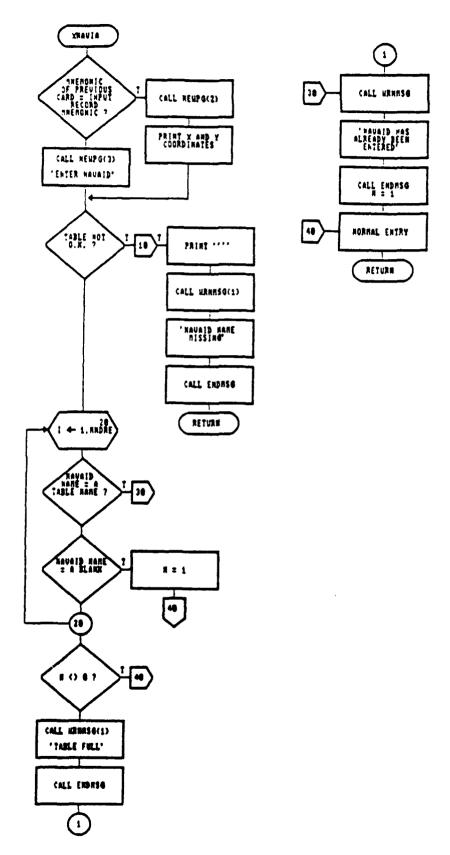


Figure 61. SubProgram XNAVAI Flow Diagram

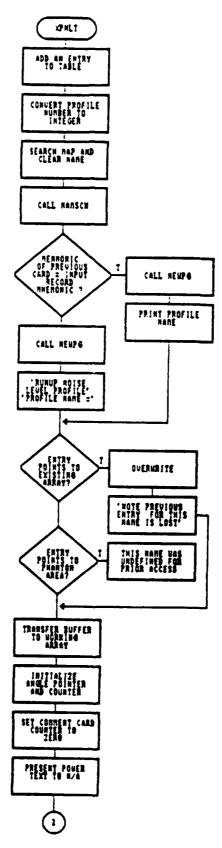


Figure 62. SubProgram XPNLT Flow Diagram

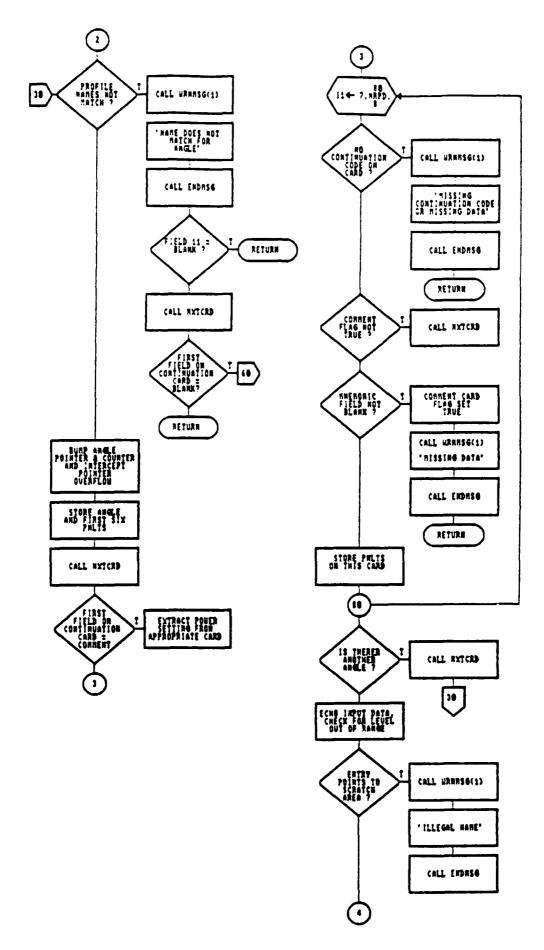


Figure 62-A. SubProgram XPNLT Flow Diagram

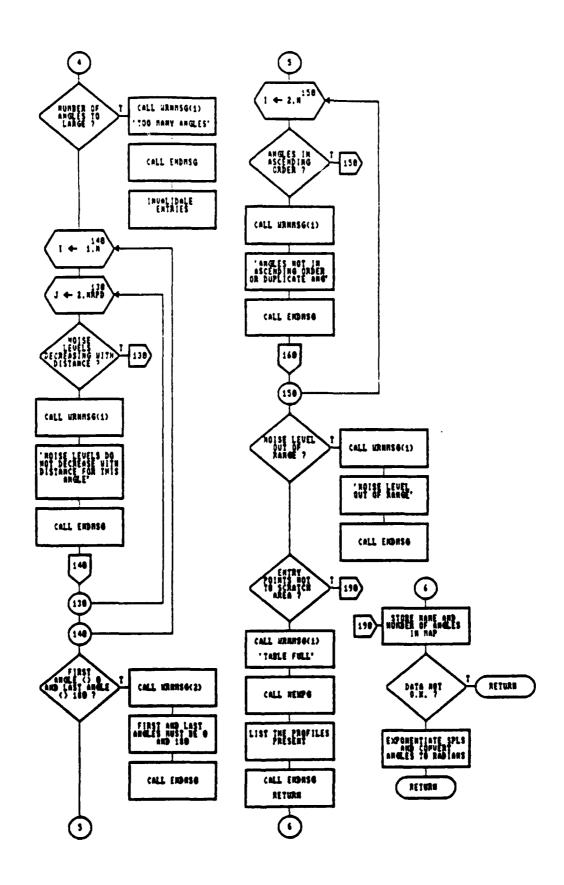


Figure 62-B. SubProgram XPNLT Flow Diagram

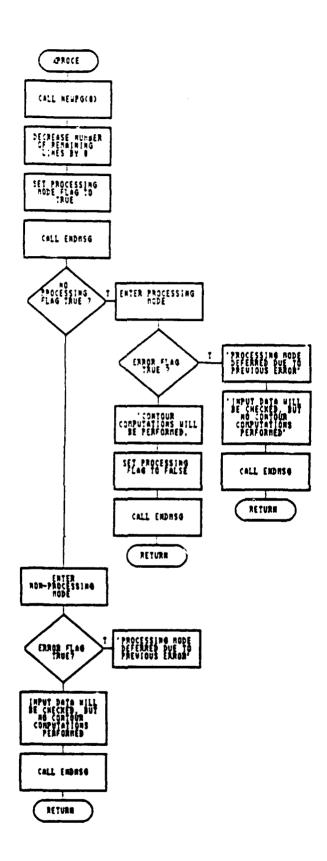


Figure 63. SubProgram XPROCE Flow Diagram

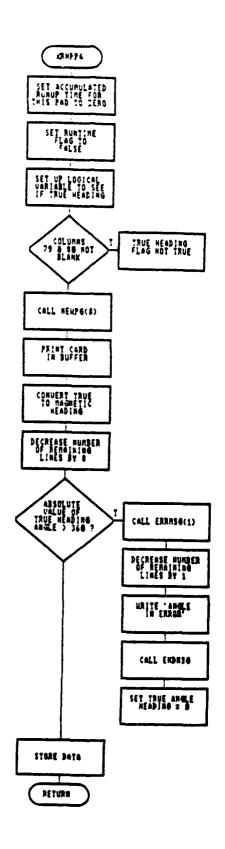


Figure 64. SubProgram XRNPPA Flow Diagram

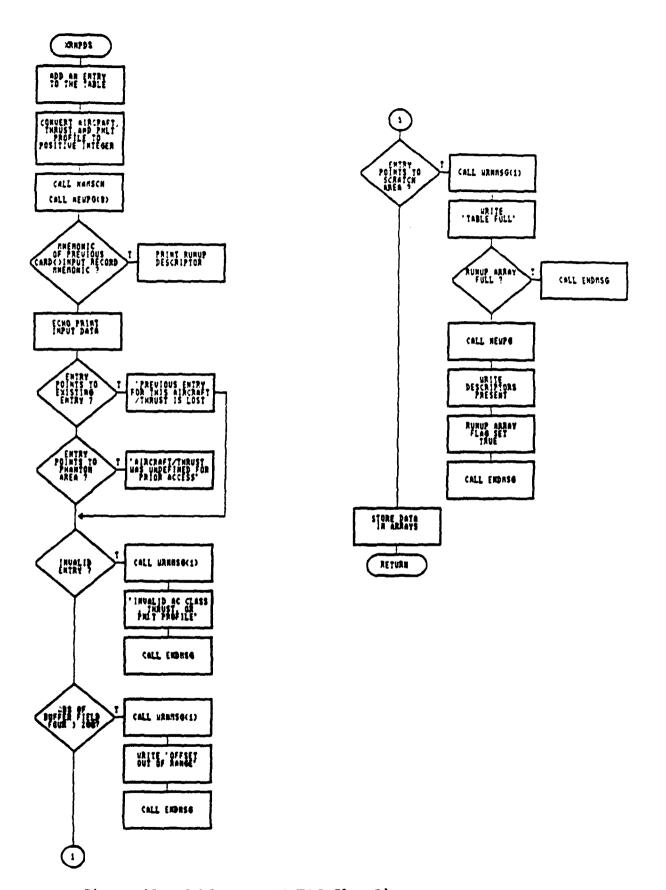


Figure 65. SubProgram XRNPDS Flow Diagram

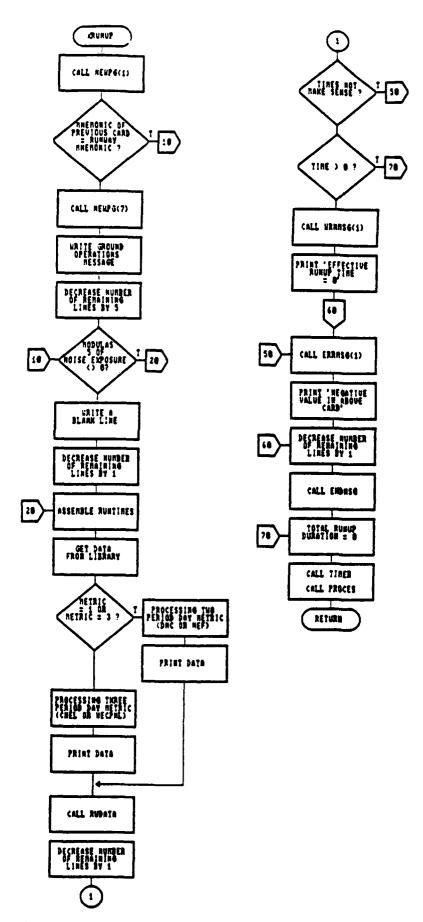


Figure 66. SubProgram XRUNUP Flow Diagram

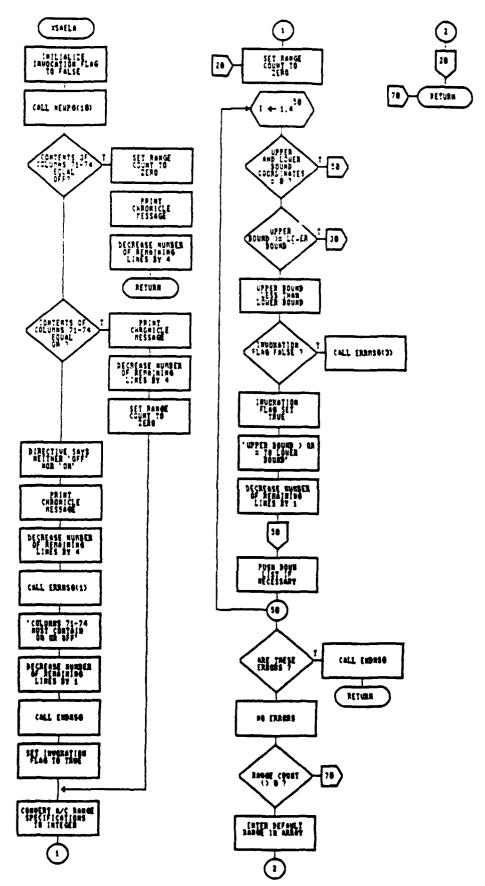


Figure 67. SubProgram XSAELA Flow Diagram

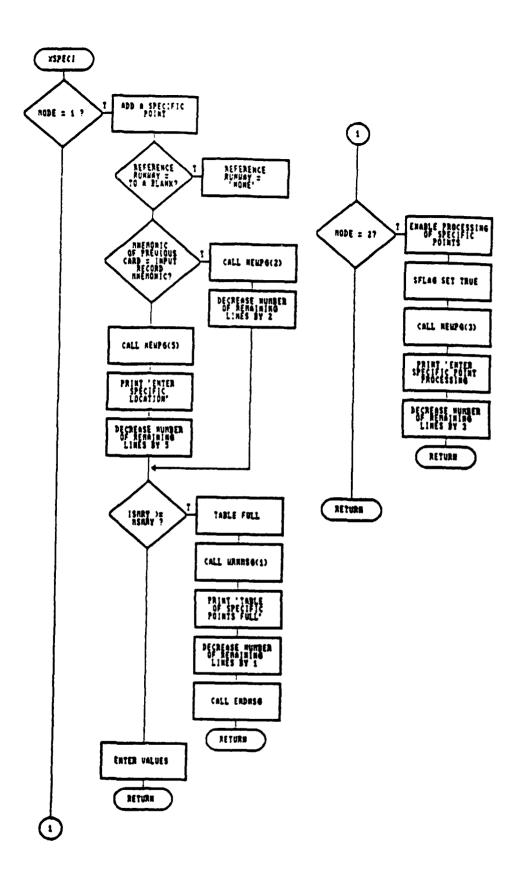
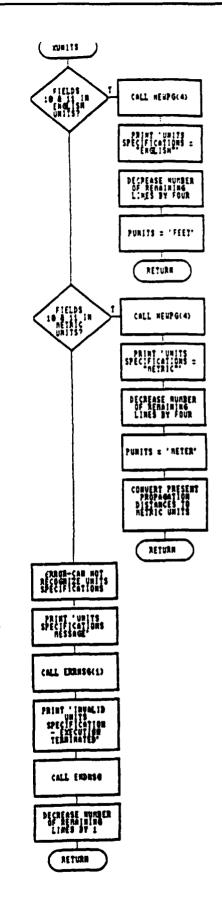


Figure 68. SubProgram XSPECI Flow Diagram



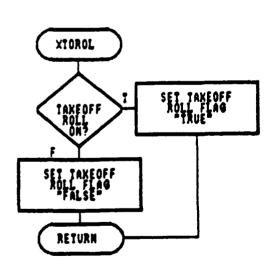


Figure 69. SubProgram XTOROL Flow Diagram

Figure 70. SubProgram XUNITS Flow Diagram

# APPENDIX B Summary of NMAP 6.0 Subroutines

# **B.1 COMMON VARIABLES**

The NOISEMAP program makes extensive use of common storage in the form of labeled common blocks. Use of common storage reduces program memory requirements and allows large amounts of data to be passed between calling subprograms without needing to be passed in lengthy parameter lists.

The various labeled common blocks occur only in the subprograms in which the variables are used. All common block variables are initialized in the BLOCK DATA subroutine. All variables in labeled common blocks are listed in Table 3. The following sections describe the labeled common blocks.

#### CHRVAR Common

All character variables used in common are contained in CHRVAR.

#### **COMPUT Common**

Variables needed to compute noise exposure such as flight path parameters and volume of operations are contained in COMPUT.

#### **CXAREA Common**

The variables in CXAREA are primarily used in the calculation of the approximate areas within selected contour lines.

#### ERROR Common

The variables in ERROR are used to keep track of the page number on which errors and warnings occurred and number of errors and warnings issued by the program.

## **EXPOS Common**

The variables in EXPOS are used to compute the noise exposure for grid points.

## **FACTO Common**

The variables in FACTO are correction factors used in computing noise exposure.

## FLIGHT Common

The variables in FLIGHT are primarily used to store flight track and altitude profile data.

## **GRD** Common

Labeled common GRD stores the array of grid points.

## **INPUT** Common

The variables in INPUT are used to input data from the run file and contain the x and y coordinates of the grid origin.

#### **LATATN** Common

The variables in LATATN are used in lateral attenuation calculations.

## **MNEMIC Common**

The variables in MNEMIC indicate the type of data that is contained on the input records of the run file. These key words or mnemonics are defined in Section 4 and are also contained in the variable definition list in Appendix B.

#### **NAVAID Common**

All variables in NAVAID contain navigational aid information.

#### **OFFSET Common**

The variable in OFFSET contains the offset dB factors used in the calculation of noise exposure due to ground runups.

## **PFRMNC Common**

The variables in PFRMNC contain the names of flight and runup descriptors, noise data sets, altitude profiles and size of the various arrays.

## RUNUP Common

These variables are related to data concerning runup pads and the minimum threshold value for computing noise exposure due to ground runups.

#### RUNWAY Common

The variables in this labeled common contain the input data for runways.

## STATUS Common

These variables indicate the status of various facets of the program such as the current version number of the NOISEMAP program, the noise measure being calculated and program flags.

# **SUMMRY Common**

The variables in SUMMRY contain input and calculated noise data for specific points.

#### B.2 MAIN

The purpose of the MAIN program is to open the input and output files, and to control program flow. When NOISEMAP is executed, the first action taken in MAIN is to open the input file (Unit 5) and the output file (Unit 6). The input file is the "run" file and the output file on Unit 6 contains an echo of the input data, error and warning messages, and specific point output if requested. This printed output file is referred to as the Chronicle. The input file consists of data in card image format. Each card image contains 80 characters divided into twelve fields. The first field in each card is a mnemonic. The mnemonic is a key word that identifies the type of data contained on the card. The mnemonic is interpreted in MAIN and a subprogram is called to process the input data on the card. The subprogram returns control to MAIN when the subprogram has completed all processing associated with the data card and any continuation cards.

Only sequence dependent mnemonics are checked in MAIN. Sequence independent mnemonics are processed in subprograms SIMCHK and SELECT. If the mnemonic is not recognized in MAIN then subprogram SIMCHK is called to check sequence independent mnemonics. The following sequence dependent mnemonics are processed in MAIN:

MAIRFL - "AIRFLD" (airfield card)

MRUNWA - "RUNWAY" (runway)

MFLTTR - "FLTTRK" (flight track)

MFLIGH - "FLIGHT" (flight operations)

MRNPPA - "RNPPAD" (runup pad)

MLALTU - "LALTUD" (list altitude profiles)

MRUNUP - "RUNUP" (runup operations)

If sequence dependent mnemonics are not encountered in the correct order, e.g., a runway card is processed before an airfield card, then an error message is issued. The program will continue to process the input file but will not do any noise calculations. However, if 25 errors have been detected in MAIN, then the program will terminate with the following message: "ABNORMAL STOP IN MAIN - EXCESSIVE ERRORS."

# **B.3 ATRBUT**

# PARAMETERS: (NEW)

Subroutine ATRBUT is called by FLPATH to merge parameters from the altitude profile and the flight track to create the three dimensional flight path. The parameter NEW indicates whether the point being admitted is from the flight track or altitude profile. The first point admitted to the flight path is always taken from the first point of the flight track. Subsequent points admitted to the flight path are either from the altitude profile or the flight track depending on the value of NEW. Subroutine FLPATH determines whether the next point to be added to the flight path comes from the altitude profile or the flight track and sets the value of NEW. There are two main branches in ATRBUT: one branch processes points from the altitude profile and the other branch processes points from the flight track. Each branch further subdivides the process based on whether or not the point being evaluated is on a straight line segment or on a curved segment. If the point lies on a curved segment and the angle of curvature is greater than 60 degrees, then the angle is subdivided into equiangular segments with smaller angles of curvature.

# B.4 CHERCH

Subroutine CHERCH is called by PROCES to update the NOISEMAP grid at points where the flight exposure exceeds a given threshold. The search for grid points of significant flight exposure, i.e., the flight exposure exceeds a preset threshold, is performed using the flight path as a base pattern. Traversal along the ordinate (y axis) is initiated successively from

two points on each flight path segment: an end-point and a mid-point. The point from which traversal is initiated at any instant is called a reference point. After completion of traversal along the ordinate from a reference point, a new reference point is chosen whose abscissa (x axis) is one grid unit to the left or right of the current reference point and whose ordinate is the mid-point of the extent of traversal along the ordinate from the current reference point. This search algorithm results in dynamic tracking of the flight path and thus ensures that no points of significant exposure are missed.

When a significant point is found, the flight exposure at that grid point is assigned a negative value. This prevents redundant computations of flight exposure at the same point for a given flight path. The farthest point of traversal in each direction is kept track of by four pointers. When grid traversal is complete, the points of significance whose signs need to be restored lie entirely in the rectangle bounded by these four pointers.

## B.5 CLEAR

Subroutine CLEAR is called by SIMCHK to reset the flight descriptor, altitude profile, flight noise profile, runup descriptor and runup noise profile arrays to zero. Subroutine CLEAR is invoked when SIMCHK reads a "CLEAR" card.

## B.6 CPAREA

Subroutine CPAREA is called by XAREA to calculate the approximate area within specified contours. Up to eight contour levels can be evaluated.

#### B.7 CRVTRK

#### PARAMETERS:

(XCSTRT, YCSTRT, OLDHD, YCEND, HEAD, XCENT, YCENT, R, ANGLE)

Subroutine CRVTRK is called by ATRBUT, PROCOR XFLIGH and XFLTTR to compute the end point of a circular flight track. The following data are used for compute the end point: beginning point, the analytical heading of the beginning point, and the radius and the angle subtended. The following method is used to calculate the end point and the corresponding heading. At the origin measure a length equal to a radius along the x axis; this section is positive for a left-hand turn. Rotate this section around the origin, clock-wise for a right-hand turn, counter-clock-wise for a left-hand turn. Translate to a coordinate system where the origin is located at the beginning point of the turn. Rotate around this origin so that

the analytical heading at the beginning of the turn is correct. Translate the curved section thus obtained to the point where the turn takes place on the map. The newly found end point and the corresponding heading at that point are returned to the calling subprogram.

## **B.8 CURVE**

PARAMETERS: (X,XARRAY,I,J,K,YARRAY,M,N,L,NPTS)

The function CURVE is called by ATRBUT and XFLIGH to perform an interpolation between two values passed as arguments (XARRAY and YARRAY) and returns the interpolated value.

## **B.9 ENDMSG**

Subroutine ENDMSG is called by many subroutines to print a line of asterisks to terminate a message on the output file.

## B.10 EPNLD

Parameters: (INDEX,SLANT,ALTUD)

The function EPNLD is called by FLTEXP, SFLTEX, SPRUNU and SRUNUP to compute the difference between the real EPNL for a flight segment and the air-to-ground value of the EPNL curve. One of two algorithms is used depending on the status of the lateral attenuation flag "FLTSAE." If the flag is `FALSE` then the original NOISEMAP lateral attenuation algorithm is used. If the flag is `TRUE`, then the SAE AIR 1751 algorithm is employed. The flag is set in subroutine XFLIGH.

The SAE AIR 1751 algorithm uses the elevation angle and the lateral distance from the flight track to determine the attenuation relative to air-to-ground conditions. The original NOISEMAP algorithm uses air-to-ground, ground-to-ground or a mixture of the two depending on the sine of the angle of observation.

The sine of the angle of observation is defined as the arcsine of the ratio of aircraft altitude to slant distance. Air-to-air propagation is used for angles with the sine greater than 0.125 and ground-to-ground propagation for sine less than 0.075. Interpolation between air-to-air and ground-to-ground propagation is performed for intermediate values of the sine. The difference in EPNL corresponds to a ratio of energies.

#### **B.11 ERRMSG**

PARAMETERS: (I)

Subroutine ERRMSG is called by many subroutines to print an error in the output file and stores the page number on which the error occurs. An error banner is printed for each error and the page number is compared to the last page on which an error occurred. If another error has been printed on this page then no action is taken. However, if this is the first error on this page, then the new page number is stored. At the end of the run, subroutine PRTERR will print a summary indicating the page numbers that errors occurred.

## **B.12 FLPATH**

Subroutine FLPATH is called by XFLIGH to merge the flight track with the applicable altitude profile resulting in the division of the flight track into smaller segments that correspond to the S-distances (segment-distances) of these profiles. At any given time, the point with the smallest S-distance along the flight tack or the altitude profile is entered into the flight path.

The S-distance pointer of the most recently admitted point is advanced. Whenever a point is admitted into the flight path, the attributes of that point such as the altitude are transferred into the attribute vectors of the flight path by calling subroutine ATRBUT. The merging process is terminated as soon as the entire S-distance of the flight track is covered.

In the above description, "flight track" refers to the projection on the ground plane of the flight track information furnished in the input file. The "flight path" is the 3-dimensional version of the flight track which also incorporates the points corresponding to the S-distances of the altitude profile.

## **B.13 FLTEXP**

PARAMETERS: (M,N)

The function FLTEXP is called by CHERCH to compute the noise exposure at a specific grid location due to a flyover. The coordinates of the grid point (M,N) are found in the system in which the aircraft nose is aligned pointing to the positive x-axis.

#### **B.14 GREPNL**

# PARAMETERS: (I,J)

The function GREPNL is called by GRUNUP to compute the noise exposure at a specific grid point due to a ground runup. The coordinates of the grid point (I,J) are found in the coordinate system in which the aircraft is aligned pointing towards the positive x-axis with the runup pad at the origin. From this location the angle between the aircraft and line of sight is computed. Interpolation between the available angles in the noise data will give the desired exposure which is then corrected for the duration and frequency of the runups at that pad.

# **B.15** GRUNUP

Subroutine GRUNUP is called by PROCES, SRUNUP and XRUNUP to update the grid with EPNL values of significance due to ground run-ups. The search for stid points of significant EPNL, i.e., above a given threshold, is based on the a priori knowledge that the resulting pattern approximates the shape of a cartioid. Thus the search is bounded by the square that circumscribes the outermost cartioid pattern. The search proceeds along the abscissa form one vertical side of the square to the other. In the vicinity of the cusp of the cartioid, it is possible that the points of significance on either side of the cusp might be ignored. To avoid this o 6 2problem, the logical flag "TRAP" indicates whether any significant point exists at a given ordinate level. Based on this flag, the search is continued or terminated in that direction.

## **B.16 INTLIZE**

Subroutine INTLIZE is called by MAIN to initialize various items which are required before processing can commence. The DB offsets for the John Mills ground runup calculations are initialized and the lateral attenuation flag is turned off. The current date is obtained from the computer for use in the printed output file.

#### **B.17 LINESD**

# PARAMETERS: (AX,AY,AZ,BX,BZ,OX,OY,SLDIS,ELEV)

Subroutine LINESD is called by SFLTEX to compute the closest point of approach between a line segment in the flight path and an observer. Two frames of reference are used: frame 1 is the main, grid oriented frame, and frame 2 is the frame with the observer at the origin and the flight path parallel to the y-axis and the x-axis is along the slant distance vector.

Calculations are performed in frame 2. Actual computations are a mixture of trigonometry in this coordinate system, and calculations in the ground plane.

## B.18 LINEX

PARAMETERS:

(AX,AY,AZ,BX,BY,BZ,AB,ABSQR,IA,IB,CHEAD,SHEAD,OX,OY,EXPOSE,SLDIS,CZ)

Subroutine LINEX is called by FLTEXP and SFLTEX to compute the noise exposure integral for a straight flight path section at a given point. Three frames of reference are used in the calculations: frame 1 is the main, grid oriented, frame; frame 2 is the frame with the observer at the origin, the flight path parallel to the y-axis and the x-axis is along the slant distance vector; and frame 3 is the auxiliary frame with the y-axis parallel to the flight path and the origin at the projection of the slant distance vector intersection point. Calculations are performed - at least logically - in frame 2 actual computations are a mixture of trigonometry in this coordinate system, calculations in the ground plane and vector relationships in the coordinate system in which the origin is at the observer location, but which otherwise is parallel to the grid-based coordinate system.

#### B.19 NAMSCH

PARAMETERS: (MAP,MNIM1,MDIM2,NAME,NDIM1,XENTRY,CODE)

Subroutine NAMSCH is called by XALTUD, XEPNDB, XFLIGH, XFLTDS, XPNLT and XRUNPDS to search the appropriate array for an input name vector. The routine will return one of the following codes to the calling routine:

Code 0 if the name vector is equal to zero, then the entry points to the scratch area (the last element in the array). Code 1 if there is an empty slot in the array. Code 2 if the name already exists in the array. Code 3 if a phantom entry exists (the negative of the namevector). Code 4 if he array is full.

#### B.20 NEWPG

PARAMETERS: (LINE)

Subroutine NEWPG is called by numerous subroutines to move the line printer to the top of a new page and to print the airfield identifier with page number on top line if number of lines remaining on current page is less than calling argument LINE. If the number of lines

remaining on the page is greater than LINE, no action is taken. Otherwise, the line count is reset for a full page, the page counter is bumped, and a new page is started. If LINE is zero, then the page counter is set to zero and new page is started.

## **B.21 PRELUD**

Subroutine PRELUD is called by XFLIGH to calculate the necessary parameters for the computation of flight exposure. It computes the radius of curvature, sine and cosine of the aircraft heading on the flight path, tangent of the climb angle and the secant of the climb angle.

## **B.22 PROCES**

Subroutine PROCES is called by XRUNUP and XFLIGH to control the computations of noise exposure at grid points when a FLIGHT or RUNUP card is encountered by calling the appropriate subprograms.

#### **B.23 PROCOR**

Subroutine PROCOR is called by XFLIGH to compute the coordinate information for altitude profiles which are specified at given distances along the flight track. The altitude profile is superimposed on the flight track. For the terminal point of each segment of the profile, it locates the preceding point on the flight track. Using the coordinate information and the analytical head of the point on the flight track, it then computes the coordinates of the endpoint of the segment on the profile.

#### B.24 PRTERR

Subroutine PRTERR is called by INTLZE and XEND. When called by INTLZE the error and warning counters are set to zero. XEND calls PRTERR to print error statistics at the end of the run. A new page is started and if any errors or warnings were detected the page number(s) where these errors occurred are listed for easy reference. Up to 200 pages of warnings and up to 56 pages may have errors on them before the program stops keeping track of the page number that the error or warning occurred on. Beyond that point only the number of errors will be the counted.

**B.25 PRTGRD** 

Subroutine PRTGRD is called by SIMCHK to print the NOISEMAP grid values. Only

grid values greater than or equal to the threshold are printed; all values less than the threshold

are blank.

**B.26 PSUMRY** 

Subroutine PSUMRY is called by XEND to print the summary listings for specific

points if specific point processing is requested. Two listings are printed for each specific point:

the first listing contains the top 18 aircraft contributors and the second listing, the top 18 runup

contributors.

B.27 RDCARD

Subroutine RDCARD is called by MAIN, SELECT and SIMCHK to read individual

records in the input file and to place them into the input buffer. If the record has a continuation

card then the alternate entry point "NXTCRD" is called from the routine processing the first

record. If the record is a comment, then it is printed unless the printing of comments is

suppressed.

**B.28 RJCHAR** 

PARAMETERS: (LJCHAR, OUTCHR)

Subroutine RJCHAR is called by UPFLSP to right justify the character variable

LJCHAR for the specific point output summary.

B.29 RUDATA

PARAMETERS: (IAIRCR, ITHRST)

Subroutine RUDATA is called by XRUNUP to locate the maximum noise level curves

for the ground runup of aircraft IAIRCR and thrust ITHRST. Array "RDMAP" is searched for

valid combinations and array "MNLMAP" is searched to see if the required noise profile is

available. If the requested data is not available an error is generated and the program will

attempt to make a dummy entry to reserve space for the missing item.

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#### **B.30 SELECT**

Subroutine SELECT is called by SIMCHK to select the noise measure that will be computed by NOISEMAP. The following types of noise measures can be computed by NOISEMAP:

- 1. Day-Night Average Level (DNL)
- 2. Community Noise Equivalent Level (CNEL)
- 3. Noise Exposure Forecast (NEF)
- 4. Weighted Equivalent Continuous Perceived Noise Level (WECPNL)

The default noise measure is the Day-Night Average Level. If the noise measure is changed from the default, then the appropriate noise profile mnemonics and weighting functions are reset to the appropriate values.

#### **B.31 SFLTEX**

Subroutine SFLTEX is called by PROCES to compute the noise exposure due to aircraft flyover at specific points within the area bounded by the NOISEMAP grid. The coordinates of the specific points are found in the coordinate system in which the aircraft is aligned pointing towards the positive x-axis. From this the angle between aircraft and the line of sight is computed. Interpolation between the available angles in the noise data set will give the desired exposure.

## **B.32 SGREPN**

## PARAMETERS: (IS)

Subroutine SGREPN is called by SGRUNP to compute the noise exposure due to a ground runup at specific point IS. The coordinates of the specific points are found in the coordinate system in which the aircraft is aligned pointing towards the positive x-axis with the runup pad at the origin. From this the angle between aircraft and line of sight is computed. Interpolation between the available angles in the noise data set will give the desired exposure which is then corrected for the duration and frequency of the runups at that pad.

## **B.33 SGRUNP**

Subroutine SGRUNP is called by PROCESS to compute ground runup contributions at each specific point.

## **B.34 SIMCHK**

Subroutine SIMCHK is called by MAIN to check the input record for a sequence-independent mnemonic, and to process that card. This routine assumes all sequence-dependent mnemonics have previously been checked. If the mnemonic is not matched, then routine SELECT is called in a last attempt to identify the mnemonic. If a match for the mnemonic is not found in SELECT then an error is issued by SELECT.

#### B.35 SPRUNU

Subroutine SPRUNU is called by SFLTEX to calculate the noise contribution due to takeoff roll for specific point noise level calculations. Two different lateral attenuation methods are used to calculate the takeoff roll contributions depending on the status of the flag FLTSAE. If FLTSAE is "TRUE" then SAE AIR 1751 algorithm is used; if it is "FALSE" then the original NOISEMAP algorithm is used.

# B.36 SRUNUP6

Subroutine SRUNUP is called PROCES to calculate the noise level due to takeoff roll for all takeoffs for use in updating the grid. Two different lateral attenuation methods are used to calculate the takeoff roll contributions depending on the status of the flag FLTSAE. If FLTSAE is "TRUE" then SAE AIR 1751 algorithm is used; if it is "FALSE" then the original NOISEMAP algorithm is used.

#### B.37 SUPPAG

PARAMETERS: (CUTOFF, NBASE, IWIDTH, 11, 12)

Subroutine SUPPAG is called by CPAREA and PRTGRD to determine the first page from the top (I1) to the bottom (I2) which contains a value greater than or equal to a CUTOFF in a vertical set of pages from a printer plot.

## **B.38 TIMER**

Subroutine TIMER is called by XRUNUP to check the accumulated ground runup time against the total number of seconds in the day and night periods.

# **B.39 TIPAGE**

Subroutine TIPAGE is called by XAIRFL, XEND and PRTERR to write the title page on the Chronicle listing. The call from XAIRFL writes the title page at the beginning of the Chronicle listing and the call from either XEND or PRTERR writes the title page at the end of the Chronicle listing.

# **B.40 TURNEX**

PARAMETERS: (R,RSQ,PHI,RTGB, RTGBSQ,SECBET,ADJQ,ADJT,OBSX,OBSY CHEAD,SHEAD,CENTX,CENTY,OZ,EXPOSE,SLDIS,ELEV)

Subroutine TURNEX is called by FLTEXP and SFLTEX to compute the noise exposure integral and slant distance for a curved flight track segment. The observer point is transformed to a position in frame of reference where the center of curvature of the flight track is at the origin and the radius vector connecting the center and the first point on the track is along the positive x-axis. The integral is then evaluated and a slant distance is computed. 3.41 UPFLSP (IS,FLEXPO)

Subroutine UPFLSP is called by SFLTEX to update the arrays (CFSMRY and FSMRY) containing the most significant flight events for each location IS with the noise exposure level FLEXPO.

## **B.42 UPRUSP**

PARAMETERS: (IS,RNPEPN)

Subroutine UPRUSP is called by SGRUNP to update the arrays (CRSMRY and RSMRY) containing the most significant runup events for each location IS with noise exposure level RNPEPN.

#### B.43 WRNMSG

## PARAMETERS: (I)

Subroutine WRNMSG is called by numerous subroutines to print a warning identifier and to store the page number on which a warning occurred. A warning banner is printed and the page number is compared to the last page on which a warning occurred. If the page number is the same no action is taken. However, if the page number is different and space is

available in PAGE, then it is sorted; otherwise the number of warnings since PAGE was filled up is kept. Subroutine PRTERR will print this information at the end of the run.

#### B.44 XAIRFL

Subroutine XAIRFL is called by MAIN to initialize the airfield. The routine reads the airfield coordinates, magnetic declination, airfield elevation, grid spacing and the direction of declination from the first Airfield card. The airfield title is then read from the second Airfield card and the title page is written in the Chronicle. The input data is then checked for errors. An altitude correction factor, ALTCOR, is computed using the airfield elevation.

## B.45 XALTUD

Subroutine XALTUD is called by SIMCHK to enter an altitude profile name into array ALTMAP and the altitude profile distance and altitude values into arrays ALTXC and ALTZC respectively. The profile data is checked for errors.

#### B.46 XAREA

Subroutine XAREA is called by SIMCHK to calculate approximate areas within the specified contours.

## B.47 XECHO

Subroutine XECHO is called by SIMCHK to select the expansion mode for printing the noise profile data sets in the Chronicle. Unless an ECHO card is used, printing of the SEL and AL noise profile data sets are suppressed by default. The "NOECHO" flag is set FALSE if an ECHO card is processed.

#### B.48 XEND

Subroutine XEND is called by SIMCHK to initiate program termination procedures when an END card is processed. This routine creates a disk file for the NOISEMAP grid for use in the PLOTT88 program or to create a grid printout on the printer. Subroutine PRTERR is called to print the error summary, subroutine PSUMRY is called to prepare the specific point summary and subroutine TIPAGE is called to print a title page on the last page in the Chronicle.

#### B.49 XEPNDB

Subroutine XEPNDB is called by SIMCHK to enter the aircraft flyover noise profile data generated by the OMEGA10 program. The profile name is entered in array INLMAP. The air-to-air data is entered in array INLAG and the ground-to-ground data in array INLGG. The data can be entered in either order although the air-to-air data is normally entered first. If the noise profile name identifier (IDENT) already exists in array INLMAP, then the existing entry will be overwritten. Noise levels are limited to + or - 200 db.

## **B.50 XFLIGH**

Subroutine XFLIGH is called by MAIN to process a FLIGHT card and check for the presence of the associated noise information, culminating in the augmentation of the grid with the flight exposure resulting from that flight. For the aircraft and mission numbers specified on the FLIGHT card, identifiers of the noise profiles are obtained from the flight descriptor array, FDMAP. The presence of these profiles is then checked. If subflight boundaries do not coincide with end-points of flight track segments, the latter are subdivided to meet this criterion. After the creation of the merged flight path, a dope vector (INLPNO) is set up containing the noise profile numbers to be used for the segments within a subflight. Finally subroutine PROCES is called to update the grid.

## B.51 XFLTDS

#### PARAMETERS: (INFLG)

Subroutine XFLTDS is called by SIMCHK to enter flight descriptor data. The flight descriptor identification name is stored in array FDTEXT. The value of INFLG determines whether the entry is a takeoff or landing descriptor: a one (1) signifies a takeoff descriptor and a two (2), a landing descriptor. FDMAP contains the aircraft number, mission number, number of subflights and the altitude profile number. The noise profile name for the subflights are entered in array FLPLST and the beginning and end subflight distances are entered in array FLDLST. If the flight descriptor name identifier (IDENT) already exists in array FDMAP, then the existing entry will be overwritten. If warning(s) or error(s) are printed, then data is not entered.

#### B.52 XFLTTR

Subroutine XFLTTR is called by MAIN to compute the coordinates of the end-points of the segments on the flight track furnished by the user. Coordinates of the end-point of a straight line segment are computed by using the coordinates of the starting point and the segment length coordinate computation of the end-points of curved segments is accomplished in subroutine CRVTRK. All data appearing on the FLTTRK card is echoed in the Chronicle listing and checked for errors.

#### **B.53 XNAVAI**

Subroutine XNAVAI is called by SIMCHK to enter navigational aids. The navaid identifier is entered in array VORNME and the x and y coordinates are entered in array VORMAP. The navaid name is checked against currently known names in array VORNME.

## **B.54 XPNLT**

Subroutine XPNLT is called by SIMCHK to enter the ground runup noise profile data generated by OMEGA 11. The noise profile name is entered in array MNLMAP. The angle data is stored in array MNLANG and the noise data is stored in array MNLVL. If the PNLT profile name (IDENT) to be entered matches an ident already in array NMLMAP, then existing entry will be overwritten. If warning(s) or errors are printed, then data is not entered. An entry N is deleted by setting MNLMAP (1,N) equal to zero. Noise levels are limited to + or - 200 db

## **B.55 XPROCE**

# PARAMETERS: (LFLG)

Subroutine XPROCE is called by SIMCHK to set the program processing status flag NOGO either "TRUE" or "FALSE" depending on the value of the argument LFLG. LFLG is "TRUE" for a "PROCES" card and "FALSE" for a "NOPROC" card. The program cannot enter the process mode if the error flag, ERRFLG, has previously been set to "TRUE." The flag NOGO is initialized "FALSE" in the BLOCK DATA subroutine.

#### **B.56 XRNPDS**

Subroutine XRNPDS is called by SIMCHK to enter runup descriptors. The descriptor name is stored in array RUTXT. The aircraft identification number and thrust number are

entered in RDMAP and the PNLT profile name is entered in array RUPLST. If the aircraft identification number and thrust number to be entered matches an existing entry in RDMAP, then existing entry will be overwritten. If warning(s) or error(s) are printed, then data is not entered.

## B.57 XRNPPA

Subroutine XRNPPA is called by MAIN to initialize a ground runup pad. The subroutine transforms the external runup pad coordinates to internal coordinates, XPAD and YPAD, the time accumulators (TIMOFL) for the runup pad are set to zero and the runup pad heading is converted to a magnetic heading if the input heading is a true heading.

## **B.58 XRUNUP**

Subroutine XRUNUP is called by the MAIN program to compute noise exposure for all runups at a given pad, of a given class of aircraft and at a given thrust. Subroutine RUDATA is called to make sure that the aircraft identification number and thrust numbers are available for the calculations. The runup times are read from the "RUNUP" card and summed for all time groups (day, evening and night) and then checked in routine TIMER to ensure they do not exceed the total number of seconds in a day. Subroutine PROCES is then called to initiate the noise exposure computation. Specific points and the grid are then updated with the noise exposure due to this ground runup.

## B.59 XRUNWA

Subroutine XRUNWA is called by the MAIN program to screen and process the data appearing on the "RUNWAY" card. The runway coordinates are transformed into the internal coordinates XBEG, YBEG, XEND and YEND. The runway length (RWYLEN) is computed and checked to make sure it dose not exceed 16,000 feet. The inclination angle of the runway is also calculated. The runway glide slope (GSLOPE) and the location of the landing and takeoff thresholds are read from the input file and processed by XRUNWA. The coordinates of the landing threshold (XLAND and YLAND) and the takeoff threshold (XTO and YTO) are calculated. Data appearing on the "RUNWAY" card is echoed in the Chronicle.

#### B.60 XSAELA

Subroutine XSAELA is called by SIMCHK to service the "SAELAT" card. The SAELAT card determines which algorithm will be used to compute lateral attenuation: the

original NOISEMAP algorithm or the SAE 1751 algorithm. If the SAELAT algorithm is turned on, the logical flag FLTSAE is set "TRUE" and the SAE lateral attenuation algorithm is used on a selective basis for only those flights whose aircraft identification numbers lie within a specified range. If ranges are not specified on the SAELAT card then the default range is aircraft 800 through 999 which are the current numbers for the civil fleet.

## B.61 XSPECI

PARAMETERS: (MODE)

Subroutine XSPECI is called by SIMCHK to enter or list specific point and to turn specific point processing on or off depending on the value of the argument MODE. If MODE equals one (1) then the subroutine processes the name and the x and y coordinates of the specific location at which the LDN levels are to be calculated. The external coordinates are converted to internal coordinates SPX and SPY. If MODE equals two (2) then all the specific points are listed. If MODE equals three (3) then the specific point processing flag, SFLAG, is set "TRUE" and noise exposure is calculated for all specific points even if the program NOGO flag is "TRUE." If MODE equals four (4) then SFLAG is set "FALSE" and no noise exposure calculations are performed for specific points.

## B.62 XTOROL

Subroutine XTOROL is called by SIMCHK whenever a "TOROLL" card is encountered to enable or disable the takeoff roll algorithm. The takeoff roll algorithm is enabled by default. The takeoff roll logical flag "TORFLG" is set true in subroutine BLOCK DATA. The takeoff roll algorithm is disabled when the first landing is processed. The MCM will issue a "TOROLL OFF" for a landing descriptor. After the first landing descriptor is processed, the MCM will issue "TOROLL ON" for takeoffs and closed patterns and "TOROLL OFF" for landings.

# **B.63 XUNITS**

Subroutine XUNITS is called by SIMCHK to establish the unit of measure, English or Metric, that will be used by the program for internal calculations and on the output devices. English units (feet) are used in the input file and if "METRIC" is entered on the "UNITS" card, then the scaling factor, DISFAC, is set equal to 3.280840 to convert feet to meters. The propagation distances in array DISTT are converted to meters if the METRIC mode is invoked.

The program default mode is English units. If a "UNITS" card does not contain the words "ENGLISH" or "METRIC" then an error message is issued.

# B.64 BLOCK DATA

The purpose of the BLOCK DATA subroutine is to initialize variables in the labeled common blocks.